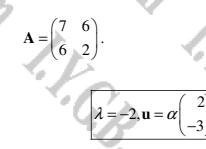
Created by T. Madas MARTRICES MOUESTIONS ALASINALIS COM LYCER MARIASINALIS COM LYCER MARIASIN

Question 1 (**)

Find the eigenvalues and the corresponding eigenvectors of the following 2×2 matrix.



2		
$\begin{array}{c} A_{12} & \begin{pmatrix} 7 & 4 \\ 6 & 2 \end{pmatrix} \\ \hline \\$	\$ #16. 3 = -2.	$\begin{array}{c} \left[x + c_{3} = -2i \right] \\ 6i + 2i_{3} = -2i \\ \cdots \\ y = -\frac{3}{2}x \\ \end{array} $ $\begin{array}{c} q_{1} + c_{3} = 0 \\ \hline p \\ \hline q_{2} + c_{3} \\ \hline q_{3} \\ \hline \end{array} $
$\begin{array}{c} \Rightarrow & \uparrow \uparrow \uparrow \uparrow \uparrow \uparrow \uparrow \uparrow \downarrow \uparrow \downarrow \uparrow \downarrow \downarrow \downarrow \downarrow \downarrow \downarrow \downarrow$	(* 16 A=11	$\begin{array}{c} \widehat{a} + \mathcal{C}_{3,z} & \ a\ _{2} \\ \widehat{b} + 2g = \ y\ _{2} \\ \widehat{b} + 2g = \frac{1}{2}g \\ \therefore \ g = \frac{2}{3}g \\ \widehat{c} \\$

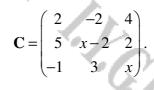
 $\lambda = 11, \mathbf{u} = \beta$

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Question 2 (**)

A transformation in three dimensional space is defined by the following 3×3 matrix, where x is a scalar constant.



Show that **C** is non singular for all values of x.

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20.
EVAWATING THE DETRAINANT OF THE MATRIX AFTLE SIMPLEICATION WITH
ELEMENTARY VARIABLE VARIABLE
$ \underline{\zeta} = \begin{vmatrix} 2 & -2 & 4 \\ 5 & 2 -2 & 2 \\ -1 & 3 & 2 \\ -1 & 3 & 2 \end{vmatrix} \begin{pmatrix} \zeta_{12}(2) \\ -\zeta_{12}(2) \\ -\zeta_{12}(2) \\ -\zeta_{12}(2) \end{vmatrix} = \begin{vmatrix} 2 & 0 & 0 \\ -1 & 2 & 243 \\ -1 & 2 & 242 \end{vmatrix} $
EXPANDING BY THE FIRST ROW
$\dots = \begin{array}{ c c c c c c c c c c c c c c c c c c c$
$= \Im \left[\Im^2 + S\alpha + 6 + 16 \right]$
$= 2 \left[x^2 + 5x + 22 \right]$
$= \Im \left[\left(\chi + \frac{3}{2} \right)^2 - \frac{\chi}{4} + 22 \right]$
$= 2\left(1+\frac{\epsilon}{2}\right)^2 + \frac{\epsilon_2}{2} > 0 \text{for Au } \infty$
THEFFORE I IS NON SNOULL FOR the 2

Question 3 (**)

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The 2×2 matrix **A** is given below.

$$\mathbf{A} = \begin{pmatrix} 1 & 8 \\ 8 & -11 \end{pmatrix}.$$

- a) Find the eigenvalues of A.
- b) Determine an eigenvector for each of the corresponding eigenvalues of A.
- c) Find a 2×2 matrix **P**, so that

$$\mathbf{P}^{\mathrm{T}}\mathbf{A}\mathbf{P} = \begin{pmatrix} \lambda_{1} & 0\\ 0 & \lambda_{2} \end{pmatrix}$$

where λ_1 and λ_2 are the eigenvalues of **A**, with $\lambda_1 < \lambda_2$.

$$\underline{\lambda_1 = -15, \ \lambda_2 = 5}, \ \mathbf{u} = \begin{pmatrix} 1 \\ -2 \end{pmatrix}, \ \mathbf{v} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}, \ \mathbf{P} = \begin{pmatrix} \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} \\ -\frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{pmatrix}$$

$(\mathbf{O}) A = \begin{pmatrix} \mathbf{I} & \mathbf{S} \\ \mathbf{I} & \mathbf{I} \\ \mathbf{I} & \mathbf{I} \end{pmatrix}$	$(\begin{array}{c} 1\\ 1\\ 1\\ 1\end{array}) \begin{array}{c} \vdots\\ 1\\ \vdots\\ 1\\ 1\end{array} \\ (\begin{array}{c} 1\\ 1\\ 1\\ 1\\ 1\end{array}) \\ (\begin{array}{c} 1\\ 1\\ 1\\ 1\\ 1\end{array}) \\ (\begin{array}{c} 1\\ 1\\ 1\\ 1\end{array}) \\ (\begin{array}{c} 1\\ 1\\ 1\\ 1\end{array}) \\ (\begin{array}{c} 1\end{array}) \\ (\begin{array}{c} 1\\ 1\end{array}) \\ (\begin{array}{c} 1\end{array}) \\ (\begin{array}{c} 1\\ 1\end{array}) \\ (\begin{array}{c} 1\end{array}) $
OHABACTERISTIC EXPLATION	$\begin{array}{c} \lambda = -15 & x + \delta \mu = -15\eta \\ & & & & \\ & & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ $
$\Rightarrow (1-\lambda)(11-\lambda)-64=0$ $\Rightarrow (\lambda-1)(\lambda+11)-64=0$	(C) NORMAURE ERSULTORS , BUH HAVE RAVON IS
$\Rightarrow (3 + 15)(3 - 5) \Rightarrow$	$P = \begin{pmatrix} \frac{1}{\sqrt{5}}, & \frac{2}{\sqrt{5}} \\ -\frac{2}{\sqrt{5}}, & \frac{1}{\sqrt{5}} \\ -\frac{2}{\sqrt{5}}, & \frac{1}{\sqrt{5}} \end{pmatrix}$
$\rightarrow g = \leq \frac{1}{2}$	12 3

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Question 4 (**)

Describe fully the transformation given by the following 3×3 matrix.

rotation in the z axis, anticlockwise, by $\arcsin(0.96)$

(0.23 -0 能 0) 0.46 0.28 D 0 0 () MOX THE 2 400 - 0 (0.23) 0 0 () MOX THE 2 400 - 0 (0.23)

Question 5 (**)

A transformation in three dimensional space is defined by the following 3×3 matrix, where k is a scalar constant.

$$\mathbf{A} = \begin{pmatrix} 1 & -2 & k \\ k & 2 & 0 \\ 2 & 3 & 1 \end{pmatrix}$$

Show that the transformation defined by A can be inverted for all values of k.

Dr.				,	proof
9	2				
मिल मार महाप्राइतिल मिल क्लान्स्याय				0,50	89PMDING-
$\det \underline{A} = \begin{bmatrix} 1^+ \\ k^- \\ 2^+ \end{bmatrix}$	-2 k ⁺ 2 ⁺ o ⁻ 3 l ⁺	= k k 2 2 3	- 0	1-2/2 3	+ 1 1 -2
	=	k (3k-4) 3k ² -4k+ 3k ² -2k+	2k.+2,		
		SINCE 62.	-4ac =		L.
IS THE DETIRUMINAN XECRUBEO BY A (, 114€	тенизскематра)

Question 6 (**)

The 3×3 matrix **A** is given below.

$$\mathbf{A} = \begin{pmatrix} 2 & 1 & -1 \\ 0 & 2 & -2 \\ 3 & 4 & -1 \end{pmatrix}$$

a) Find the inverse of A.

The point P has been mapped by A onto the point Q(6,0,12).

b) Determine the coordinates of P

5 4 -6 $A = \begin{pmatrix} 2 & 1 & -1 \\ 0 & 2 & -2 \\ 3 & 4 & -1 \end{pmatrix}$ MATRIX OF MUNIORS = ALL (ALLUGATT) $f = \frac{1}{12} \begin{pmatrix} 6 & -3 \\ -6 & 1 \\ -6 & 1 \\ -6 & -5 \\ -6$ Ap = 4 AAP = Aa ∴ P(3,1,1)

0

P(3,1,1)

6

 $^{-1} = \frac{1}{-1}$

12

Question 7 (**)

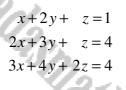
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.V.G.B

The 3×3 matrix **A** is given below.

$$\mathbf{A} = \begin{pmatrix} 1 & 2 & 1 \\ 2 & 3 & 1 \\ 3 & 4 & 2 \end{pmatrix}.$$

- a) Find the inverse of A.
- **b**) Hence, or otherwise, solve the system of equations



$$y + z = 4$$

$$y + 2z = 4$$

$$A^{-1} = \begin{pmatrix} -2 & 0 & 1 \\ 1 & 1 & -1 \\ 1 & -2 & 1 \end{pmatrix}, \quad x = 2, \quad y = 1, \quad z = -3$$

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Question 8 (**)

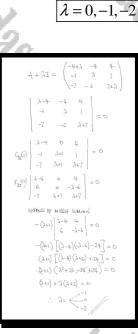
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The 3×3 matrix **A** is given below.

$$\mathbf{A} = \begin{pmatrix} -4 & -4 & 4 \\ -1 & 0 & 1 \\ -7 & -6 & 7 \end{pmatrix}.$$

Given that I is the 3×3 identity matrix, determine the values of the constant λ , so that $\mathbf{A} + \lambda \mathbf{I}$ is singular.



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Question 9 (**)

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The 3×3 matrix **A** is defined in terms of the scalar constant k by

$$\mathbf{A} = \begin{pmatrix} 2 & -1 & 3 \\ k & 2 & 4 \\ k - 2 & 3 & k + 7 \end{pmatrix}$$

Given that $|\mathbf{A}| = 8$, find the possible values of k.

EX BY THE FILLT PAN -1 3* 2 4 3 KH7 k k-2 $\begin{vmatrix} 2 & 4 \\ 3 & k+7 \end{vmatrix} - (-i) \begin{vmatrix} k & 4 \\ k-2 & k+7 \end{vmatrix} + 3 \begin{vmatrix} k & 2 \\ k-2 & 3 \end{vmatrix} = 8$ k(2+7)-4(2-2)+3[3k-2(2-2)]=8 +3[k+4] 22 (k++)(k+46) 2+20K+64-10K-40 = 8 2+10k+16=0 erc erc 45 2600

k = -2, k = -8

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Question 10 (**)

Find the eigenvalues and the corresponding equations of invariant lines of the following 2×2 matrix

$$\mathbf{B} = \begin{pmatrix} 4 & -5 \\ 6 & -9 \end{pmatrix}.$$

$\lambda = 1, y = \frac{3}{5}x$	$, \lambda =$	=-6, y=2x
<i>h</i>		0.
$\delta_{2}\begin{pmatrix} 4 & -5 \\ \delta & -9 \end{pmatrix}$ CHAREDSIC (RUATION)	•)(*))=)	$\begin{array}{l} 4\lambda - 5j = x \\ 6\lambda - 9j = y \end{array} \Rightarrow \begin{array}{l} 5y = 3x \\ y = \frac{3}{2}x \end{array}$
$ \begin{array}{c} (1 + 1) + 1 = 0 \\ (1 + 1) + 1 \\ (1 + 1) + 1 = 0 \\ (1 + 1) + 1 \\ (1 + 1) + 1 $	● 1F A=-6	42-59=-62]= 59=102 62-99=-69]= 59=102 9= 22

Question 11 (**)

A transformation in three dimensional space is defined by the following 3×3 matrix, where y is a scalar constant.

$$\mathbf{M} = \begin{pmatrix} y - 3 & -2 & 0 \\ 1 & y & -2 \\ -1 & y -1 & y -1 \end{pmatrix}$$

If $|\mathbf{M}| = 0$, find the possible values of y.

4-3 (<u>M</u>) = 8-1 9-1 $= (9-3) \begin{vmatrix} y & -2 \\ y-1 & y-1 \end{vmatrix} + 2 \begin{vmatrix} 1 & -2 \\ -1 & y-1 \end{vmatrix} + 0 \begin{vmatrix} 1 & y \\ y-1 \end{vmatrix}$ $= (y-3) \left[y(y-1)+2(y-1) \right] + 2 \left[y-1-2 \right]$ $= (y-3)(y^2-y+2y-2) + 2(y-3)$ $=(y-3) \left[y^2-y+2y-2+2 \right]$ = (y-3) (y²+y) = y(y+1)(y-3) IF M=0 O those

y = -1, y = 0, y = 3

J= C

y(y+1)(y-3) = c

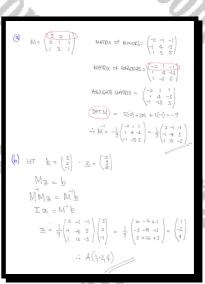
Question 12 (**) The 3×3 matrix M is given below.

$$\mathbf{M} = \begin{pmatrix} 5 & 2 & 1 \\ 0 & 1 & 1 \\ 1 & 3 & 1 \end{pmatrix}.$$

a) Find the inverse of M.

The point A has been transformed by **M** into the point B(5,2,-1).

b) Determine the coordinates of *A*.



5

-5

A(1, -2, 4)

2

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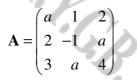
-4 13

 $\mathbf{M}^{-1} = \frac{1}{9}$

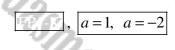
Question 13 (**)

P.C.B.

A non invertible transformation in three dimensional space is defined by the following 3×3 matrix, where *a* is a scalar constant.



Determine the possible values of a.



IF THE TRANSCOMMITTON IS NOT INDERTISE, THE MATTERS $\underline{A} \cong \underline{NOT}$ INDERTISE, so det $\underline{A} = 0$ — GUAND by THE FIRST ROW

- $\Rightarrow |\underline{A}| = 0$
- $\Rightarrow \begin{vmatrix} a & \bar{1} & \bar{2} \\ 2 & -l & a \\ 3 & a & 4 \end{vmatrix} = 0$
- $\begin{array}{c} \bullet \\ \Rightarrow \\ \alpha \\ \alpha \\ \alpha \\ + \end{array} \begin{vmatrix} -1 \\ 2 \\ 3 \\ 4 \end{vmatrix} \begin{vmatrix} 2 \\ 4 \\ 3 \\ 4 \end{vmatrix} \begin{vmatrix} 2 \\ 2 \\ 3 \\ \alpha \end{vmatrix} = 0$
- $\implies a(-4-a^{2}) (8-3a) + 2(2a+3) = 1$ $\implies -46 - a^{3} - 8 + 3a + 46 + 6 = 0$
- $= 0 = a^3 3a + 2$

- $\implies q^{2}(a-1) + q(a-1) 2(a-1) = 0$ $\implies (a-1)(q^{2}+a-2) = 0$
- (a-1)(a-1)(a+2)=0
- 9 9= < 1 -2. (\$660mm)

Question 14 (**)

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The 3×3 matrix **M** is given below.

$$\mathbf{M} = \begin{pmatrix} 3 & 2 & 1 \\ 1 & -2 & -1 \\ 1 & 0 & 3 \end{pmatrix}$$

- a) Find the inverse of M.
- **b**) Hence, or otherwise, solve the following system of equations.

$$3x+2y+z=7$$
$$x-2y-z=1$$
$$x + 3z = 11$$

$$\square, \mathbf{M}^{-1} = \frac{1}{12} \begin{pmatrix} 3 & 3 & 0 \\ 2 & -4 & -2 \\ -1 & -1 & 4 \end{pmatrix}, x = 2, y = -1,$$

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$$\begin{array}{c} \textbf{q} \\ \textbf{m} \\ \textbf$$

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Question 15 (**)

A 3×3 matrix **T** represents the linear transformation

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$$\mathbf{T}\begin{pmatrix} x\\ y\\ z \end{pmatrix} : \mapsto \begin{pmatrix} X\\ Y\\ Z \end{pmatrix}$$

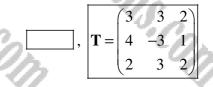
so that

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$$\mathbf{T}\begin{pmatrix}1\\0\\0\end{pmatrix}:\mapsto \begin{pmatrix}3\\4\\2\end{pmatrix}, \quad \mathbf{T}\begin{pmatrix}1\\1\\0\end{pmatrix}:\mapsto \begin{pmatrix}6\\1\\5\end{pmatrix}, \quad \mathbf{T}\begin{pmatrix}2\\1\\-4\}:\mapsto \begin{pmatrix}1\\1\\-1\end{pmatrix}.$$

Find the elements of T.



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WORLING ON ON 1 LAND THE WARD UPDATE ON AND THE AD THE AD
THE REST COLUMN OF THE MATRIX
$\underline{T} = \begin{bmatrix} 3 & a & b \\ 4 & c & d \\ 2 & e & \xi \end{bmatrix}$
🙆 NOW WE MAP THE OHGETWO NECTORS, OBTIGNING SMUTCHARDUS EPUATIONS
$\begin{bmatrix} 3 & a & b \\ 4 & c & b \\ 2 & e & -f \\ 2 & e & -f \\ \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 1 & 1 \\ 0 & -4 \\ \end{bmatrix} = \begin{bmatrix} 4 & 1 \\ 1 & 1 \\ 5 & -1 \\ \end{bmatrix}$
$\begin{bmatrix} I & a \\ + t & c & s + c \\ - t & z + e & + c \\ - t & z + z \\ - t & z $
THESE GRAPTICAN VIEWD
• a+3=6 • c+4 =1 • e+2=5
a=3 Ce-3 e=3
• $6+q-4b=1$ • $8+c-b=1$ • $4+e-4t=-1$ 9-4b=1 • $8+z-4b=1$ • $4+z-4t=-18-c+b$ • $8-4tb=2$ $d=1$ $t=2$
HANGE THE BLOW BAD MATERIX IS
$\Box = \begin{bmatrix} 3 & 3 & 2 \\ 4 & -3 & 1 \\ 2 & 3 & 2 \end{bmatrix}$

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Question 16 (**+)

Find the eigenvalues of the following 3×3 matrix.

 $\left(\frac{1}{2}\right)$

 $\mathbf{A} = \begin{pmatrix} 3 & -1 & 1 \\ 2 & 0 & 2 \\ -1 & 1 & 1 \end{pmatrix}.$

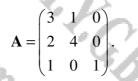
 $\lambda = 0, 2$



Question 17 (**+)

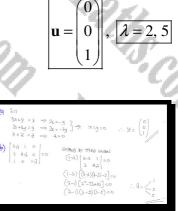
P.C.B.

The 3×3 matrix A is given below.



a) Given that $\lambda = 1$ is an eigenvalue of A find the corresponding eigenvector.

b) Find the other two eigenvalues of A



Question 18 (**+)

A transformation in three dimensional space is defined by the following 3×3 matrix.

$$\mathbf{A} = \begin{pmatrix} 1 & 3 & -1 \\ 2 & 3 & 1 \\ 4 & 0 & -5 \end{pmatrix}$$

a) Find the value of det A.

A cone with a volume of 26 cm³ is transformed by the matrix composition AB^2

b) Given that det $\mathbf{B} = \frac{1}{13}$, calculate the volume of the transformed cone.



2 3 1 4 6 -5	231 4 0-5 (-4) = -45+	$ \begin{vmatrix} = \frac{6xp}{1st} & = 3 \\ 84t = 39 \end{vmatrix}$	3 -6 2 -5 -6 4 -5
	$2 = 39 \times \left(\frac{1}{3}\right)^2 =$	//	

Question 19 (**+)

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The 3×3 matrix **A** is given below.

$$\mathbf{A} = \begin{pmatrix} 3 & 0 & 0 \\ 1 & 1 & 1 \\ 4 & -1 & 3 \end{pmatrix}$$

- a) Show that A only has two eigenvalues.
- **b**) Find the eigenvectors associated with each of these eigenvalues.

	4/0
(a) GHR49782155 ERUATION)	$\begin{cases} \underbrace{(k)}_{j=1}^{k} \bullet F_{j} = 3 \\ 3z_{j} = \frac{1}{2} \underbrace{(k_{j} + 2z_{j} = 3z_{j})}_{(k_{j} + 2z_{j} + 2z_{j} = 3z_{j})} \Rightarrow \frac{1}{2} \underbrace{(k_{j} - 2z_{j} + 2z_{j} = 3z_{j})}_{(k_{j} + 2z_{j} + 2z_{j} = 3z_{j})} \Rightarrow \underbrace{(k_{j} - 2z_{j} + 2z_{j} = 3z_{j})}_{(k_{j} + 2z_{j} + 2z_{j} = 3z_{j})} \Rightarrow \underbrace{(k_{j} - 2z_{j} + 2z_{j} = 3z_{j})}_{(k_{j} + 2z_{j} + 2z_{j} = 3z_{j})} \Rightarrow \underbrace{(k_{j} - 2z_{j} + 2z_{j} + 2z_{j} + 2z_{j})}_{(k_{j} + 2z_{j} + 2z_{j} + 2z_{j} + 2z_{j})} \Rightarrow \underbrace{(k_{j} - 2z_{j} + 2z_{j} + 2z_{j} + 2z_{j})}_{(k_{j} + 2z_{j} + 2z_{j} + 2z_{j} + 2z_{j})} \Rightarrow \underbrace{(k_{j} - 2z_{j} + 2z_{j} + 2z_{j} + 2z_{j})}_{(k_{j} + 2z_{j} + 2z_{j} + 2z_{j})} \Rightarrow \underbrace{(k_{j} - 2z_{j} + 2z_{j} + 2z_{j} + 2z_{j})}_{(k_{j} + 2z_{j} + 2z_{j} + 2z_{j})} \Rightarrow \underbrace{(k_{j} - 2z_{j} + 2z_{j} + 2z_{j} + 2z_{j})}_{(k_{j} + 2z_{j} + 2z_{j} + 2z_{j})} \Rightarrow \underbrace{(k_{j} - 2z_{j} + 2z_{j} + 2z_{j} + 2z_{j})}_{(k_{j} + 2z_{j} + 2z_{j} + 2z_{j})} \Rightarrow \underbrace{(k_{j} - 2z_{j} + 2z_{j} + 2z_{j})}_{(k_{j} + 2z_{j} + 2z_{j} + 2z_{j})}$
$ \begin{array}{c} \Rightarrow \left(\widehat{\boldsymbol{3}} \cdot \boldsymbol{\Lambda}\right) \left \begin{array}{c} l \cdot \boldsymbol{\lambda} & l \\ -l & 3 \cdot \boldsymbol{\lambda} \end{array} \right = 0 \\ \Rightarrow \left(3 \cdot \boldsymbol{\lambda}\right) \left[\left(l \cdot \boldsymbol{\lambda}\right) \left(3 \cdot \boldsymbol{\lambda}\right) + l \right] = 0 \\ \Rightarrow \left(3 \cdot \boldsymbol{\lambda}\right) \left(\left(3 \cdot \boldsymbol{\lambda}\right) \left(3 \cdot \boldsymbol{\lambda}\right) + l \right) = 0 \\ \Rightarrow \left(3 \cdot \boldsymbol{\lambda}\right) \left(\left(3 \cdot \boldsymbol{\lambda}\right) + l \right) = 0 \\ \Rightarrow \left(3 \cdot \boldsymbol{\lambda}\right) \left(3 \cdot \boldsymbol{\lambda} + \boldsymbol{\lambda}\right) = 0 \end{array} $	$\begin{cases} \vdots \left(\begin{array}{c} q = 4\lambda \\ r \end{array} \right) \neq \begin{array}{c} a - b_{1} + 2 = a \\ \hline c \end{array} \\ \vdots \\ c \end{array} \\ \cdot \left(\begin{array}{c} 4 \\ r \\ 7 \end{array} \right) \\ \cdot H & b_{2} \\ \hline c \end{array} \\ \cdot \left(\begin{array}{c} a \\ b \\ r \end{array} \right) = \left(\begin{array}{c} a \\ r \\ r \\ r \end{array} \right) \\ \cdot H & b_{2} \\ \hline c \end{array} \\ \cdot \left(\begin{array}{c} a \\ r \\ r \\ r \end{array} \right) \\ \cdot H & b_{2} \\ c \end{array} \\ \cdot \left(\begin{array}{c} a \\ r \\ r \\ r \\ r \end{array} \right) \\ \cdot \left(\begin{array}{c} a \\ r \\ r \\ r \\ r \end{array} \right) \\ \cdot \left(\begin{array}{c} a \\ r \\ r \\ r \\ r \\ r \end{array} \right) \\ \cdot \left(\begin{array}{c} a \\ r \\$
$\Rightarrow (3-2)(\lambda-2)^{2} = 0$ $\Rightarrow \lambda = \sqrt{3} (2.84mb)$	$\begin{array}{c c} & & & & \\ & & & & \\ & & & & \\ & & & & $

0

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u =

 $\lambda = 2, \ \lambda = 2, \ \lambda = 3$,

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 $\mathbf{v} =$

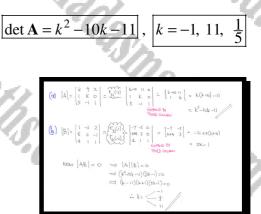
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Question 20 (**+)

The 3×3 matrices **A** and **B** are defined in terms of a scalar constant k by

- $\mathbf{A} = \begin{pmatrix} k & 9 & 2 \\ 1 & k & 0 \\ 5 & -1 & 1 \end{pmatrix} \quad \text{and} \quad \mathbf{B} = \begin{pmatrix} 1 & -3 & 2 \\ k & 2 & -1 \\ 4 & 1 & 1 \end{pmatrix}.$
- **a**) Find an expression for det **A**, in terms of k.
- **b**) Find the possible values of k given that **AB** is singular.



Question 21 (**+)

It is given that A and B are 3×3 matrices that satisfy

 $det(\mathbf{AB}) = 20$ and $det(\mathbf{A}^{-1}) = -4$

A solid S, of volume 5 cm³, is transformed by **B** to produce an image S

Find the volume of S'.

$det (AB) = 20$ $det (A^{-1}) = -4$ \downarrow $det A = -\frac{1}{4}$	} ⇒	$det A \times det B = 30$ $\frac{1}{4} \times det B = 20$ $det B = -80$
		in Volume of THE IMAGE L
		5×80 = 400 aug

 400 cm^3

Question 22 (***)

x+3y+2z = 14 2x + y + z = 73x+2y - z = 7

Solve the above system of simultaneous equations by manipulating their augmented matrix into reduced row echelon form.

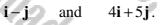
No credit will be given for alternative solution methods.

x = 1, y = 3, z = 2



Question 23 (***)

A 2×2 matrix **M** has eigenvalues $\lambda = -2$ and $\lambda = 7$, with respective eigenvectors



Find the elements of M.



· ·		a-b=-2 c-d= 2 =	=) a= b-2 c= d+2	
$\begin{pmatrix} c & q \\ a & p \end{pmatrix}$	$ \begin{pmatrix} 4 \\ 5 \end{pmatrix} \in \begin{pmatrix} 28 \\ 35 \end{pmatrix} \implies $	44 + 5b = 28 4c + 5d = 35		
1/MCE-	4(b-2) + 5b = 28 9b = 36 b = 4 0 = 2	4(d+2) + 5 9d = 27 d = 3 C = 5	d = 3 $\therefore M = \begin{pmatrix} 2 & 4 \\ 5 & 3 \end{pmatrix}$	
M = UD	$U^{-1} = \begin{pmatrix} t & 4 \\ -1 & 5 \end{pmatrix} \begin{pmatrix} -2 & 0 \\ 0 & 7 \end{pmatrix}$ $= \frac{1}{9} \begin{pmatrix} 18 & 36 \\ 45 & 27 \end{pmatrix} =$	$\begin{pmatrix} \frac{1}{9} \begin{pmatrix} 5 & -4 \\ 1 & 1 \end{pmatrix} = \frac{1}{9} \begin{pmatrix} 2 & 4 \\ 5 & 3 \end{pmatrix}$	(-2 28)(S - +) (2 35)(L)	

Question 24 (***)

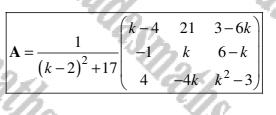
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The 3×3 matrix **A** is given in terms of a constant k below.

$$\mathbf{A} = \begin{pmatrix} k & 3 & 6 \\ 1 & k & 1 \\ 0 & 4 & 1 \end{pmatrix}.$$

- a) Show that A has an inverse for all values of k.
- **b**) Find \mathbf{A}^{-1} in terms of k.



(a) $A = \begin{pmatrix} k & 3 & k \\ 1 & k & 1 \\ 0 & 4 & 1 \end{pmatrix} \qquad [4] = k \begin{vmatrix} k & 1 \\ 4 & 1 \end{vmatrix} - \begin{pmatrix} 3 & k \\ 4 & 1 \end{vmatrix} = k(k-4) - (-2i)$
$= k^2 - 4k + 2l = (k - 2)^2 - 4k + 2l$
$= (k-2)^2 + 17 > 0$
. A mill taways there the invitese
(b) MATERY OF LUNCES = $\begin{pmatrix} k+4 & 1 & 4 \\ -2i & k & 4k \\ 3-6k & k-6 & k^{2}-3 \end{pmatrix}$
MATRIX OF GOARTERS = $\begin{pmatrix} k-4 & -1 & 4\\ 2i & k & -4k \\ 3-6k & 6-k & k^2 & 3 \end{pmatrix}$
$\label{eq:4.1} \begin{array}{rcl} & -4 & 2i & 3-6k \\ & -i & k & 6-k \\ & -4k & k^{2}_{-3} \end{array} \end{array}$
$I_{\bullet} = \frac{1}{(1+2)^{2}+17} \begin{pmatrix} 1 & 2 & 3-4k \\ -1 & k & 6-k \\ 4 & -4k & k^{2}-3 \end{pmatrix}$

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Question 25 (***)

The 2×2 matrix **M** has eigenvalues -2 and 7.

The respective eigenvectors of **M** are $\begin{pmatrix} 1 \\ -1 \end{pmatrix}$ and $\begin{pmatrix} 4 \\ 5 \end{pmatrix}$

Find the entries of M.

 $\mathbf{M} = \begin{pmatrix} 2 & 4 \\ 3 & 5 \end{pmatrix}$

1.00	1 . AL	1. Contraction 1. Con			
(ab) (cd)	Tt+nu	$ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} t \\ -t \end{pmatrix} \begin{pmatrix}$	$= -2 \begin{pmatrix} l \\ -l \end{pmatrix} + \begin{pmatrix} -1 \\ 2 \\ 2 \\ 2 \\ -1 \end{pmatrix} = 7 \begin{pmatrix} 4 \\ 3 \\ 3 \end{pmatrix} = \begin{pmatrix} 3t \\ 3t \\ 3 \\ 3 \end{pmatrix}$:) ;)	
	THUS	a - b = -2 4a + Sb = 2B a = b - 2	c - d = 2, 4c + 5d = 35 c = d + 2		
	4. 4.4	4(b-2) + Sb=28 9 b = 36 b=4 a=2	$\begin{array}{c} 4(b+2)+5d=35\\ 9d=27\\ \vdots \left(\overline{d=3} \right)\\ \overline{(c=5)} \end{array}$		2 4) 8 5)

Question 26 (***)

2x+5y+3z = 2x+2y+2z = 4x+y+4z = 11

Solve the above simultaneous equations by manipulating their augmented matrix into reduced row echelon form.

No credit will be given for alternative solution methods.

x = 12, y = -5, z = 1

$\begin{pmatrix} 2 & 9 \\ 1 & 1 \\ 1 & 1 \end{pmatrix}$	5 3 2 2 1 4	$\left(\begin{array}{c} 2 \\ 4 \\ 1 \end{array} \right) \left(\begin{array}{c} r_{\alpha} \\ r_{\alpha} \end{array} \right)$	$\begin{pmatrix} l & 2 \\ 2 & 5 \\ l & l \end{pmatrix}$	$\begin{pmatrix} 2 & 4 \\ 3 & 2 \\ 4 & 1 \end{pmatrix} \begin{pmatrix} r_2(q) \\ r_3(q) \\ r_6(q) \end{pmatrix} \begin{pmatrix} 1 & 2 & 2 & 4 \\ 0 & (-1 & -6 \\ 0 & -(-2 & 7) \end{pmatrix} \begin{pmatrix} r_{23}(q) \\ r_{23}(q) \\ q \end{pmatrix}$	(0 0 1 1 (1 5 5 4)	
[₁₄ (-t)			$\frac{t^{31}(-d)}{t^{22}(1)}$	$\begin{array}{ccc} SI=\Omega & \ddots & \begin{pmatrix} SI & 0 & 0 & J \\ D_{r}=U & \ddots & \begin{pmatrix} SI & 0 & 0 & J \\ D_{r}=0 & 0 & 0 \end{pmatrix} \\ I=S & & & \\ \end{array}$		

Question 27 (***)

The 3×3 matrices **A** and **B** are given below.

D.

$$\mathbf{A} = \begin{pmatrix} 3 & 4 & 2 \\ 1 & 1 & 4 \\ 4 & 5 & 7 \end{pmatrix} \quad \text{and} \quad \mathbf{B} = \begin{pmatrix} -10 & -14 & 16 \\ 10 & 14 & -6 \\ 5 & 6 & 6 \end{pmatrix}.$$

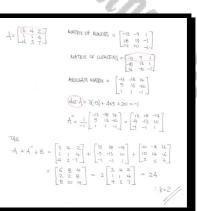
Show clearly that

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 $\mathbf{A} + \mathbf{A}^{-1} + \mathbf{B} = k\mathbf{A} ,$

stating the value of the scalar constant k



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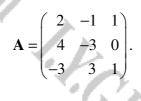
k = 2

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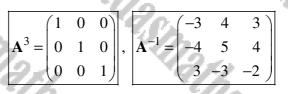
Question 28 (***)

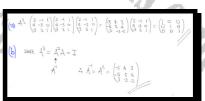
The 3×3 matrix A below, represents a transformation such that $\mathbb{R}^3 \mapsto \mathbb{R}^3$.



a) Find the entries of \mathbf{A}^3 .

b) Determine the entries of \mathbf{A}^{-1}





Question 29 (***)

I.C.B.

Factorize fully the following 3×3 determinant.

 $\begin{vmatrix} 1 & x & y+z \\ 2 & y & z+x \\ 3 & z & x+y \end{vmatrix}.$

|(x+y+z)(x-2y+z)|

 $\begin{array}{|c|c|c|c|c|c|} & & & & & \\ 1 & & & & & \\ 2 & & & & \\ 3 & & & & \\ 3 & & & & \\ 2 & & & \\ 3 & & & \\ 1 & & \\ 3 & & & \\ 1 & & \\ 1 & & \\ 1$

Question 30 (***)

I.C.B.

Solve the following simultaneous equations by manipulating their augmented matrix into reduced row echelon form.

 $\begin{pmatrix} 1 & 1 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 5 \\ 8 \\ 8 \end{pmatrix}$

x = 2, y = -1, z = 4

 $\begin{pmatrix} 1 & 5 \\ (& 3 \\ -2 \end{pmatrix} \int_{23}^{2} (-2)$

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No credit will be given for alternative solution methods.

Question 31 (***)

The 3×3 matrix **D** is given below in terms of the constants a, b, c and d.

$$\mathbf{D} = \begin{pmatrix} a & 1 & b \\ c & 7 & 0 \\ 3 & d & 2 \end{pmatrix}.$$

It is further given that

 $\mathbf{u} = \mathbf{i} + 3\mathbf{k}$ and $\mathbf{u} = 3\mathbf{i} + 4\mathbf{j} + \mathbf{k}$

are eigenvectors of **D** with corresponding eigenvalues λ and μ .

Determine in any order the value of a, b, c, d, λ and μ .

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$\begin{pmatrix} c & 7 & 0 \\ 3 & d & 2 \end{pmatrix} \begin{pmatrix} 0 \\ 3 \end{pmatrix} = \mathcal{N} \begin{pmatrix} 0 \\ 3 \end{pmatrix} \implies 3$	+ 3b=7 () C=0 (2) + 6=37 (3)
$ \begin{pmatrix} \alpha & i & b \\ c & 7 & c \\ 3 & d & 2 \end{pmatrix} \begin{pmatrix} 3 \\ 4 \\ i \end{pmatrix} = i^{*} \begin{pmatrix} 3 \\ 4 \\ i \end{pmatrix} \implies \begin{cases} 34 \\ 34 \end{cases} $	+4q + s = 4n (2) $+4q + s = 4n (2)$ (4)
$ \begin{array}{c} \textcircled{2} \hline \hline$	=7 =-4- =-1
$ \begin{array}{c} (\underline{\delta} & \underline{\eta} = 3\lambda \\ \hline \underline{\beta=3} & \Longrightarrow (\underline{0} & \alpha+3b=3 \\ \underline{\delta} & \underline{\delta} & \alpha+b=17 \end{array} \xrightarrow{3\alpha} \begin{array}{c} \underline{\delta} & \underline{\delta} & \alpha+3b=3 \\ \underline{\delta} & \underline{\delta} & \underline{\delta} & \alpha+b \end{array} $	$= \frac{1}{2} = \frac{1}{2} \Rightarrow \frac{1}{2} = $
$\begin{array}{cccc} +\mu v \mathcal{L} & \mathcal{L} & \mathcal{L} \\ & & \mathcal{L} $	

a=6, b=-1, c=0, d=-1, $\lambda=3$, $\mu=7$

Question 32 (***)

The 2×2 matrix **A** and the 3×3 matrix **B** are given below.

$$\mathbf{A} = \begin{pmatrix} 1 & 2 \\ 2 & -4 \end{pmatrix} \text{ and } \mathbf{B} = \begin{pmatrix} 2 & 1 & 1 \\ 1 & 1 & 0 \\ 0 & 2 & 1 \end{pmatrix}$$

The straight line L_1 with equation

$$y = x + k ,$$

where k is a constant, is transformed by **A**.

a) Find an equation for the image of L_1 under **A**.

The straight line L_2 with Cartesian equation

$$\frac{x-1}{2} = \frac{y-3}{2} = z-2$$

is transformed by **B**.

b) Find a Cartesian equation for the image of L_2 under **B**.

$$2x + 3y = 16k, \qquad \boxed{\frac{x - 7}{7} = \frac{y - 4}{4} = \frac{z - 8}{5}}$$

$$(4) \qquad y = 3 + k \qquad \text{MONITORE} \qquad 3 = k \\ y = 0 + k \qquad \text{MONITORE} \qquad 3 = k \\ (y) = (\frac{z}{4}, -1) \\ (y) = (\frac{z}{4},$$

Question 33 (***)

The 3×3 matrix **A** is given in terms of the scalar constant k by

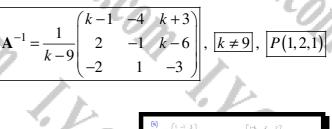
$$\mathbf{A} = \begin{pmatrix} 1 & -1 & 3 \\ 2 & 1 & k \\ 0 & 1 & 1 \end{pmatrix}$$

- **a**) Find, in terms of k, the inverse of **A**.
- **b**) State the condition that k must satisfy, so that the inverse matrix exists.

Now suppose that k = 4.

The point P has been transformed by the matrix A into the point Q(2,8,3).

c) Determine the coordinates of P.



(a) $A = \begin{pmatrix} 1 & -1 & 3 \\ 2 & 1 & k \\ 0 & 1 & 1 \end{pmatrix}$	MATRIX OF UNITES = $\begin{bmatrix} 1-k & 2 & 2 \\ -2 & (& 1 \\ -k-3 & k-6 & 3 \end{bmatrix}$
	MATER OF GORGERESS (1-6 -2 2 2 1 -1 _2-3 -4246 3
	$\label{eq:approximate} \text{Absolute MATRix} = \begin{bmatrix} 1 - k & 2 & -k - 3 \\ -2 & 1 & -k \cdot 6 \\ 2 & -1 & 3 \end{bmatrix}$
der:A = 1(1-64-1(2)	$\begin{split} & 43 \mathcal{K}_{2, 1}: -l_{\mathbf{x}}^{-1} + 2 + 2_{\mathbf{x}} \in \mathbf{z} = 3_{\mathbf{x}} 1_{\mathbf{x}} \\ & \mathbf{z} = \frac{l}{\mathbf{q}_{\mathbf{x}}} 1_{\mathbf{x}} = \frac{l}{\mathbf{q}_{\mathbf{x}}} 1_{\mathbf{x}} - \mathbf{z}_{\mathbf{x}} + \mathbf{z}_{\mathbf{x}} \mathbf{z}_{\mathbf{x}} \\ & \mathbf{z} = -\mathbf{z} + \mathbf{z}_{\mathbf{x}} \mathbf{z}_{\mathbf{x}} \\ & \mathbf{z} = -\mathbf{z} + \mathbf{z}_{\mathbf{x}} \mathbf{z}_{\mathbf{x}} \end{bmatrix} \approx \frac{l}{\mathbf{k} - \mathbf{q}} \begin{bmatrix} \mathbf{L}_{\mathbf{x}} & -\mathbf{z}_{\mathbf{x}} \mathbf{k} \mathbf{z}_{\mathbf{x}} \\ \mathbf{z} = -\mathbf{k} + \mathbf{c}_{\mathbf{x}} \\ \mathbf{z} = -\mathbf{z} + -\mathbf{z}_{\mathbf{x}} \end{bmatrix} \end{split}$
(b) k≠ q	
(c) $\begin{cases} A_{i} = A_{i} \neq \\ A_{i} A_{j} = A_{i} \neq \\ P = A_{i$	$ \begin{split} & \overset{\mathtt{a}}{=} -\frac{t}{4} \begin{pmatrix} 3 & -\mathbf{q} & \mathbf{T} \\ 2 & -1 & -2 \\ -2 & t & -3 \end{pmatrix} \begin{pmatrix} 2 \\ 8 \\ 3 \end{pmatrix} = +\frac{t}{4} \begin{pmatrix} \mathbf{G} - 3\mathbf{r} + 2\mathbf{I} \\ \mathbf{d} - 3\mathbf{r} - \mathbf{G} \\ -\frac{2}{7} + 4\mathbf{G} - \mathbf{q} \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix} \\ & \overset{\mathtt{a}}{=} \mathbf{P} \begin{pmatrix} \mathbf{D} \\ \mathbf{P} \\ \mathbf{I} \end{pmatrix} \end{split} $

Question 34 (***)

The 3×3 matrix **M** is given below, in terms of a scalar constant k.

$$\mathbf{M} = \begin{pmatrix} k & 0 & 2 \\ 4 & 3 & 2 \\ -2 & -1 & 0 \end{pmatrix}$$

- **a**) Show that $\lambda_1 = 1$ is an eigenvalue of **M** for all values of k.
- **b**) Given that $\begin{vmatrix} -2 \\ 1 \end{vmatrix}$ is an eigenvector of **M** with corresponding eigenvalue $\lambda_2 \neq 1$.

find the values of λ_2 and the value of k.

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c) Find the value of the third eigenvalue of M

 $\lambda_2 = -2$ $|k = -3|, |\lambda_3 = 1$

Question 35 (***)

The 3×3 matrices **A** and **B** are given below.

 $\mathbf{A} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \quad \text{and} \quad \mathbf{B} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix},$

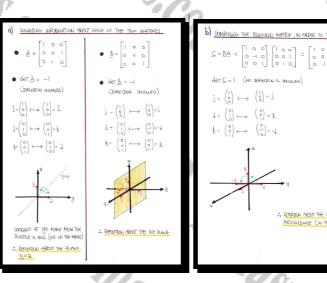
a) Describe geometrically the transformations given by each of the two matrices.

The matrix C is defined as the transformation defined by the matrix A, followed by the transformation defined by the matrix B.

b) Describe geometrically the transformation represented by C.

, **A** : reflection in the plane y = z, **B** : reflection in the *xz* plane,

C: rotation in the x axis, 90°, anticlockwise



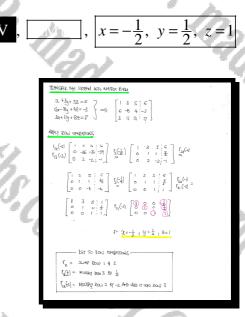
Question 36 (***)

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x + 3y + 5z = 6 6x - 8y + 4z = -33x + 11y + 13z = 17

Solve the above system of simultaneous equations by manipulating their augmented matrix into reduced row echelon form.



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Question 37 (***)

The matrix $\mathbf{A}: \mathbb{R}^2 \mapsto \mathbb{R}^2$ and the matrix $\mathbf{B}: \mathbb{R}^3 \mapsto \mathbb{R}^3$ are defined as

 $\mathbf{A} = \begin{pmatrix} 1 & 0 \\ 3 & 1 \end{pmatrix} \quad \text{and} \quad \mathbf{B} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos 45^\circ & -\sin 45^\circ \\ 0 & \sin 45^\circ & \cos 45^\circ \end{pmatrix}$

Describe geometrically the transformations given by each of these matrices. State in each case the equation of the line of invariant points.

, **A** : shear parallel to y axis, $(1,0) \mapsto (3,1)$

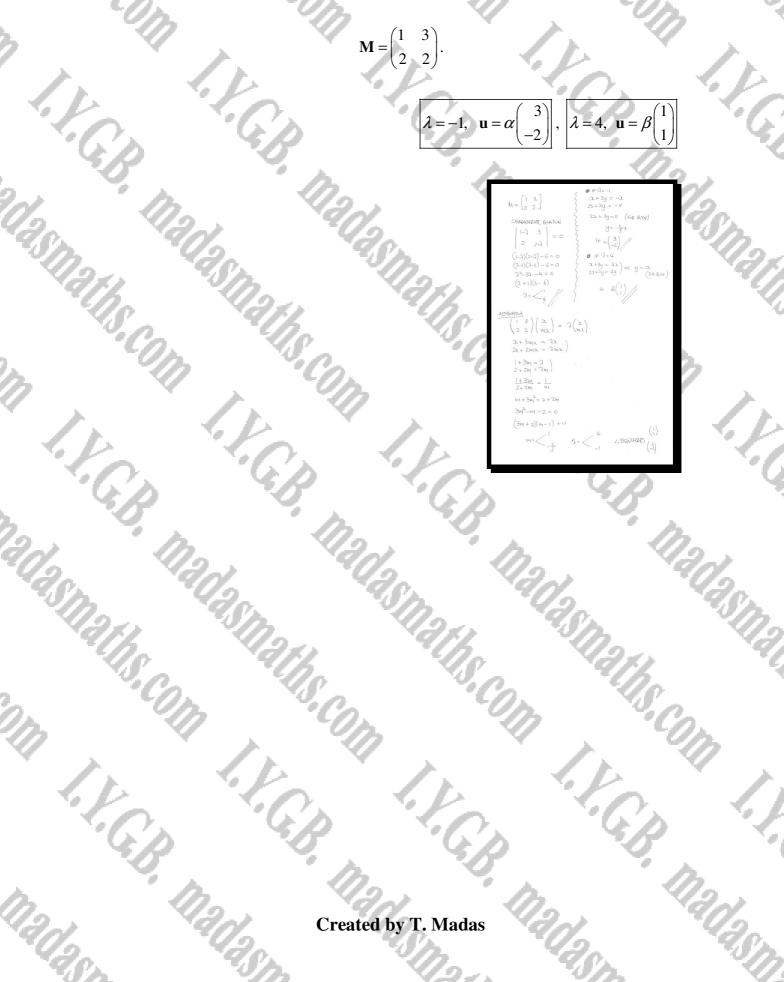
B: rotation in the x axis, 45°, anticlockwise, $\mathbf{A}: x = 0$, $\mathbf{B}: y = z = 0$, i.e. x axis

$\underline{A} = \begin{pmatrix} I & 0 \\ 3 & I \end{pmatrix}$	(A)=1 if AllA	IS PRI-SHAXD , NO REFLECTION
$\frac{i}{l} = \begin{pmatrix} l \\ o \end{pmatrix} \longmapsto$	$\begin{pmatrix} t \\ 3 \end{pmatrix}$	
$\stackrel{\bullet}{\simeq} = \begin{pmatrix} 0 \\ l \end{pmatrix} \longmapsto$		9 A
THE MATRIX DEPRISE	HURSTA SHEAR PARALLE	+ A ((,+)
(ZXXX & SHT OT	WHERE (110) Har (113)	3 - (1,3)
$\binom{1}{3}\binom{1}{1}\binom{1}{1} = \binom{1}{1}$	(¹ 4	2
INUMPLIANST ARE THE		
ON THE CY AXIS)	IE SEO	
$\underline{B} = \begin{bmatrix} 1 & 0 \\ 0 & \cos 4s \\ 0 & \sin 4s \end{bmatrix}$	0 = [<u>4]</u> = (2450)	(2245 + 518 ² 45 = 1
4 4 a y	5 6 100020	
i ⊢⇒ í	& "THE GREEN SECTION	N ⁴ IS A SMALDARD ROTATION KWIRE ABDIT O, OF THE 92
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Question 38 (***)

Find the eigenvalues and the corresponding eigenvectors of the following 2×2 matrix.



Question 39 (***)

A transformation of the x-y plane is represented by the following 2×2 matrix.

$$\mathbf{D} = \begin{pmatrix} -5 & 9\\ -4 & 7 \end{pmatrix}.$$

The straight line with equation of the form y = ax, where *a* is the gradient, is in the direction of the eigenvector of **D**.

- a) Find the equation of this straight line, stating whether this line is an invariant line or a line of invariant points.
- **b**) Show that all the straight lines of the form y = ax + c, where c is a constant, remain invariant under the transformation represented by **D**.

PROPERTY.	
(a)	$D = \begin{pmatrix} -z & g \\ -4 & 7 \end{pmatrix} \xrightarrow{\text{observed}} \begin{pmatrix} a + b + c -z + a \\ -4 & 7 - z \end{pmatrix} = o$
	=5(-5-3)(7-3)+36=0
	\Rightarrow $(3+s)(3-r) + 36 = 0$
	$\Rightarrow \lambda^2 - 2\lambda - 35 + 36 = 0$
	$\Rightarrow \lambda^2 - 2\lambda + 1 = 0$
	==) (2-1) ² = 0
	=> A=1
	$\begin{array}{ccc} Elbhaddall & -Sach Ay = \mathfrak{A} \\ & -Aach Ag = \mathfrak{g} \end{array} \Rightarrow \begin{array}{c} Ag = back \\ ag = back \end{array} \Rightarrow \begin{array}{c} g = \frac{2}{3}\mathfrak{A} \end{array}$
	//
	TT IS A WINE OF INVOLUTION TO A CONTRACT POINTS, BEERVISE 9-1
· (b)	$ \begin{pmatrix} -5 & 9 \\ -4 & 7 \end{pmatrix} \begin{pmatrix} t \\ \frac{2}{3}t+C \end{pmatrix} = \begin{pmatrix} \times \\ \checkmark \end{pmatrix} $
	$\begin{array}{c} -St \models 6t \models q_{C} &\cong \times \\ -4t \models \underbrace{g}_{t} + 7c &= \curlyvee \end{array} \xrightarrow{>}$
	X= t+ 9c } Y= ² / ₃ t+7c } ⇒
	$ \begin{cases} 3X = \frac{2}{3}t + 7c \\ Y = \frac{2}{3}t + 7c \\ \end{cases} $ Substant
	$Y - \frac{2}{3}X = C$
	Y = 3X+C It MUMRIMUT CANE

Question 40 (***)

Solve the following simultaneous equations by manipulating their augmented matrix into reduced row echelon form.

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, $x = -10, \quad y = 19, \quad z = 1$

Question 41 (***) The 3×3 matrix M is given below.

 $\mathbf{M} = \begin{pmatrix} -3 & 0 & 0 \\ 0 & -3 & 0 \\ 0 & 0 & 3 \end{pmatrix}$

M describes two consecutive linear transformations of 3 dimensional space, which can be carried out in any order.

Describe geometrically each these two transformations.

rotation about z axis, 180° , uniform enlargement, S.F. = 3

Question 42 (***)

The system of simultaneous equations

x + y + 2z = 2x + 2y + z = 22x + ay + 5z = b

 $\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 2 - 3t \\ t \\ t \end{pmatrix},$

where a and b are constants, does **not** have a unique solution, but it is **consistent**.

a) Determine the value of a and the value of b.

b) Show that the general solution of the system can be written as

where t is a parameter.

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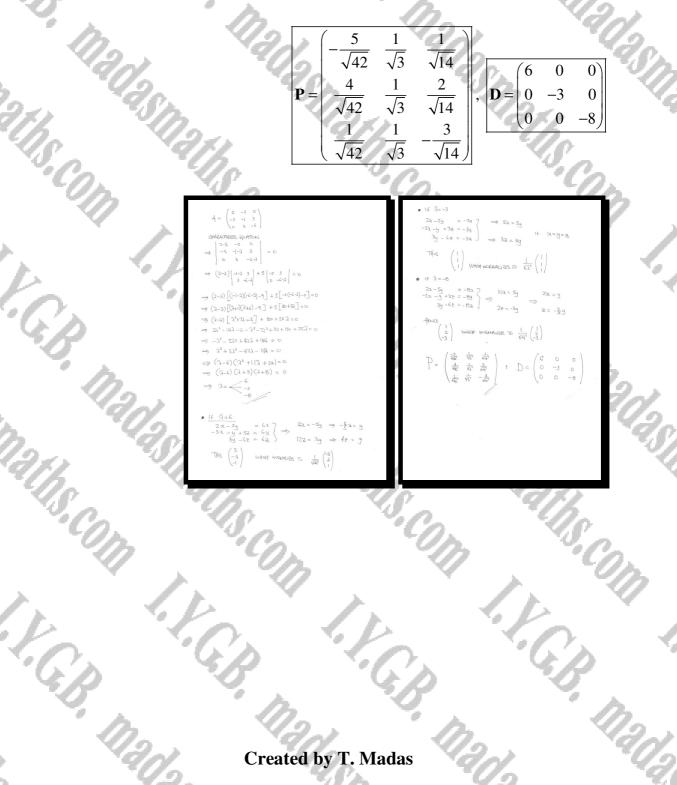
 $\begin{array}{l} (a) & \left| \begin{array}{c} i & i & 2 \\ 2 & a & 5 \\ 2 & a & 5 \\ 4 & c & 5 \\ 4 & c & 5 \end{array} \right| \left| \begin{array}{c} 1 & -2 \\ a & -1 \\ c & -1 \\ c & -1 \\ c & -1 \end{array} \right| = \left| \begin{array}{c} 1 & -1 \\ a & -1 \\ c & -$

Question 43 (***)

The 3×3 matrix **A** is given below.

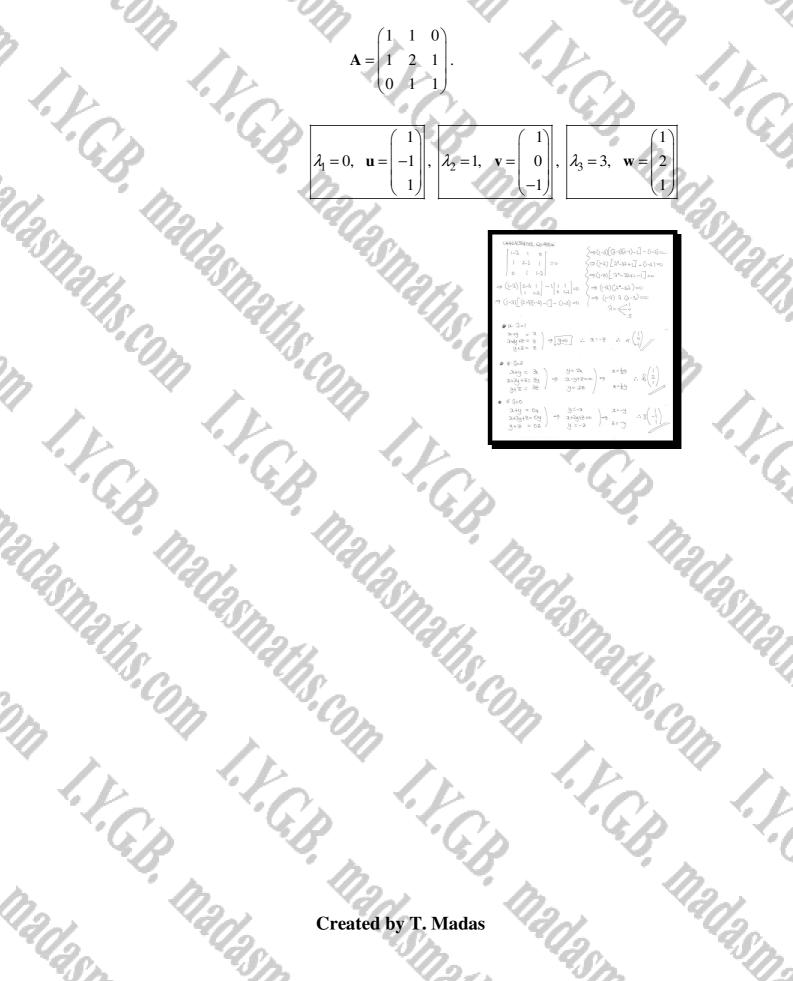
$$\mathbf{A} = \begin{pmatrix} 2 & -5 & 0 \\ -5 & -1 & 3 \\ 0 & 3 & -6 \end{pmatrix}$$

As **A** is a symmetric matrix, find the orthogonal 3×3 matrix **P** and a diagonal 3×3 matrix **D** such that $\mathbf{P}^{T}\mathbf{A}\mathbf{P} = \mathbf{D}$.



Question 44 (***)

Find the eigenvalues and the corresponding eigenvectors of the following 3×3 matrix.



Question 45 (***)

A linear transformation T in the x - y plane consists of a reflection about the straight line with equation

 $y = x \tan \alpha^{\circ}$,

followed by an anticlockwise rotation about the origin O, by an angle of β°

By considering matrix compositions, or otherwise, describe T geometrically.

reflection in the line $y = \tan\left(\alpha^{\circ} + \frac{\beta^{\circ}}{2}\right)$

$\begin{array}{llllllllllllllllllllllllllllllllllll$	
$ \begin{array}{llllllllllllllllllllllllllllllllllll$	лх 24
$ \begin{bmatrix} \log(2\alpha+\theta) & \sin(2\alpha+\theta) \\ \log(2\alpha+\theta) & -\cos(2\alpha+\theta) \end{bmatrix} $	
Reputing in the call $y = \tan(x + \frac{g}{2}) x$	

Question 46 (***)

x+3y+2z=13 3x+2y - z = 42x + y + z = 7

Solve the above system of simultaneous equations by manipulating their augmented matrix into reduced row echelon form.

No credit will be given for alternative solution methods.

x = 1, y = 2, z = 3

Question 47 (***)

The 3×3 matrix **A** is given below.

$$\mathbf{A} = \begin{pmatrix} 3 & 1 & -3 \\ 2 & 4 & 3 \\ -4 & 2 & -1 \end{pmatrix}$$

The matrix A is non singular.

a) Evaluate $\mathbf{A}^2 - \mathbf{A}$.

b) Show clearly that

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 $=\frac{1}{20}[\mathbf{A}-\mathbf{I}].$

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 $\begin{array}{l} \left(\begin{array}{c} \bullet \\ & A_{1}^{-1} \begin{pmatrix} 3 & 1 & -3 \\ 2 & 4 & 3 \\ 0 & -3 \end{pmatrix} \begin{pmatrix} 5 & 1 & -3 \\ 2 & 4 & 3 \\ 0 & -3 \end{pmatrix} = \begin{pmatrix} 2 & 0 & -3 \\ 2 & 4 & 3 \\ 0 & -3 \end{pmatrix} = \begin{pmatrix} 2 & 0 & -3 \\ 0 & -3 \\ 0 & -3 \end{pmatrix} = \begin{pmatrix} 2 & 0 & -3 \\ 0 & -3 \\ 0 & -3 \end{pmatrix} = \begin{pmatrix} 2 & 0 & -3 \\ 0 & -3 \\ 0 & -3 \end{pmatrix} = \begin{pmatrix} 2 & 0 & -3 \\ 0 & -3 \\ 0 & -3 \end{pmatrix} = \begin{pmatrix} 2 & 0 & -3 \\ 0 & -3 \\ 0 & -3 \\ 0 & -3 \end{pmatrix} = \begin{pmatrix} 2 & 0 & -3 \\ 0 & -3 \\ 0 & -3 \\ 0 & -3 \end{pmatrix} = \begin{pmatrix} 2 & 0 & -3 \\ 0 &$

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Question 48 (***)

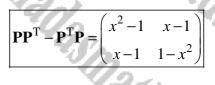
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I.C.B.

The 2×2 matrix **P** is defined in terms of x, where $x \neq 1$.

 $\mathbf{P} = \begin{pmatrix} 2 & x \\ 1 & 3 \end{pmatrix}.$

- **a**) Find in its simplest form the matrix $\mathbf{PP}^{T} \mathbf{P}^{T}\mathbf{P}$.
- **b**) Show clearly that $det(\mathbf{P}\mathbf{P}^{\mathrm{T}} \mathbf{P}^{\mathrm{T}}\mathbf{P}) < 0$.



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Question 49 (***)

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$$\begin{pmatrix} 2 & 5 & 3 \\ 1 & 2 & 2 \\ 1 & 1 & 3 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 2 \\ 4 \\ 10 \end{pmatrix}.$$

Show that the above system of simultaneous equations ...

a) ... does **not** have a unique solution.

b) ... is consistent and the general solution can be written as

 $16-4\lambda$ y

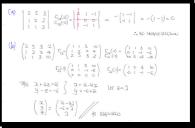
where λ is a scalar parameter.

proof

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Question 50 (***)

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The 3×3 matrix **A** is given below, in terms of a scalar constant k.

$$\mathbf{A} = \begin{pmatrix} k & 0 & 1 \\ -11 & k - 3 & 9 \\ -11 & 0 & k \end{pmatrix}$$

- a) Given that A is singular, find the value of k.
- **b**) Given instead that $\lambda = 2$ is an eigenvalue of **A**, determine the value of k on this occasion.

k=3, k=5

= (k-3)(k2+11)

 $\Rightarrow \left[\left(k-2\right) -3 \right] \left[\left(k-2\right)^{2} +11 \right] = \infty$

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(k-3) k

⇒ k=3

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Question 51 (***)

Three planes, the equations of which are given below, intersect along a straight line L.

$$x+2y+3z=2$$

$$2x+3y + z = 3$$

$$3x+4y - z = k$$

Show, by reducing an augmented matrix into row echelon form, that the equation of L can be written in the form

$$\mathbf{r} = \mathbf{j} + t (7\mathbf{i} - 5\mathbf{j} + \mathbf{k}),$$

where t is a scalar parameter.

1+3y+3z=2 2+3y+z=3 <u>fuceuns</u> + summ 2+4y-z=k 3 4-1 k
$ = - \frac{\Gamma_{12}(-2)}{\Gamma_{13}(-2)} = = \begin{pmatrix} 1 & 2 & 3 & 2 \\ 0 & -1 & -5 & -1 \\ 0 & -2 & -10 & k-6 \end{pmatrix} = \Gamma_{2}(-1)_{-} \begin{pmatrix} 1 & 2 & 3 & 2 \\ 0 & 1 & s & 1 \\ 0 & -2 & -10 & k-6 \end{pmatrix} $
$ \begin{array}{c} \cdots \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ $
$ \begin{pmatrix} 0 & 1 & 2 & 1 \\ 0 & 1 & 2 & 1 \end{pmatrix} = \dots = \begin{pmatrix} \gamma_{2i}(-2) & \cdots & \begin{pmatrix} 0 & 1 & 2 & 1 \\ 0 & 1 & 2 & 1 \end{pmatrix} \xrightarrow{\sim} \begin{pmatrix} 0 & 1 & 2 & 1 \\ 0 & 1 & 2 & 1 \end{pmatrix} \xrightarrow{\sim} \begin{pmatrix} 0 & 1 & 2 & 1 \\ 0 & 1 & 2 & 1 \end{pmatrix} $
$ \begin{pmatrix} r\\ 2^{-}\\ i \\ i \\ i \\ i \end{pmatrix} \ddagger + \begin{pmatrix} \sigma\\ \sigma \\ i \\ i \end{pmatrix} = \begin{pmatrix} g\\ g\\ z \\ z$

proof

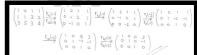
Question 52 (***)

Solve the following simultaneous equations by manipulating their augmented matrix into reduced row echelon form.

 $\begin{pmatrix} 1 & 2 & 1 \\ 1 & 1 & 3 \\ 3 & 5 & 3 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 4 \end{pmatrix}$

No credit will be given for alternative solution methods.

x = 3, y = -1, z = 0



Question 53 (***)

3x - 2y - 18z = 62x + y - 5z = 25

Show, by reducing the system into row echelon form, that the solution can be written in the form

 $\mathbf{r} = 8\mathbf{i} + 9\mathbf{j} + \lambda (4\mathbf{i} - 3\mathbf{j} + \mathbf{k}),$

where λ is a scalar parameter.

proof

 $\begin{array}{c} (4)\frac{2}{2}\left(\underbrace{\frac{3}{2}}_{\frac{1}{2}},\underbrace{\frac{3}{2}}_{-\frac{1}{2}},\underbrace{\frac{1}{2}}_{-\frac{1}{2}}\right)\left(\underbrace{\frac{3}{2}}_{\frac{1}{2}},\underbrace{\frac{1}{2}}_{-\frac{1}{2}},\underbrace{\frac{1}{2}}_{-\frac{1}{2}}\right)\left(\underbrace{\frac{3}{2}}_{-\frac{1}{2}},\underbrace{\frac{1}{2}},\underbrace{\frac{1}{2},\underbrace{\frac{1}{2}},\underbrace{\frac{1}{2}},\underbrace{\frac{1}{2},\underbrace{\frac{1}{2}},\underbrace{\frac{1}{2},\underbrace{\frac{1}{2}},\underbrace{\frac{1}{2},\underbrace{\frac$

Question 54 (***)

The 3×3 matrix **R** is defined by

$$\mathbf{R} = \begin{pmatrix} -1 & 0 & 0\\ 0 & 1 & 0\\ 0 & 0 & 1 \end{pmatrix}.$$

The image of the straight line L, when transformed by **R**, is the straight line with Cartesian equation

$$\frac{x+2}{3} = \frac{y-1}{2} = \frac{z-1}{4}.$$

Find a Cartesian equation for L.

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START BY FINDIND THE INVARE OF R - USE ELENDRAMEY
ROW OPERATIONS
$\begin{bmatrix} - & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0$
PheAwetterze The live
$\frac{\Im_{4}\chi}{3} = \frac{g-1}{2} = \frac{\chi-1}{4} \xrightarrow{g-\chi} \Longrightarrow \qquad \Im = \Im_{4} = 2$ $g = \chi_{4} + 1$ $Z = \xi \chi + 1$
$\Rightarrow \underline{X} = \underline{P} \underline{a}$
$\Rightarrow \underline{R} \times = \underline{R} \underline{R} \times$
$\Rightarrow x = R' X$
$ \overrightarrow{\begin{array}{c} \begin{array}{c} \begin{array}{c} x \\ y \\ z \end{array} \end{array}} = \left(\begin{array}{c} -1 & \circ & \circ \\ \circ & i & \circ \\ \circ & \circ & i \end{array} \right) \left[\begin{array}{c} 2\lambda + 2 \\ 2\lambda + 1 \\ 4\lambda + 1 \end{array} \right] = \left[\begin{array}{c} -3\lambda + 2 \\ 2\lambda + 1 \\ 4\lambda + 1 \end{array} \right] $
tournatt & to get
$\frac{2-2}{-5} = \frac{32-1}{2} = \frac{32-1}{4} = 2$
- op
$\frac{2-\chi}{3} = \frac{3-1}{2} = \frac{2-1}{4}$

 $\frac{x-2}{-3}$

Question 55 (***)

The 3×3 matrices **A** and **B** are given below.

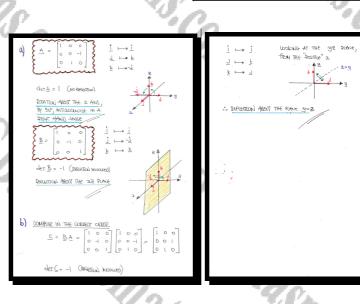
0 0 0) 0 1 0 0 -1 -10 and **B** = 0 0 0 0 0

a) Describe geometrically the transformations given by each of the two matrices.

The matrix C is defined as the transformation defined by the matrix A, followed by the transformation defined by the matrix B.

b) Describe geometrically the transformation represented by C.

, **A**: rotation about x axis, 90° anticlockwise, **B**: reflection in the xz plane,



C : reflection in the plane y = z

Question 56 (***)

The vectors **u**, **v** and **w** are defined as

$$\mathbf{u} = \begin{bmatrix} 1 \\ 2 \\ 8 \end{bmatrix}, \quad \mathbf{v} = \begin{bmatrix} 10 \\ 5 \\ a \end{bmatrix}, \quad \mathbf{w} = \begin{bmatrix} -2 \\ 1 \\ 2 \end{bmatrix}$$

where a is a scalar constant.

Given that \mathbf{u} , \mathbf{v} and \mathbf{w} are linearly dependent, determine the value of a and hence express \mathbf{u} in terms of \mathbf{v} and \mathbf{w} .

, $\underline{a=26}$, $\mathbf{u}=\frac{1}{4}\mathbf{v}+\frac{3}{4}\mathbf{w}$

$\underline{\underline{U}} = \begin{pmatrix} 1\\ 2\\ 8 \end{pmatrix} \bullet \underline{\underline{V}} =$	$\begin{pmatrix} 0 \\ S \\ q \end{pmatrix}$ • $\underline{W} \in \begin{pmatrix} -2 \\ i \\ 2 \end{pmatrix}$
i	ANT THERE SOLUPE TOPIC PRODUCT MUST BY ZAND $ \Rightarrow \begin{vmatrix} 1 & 2 & 8 \\ 10 & 5 & 4 \\ -2 & 1 & 2 \end{vmatrix} = 0$
	$G = \begin{bmatrix} 2 & 0 \\ 1 & 2 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ -2 & 2 \\ 2 & 2 \end{bmatrix} = \begin{bmatrix} 0 & 2 \\ -2 & 2 \\ 2 & 2 \end{bmatrix} \iff$
	$ \begin{array}{c} \Rightarrow & v - a + 2(2v + 2a) + 8(v + v) = 0 \\ \Rightarrow & v - a - 4v - 4a + 6v = 0 \\ \Rightarrow & 30 = 5a \\ \Rightarrow & a = 26 \end{array} $
Finatuy we thave	
$\overline{\sigma} = \Im \overline{x} + h \overline{x}$	$\implies \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix} = 3 \begin{pmatrix} 10 \\ 2z \\ 2z \end{pmatrix} + \mu \begin{pmatrix} -2 \\ 2z \\ 2z \end{pmatrix}$ $\begin{pmatrix} 2 + 2i \\ 2z \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ $
	$(\theta = 36\lambda + 2\mu)$ $q = 36\lambda$ $\lambda = \frac{1}{2}$ there = soft + p
	4= 4 (chear du 3 tuore")
	$\frac{\omega}{\omega} = \frac{1}{4}\frac{\omega}{1} + \frac{3}{4}\frac{\omega}{2}$

Question 57 (***)

The 3×3 matrices **A** and **B**, are given in terms of the constants k and h below.

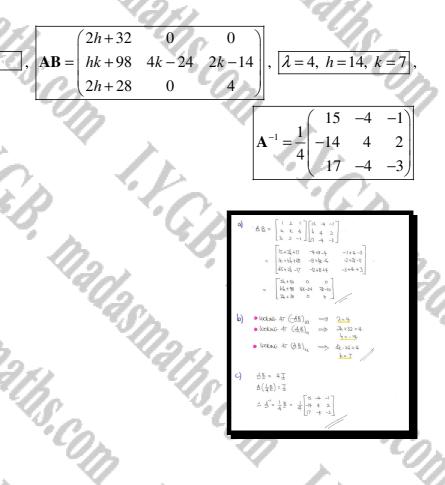
$$\mathbf{A} = \begin{pmatrix} 1 & 2 & 1 \\ 2 & k & 4 \\ 3 & 2 & -1 \end{pmatrix} \quad \text{and} \quad \mathbf{B} = \begin{pmatrix} 15 & -4 & -1 \\ h & 4 & 2 \\ 17 & -4 & -3 \end{pmatrix}.$$

a) Find the matrix composition AB, in terms of k and h.

It is further given that $AB = \lambda I$ for some values of k and h.

b) Find the value of each of the constants λ , k and h.

c) Deduce \mathbf{A}^{-1} , for the values of λ , k and h, found in part (b).



(***) Question 58

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 $\begin{pmatrix} 7 & 6 \\ 6 & 2 \end{pmatrix}$ is given. The 2×2 matrix $\mathbf{A} =$

Use the Caley- Hamilton theorem to show that

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 $\mathbf{A}^4 = \lambda \mathbf{A} + \mu \mathbf{I} \,,$

where **I** is 2×2 identity matrix.



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 $\mathbf{A}^4 = 1125\mathbf{A} + 2266\mathbf{I}$

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Question 59 (***+)

A system of equation is given in matrix form below

$$\begin{pmatrix} t & 2 & 3 \\ 2 & 3 & -t \\ 3 & 5 & t+1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$

a+b=c

where t is an integer constant, and a, b and c are real constants.

The system of equations does not have a unique solution, but it is consistent.

Show clearly that

and a control of another that the control support of
$\begin{array}{c} \text{miniple sources} \\ \left \begin{array}{c} 2 & 3 \\ 2 & 3 \\ 3 & 5 \\ \end{array} \right _{2} \left \begin{array}{c} 2 & 4 \\ -1 \\ 3 \\ \end{array} \right _{2} \left \begin{array}{c} 1 \\ 5 \\ -1 \\ 5 \\ \end{array} \right _{2} \left \begin{array}{c} 1 \\ 5 \\ -1 \\ \end{array} \right _{2} \left \begin{array}{c} 1 \\ 5 \\ -1 \\ \end{array} \right _{2} \left \begin{array}{c} 1 \\ 5 \\ -1 \\ \end{array} \right _{2} \left \begin{array}{c} 1 \\ 5 \\ -1 \\ \end{array} \right _{2} \left \begin{array}{c} 1 \\ 5 \\ -1 \\ \end{array} \right _{2} \left \begin{array}{c} 1 \\ -1 \\ -1 \\ \end{array} \right _{2} \left \begin{array}{c} 1 \\ -1 \\ -1 \\ -1 \\ \end{array} \right _{2} \left \begin{array}{c} 1 \\ -1 \\ -1 \\ -1 \\ \end{array} \right _{2} \left \begin{array}{c} 1 \\ -1 \\ -1 \\ -1 \\ \end{array} \right _{2} \left \begin{array}{c} 1 \\ -1 \\ -1 \\ -1 \\ -1 \\ \end{array} \right _{2} \left \begin{array}{c} 1 \\ -1 \\ -1 \\ -1 \\ -1 \\ \end{array} \right _{2} \left \begin{array}{c} 1 \\ -1 \\ -1 \\ -1 \\ -1 \\ \end{array} \right _{2} \left \begin{array}{c} 1 \\ -1 \\ -1 \\ -1 \\ -1 \\ -1 \\ \end{array} \right _{2} \left \begin{array}{c} 1 \\ -1 \\ -1 \\ -1 \\ -1 \\ -1 \\ -1 \\ -1 \\$
= t(8+3)-2(8+2)+3 = 8t-3t-10t-4+3 = 8t-3t-10t-4
Saw for 260 (8t+1)(t-1)=0
t. <' tez
NOW ROW REDUCING.
$ \begin{pmatrix} 7 & 7 & 7 & 7 \\ 7 & 7 & -1 & P \\ 1 & 7 & 7 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ L^{(2)} \\ L^{(2)} \\ L^{(2)} \end{pmatrix} \begin{pmatrix} 0 & -1 & -1 \\ 0 & -1 & -2\theta \\ 1 & 5 & 7 & \theta \end{pmatrix} $
$\begin{array}{l} \Pr \in \mathcal{E}(\mathbf{e}_{2} \ \mathbb{E}(\mathbf{e}_{2}) \ \mathbb{E}(\mathbf{e}_{2}$

proof

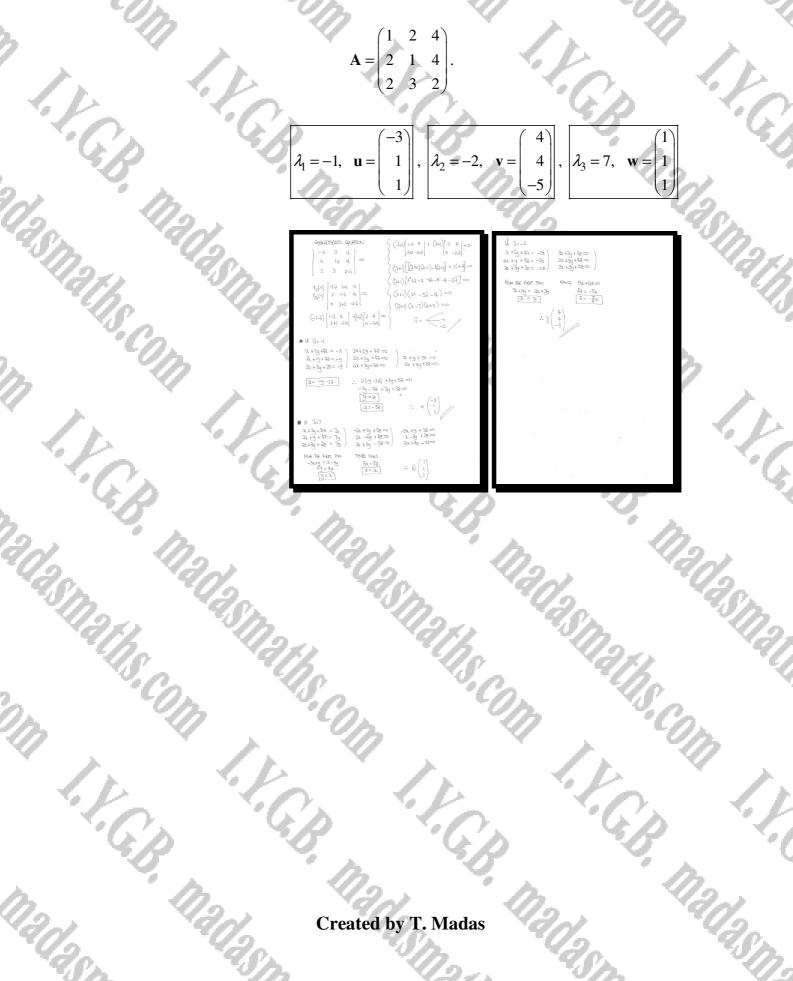
Question 60 (***+)

Express the following 3×3 determinant as the product of three linear factors.



Question 61 (***+)

Find the eigenvalues and the corresponding eigenvectors of the following 3×3 matrix.



Question 62 (***+)

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The 3×3 matrix **A** is defined in terms of a scalar constant k as

$$\mathbf{A} = \begin{pmatrix} 2 & -1 & 1 \\ 0 & 3 & 1 \\ 1 & 1 & k \end{pmatrix}$$

a) Find \mathbf{A}^{-1} , in terms of k.

b) Hence solve the following simultaneous equations

$$2x-y + z = 1$$

$$3y + z = 2$$

$$x + y + 2z = 2$$

$$\mathbf{A}^{-1} = \frac{1}{6(k-1)} \begin{pmatrix} 3k-1 & k+1 & -4\\ 1 & 2k-1 & -2\\ -3 & -3 & 6 \end{pmatrix},$$

$$x = \frac{1}{2}, y = \frac{1}{2}, z = \frac{1}{2}$$

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$\begin{cases} (b) & 2a - y + 2 = 1 \\ & 3y + 2 = 2 \\ & 1 + y + 22 = 2 \end{cases} \Rightarrow \begin{pmatrix} z & -1 & 1 \\ 0 & 3 & 1 \\ 1 & 1 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} e \begin{pmatrix} 1 \\ z \\ z \end{pmatrix}$
It A == b [where k=2] A'A = A'b
$\sum_{i=1}^{n} = \frac{1}{6} \begin{pmatrix} 5 & 3 & -4 \\ 1 & 3 & -2 \\ -3 & -3 & \zeta \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix}$
$\begin{cases} \underline{3}_{i} = \frac{1}{6} \begin{pmatrix} s + c - s \\ 1 + c - s \\ -3 - c + \pi L \end{pmatrix} \end{cases}$
(-3-C+n/
$\left\langle \begin{array}{c} \underline{\Sigma} = \frac{1}{6} \begin{pmatrix} 3\\ 3\\ 3 \end{pmatrix} \right\rangle$
$\vec{z} = \begin{pmatrix} \vec{r} \\ \vec{r} \end{pmatrix}$
) (1)
) .: a=y=2= 1

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Question 63 (***+)

The 3×3 matrix **A** is defined in terms of a scalar constant k by

$$\mathbf{A} = \begin{pmatrix} 1 & -2 & 2 \\ k & 1 & k - 1 \\ 2 & 2k - 1 & 2 - k \end{pmatrix}$$

a) Show that det **A** is independent of k.

b) Determine, with full justification, whether the vectors

$$\mathbf{i} + 2\mathbf{j} + 2\mathbf{k}$$
, $-2\mathbf{i} + \mathbf{j} + 3\mathbf{k}$ and $2\mathbf{i} + \mathbf{j}$

are linearly dependent or linearly independent.

The equations of three planes are given below.

x-2y+2z=2-2x+y-5z=32x-3y+4z=6

c) Determine, with full justification, the geometrical configuration of these three planes.

linearly independent, all 3 planes meet at a single point

= C₃₂(1) = $\begin{vmatrix} k & k+l \\ k+l & k+2 \end{vmatrix} = - \left[k(k+2) - (k+l)^2 \right]$ $-\left[k^2 + 2k - k^{\alpha} - 2k - 1 \right] = 1 \quad \text{which IND (PALLOG) or } k$ THE VEGO2S $\begin{pmatrix} 1\\ 2\\ 2\\ 1\\ 1 \end{pmatrix} \begin{pmatrix} -2\\ 1\\ 1\\ 1 \end{pmatrix} \begin{pmatrix} 2\\ 1\\ 1\\ 1 \end{pmatrix}$ THE COWMINS OF A, t D $|A| \neq 0$

Question 64 (***+)

By using elementary row and column operations, or otherwise, factorize the following determinant completely.



(***+) Question 65

The 3×3 matrices **A** and **AB** are given below.

- 9` -8 11 2 1 8 10 -7 1 2 1 and AB = 15) 2 -13 1 4 18
- a) Find the inverse of AB.
- anasmarns, **b**) Hence determine the inverse of **B**.

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2 -6 3 -1 1 $(\mathbf{AB})^{-1} =$ \mathbf{B}^{-1} 3 -3 0 4 -1-1 3 3 1 -1 -4 6) (AB) = B++-1 (AB)A = BAAA

 $\therefore (AB)^{l} = \begin{pmatrix} -6 \\ -l \\ -c \end{pmatrix}$

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Question 66 (***+)

The 3×3 matrix **A** is defined by

$$\mathbf{A} = \begin{pmatrix} 0 & 0 & -1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix}.$$

a) Describe geometrically the transformation given by A.

The 3×3 matrix **B** represents a rotation of 180° about the line x = z, y = 0.

b) Determine the elements of **B**.

The 3×3 matrix C is represents the transformation defined by **B**, followed by the transformation defined by **A**.

c) Describe geometrically the transformation represented by C.

, **A**: rotation about y axis, 90° clockwise, **B** =

C) O FINE 0 1 0 NG AT THE -AXES, TROM 0 0 |-0 - 0 0 | 0 0 det<u>a</u> = 1 (No ZERECTIO) a INJOUN • det C = +1 (io representation) POSTING & AND IS "DAT OF THE PAPER" $\underline{\vec{1}} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \longmapsto \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \underline{k}$ $\underline{i} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \longrightarrow \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix} = -\underline{i}$ $\underline{\hat{i}} = \begin{pmatrix} i \\ 0 \\ 0 \end{pmatrix} \longmapsto \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \underline{k}$ $\vec{\gamma} = \begin{pmatrix} 0 \\ i \\ 0 \end{pmatrix} \iff \begin{pmatrix} 0 \\ i \\ 0 \end{pmatrix} = \vec{\gamma}$ $\overrightarrow{\gamma} = \begin{pmatrix} 0 \\ i \\ 0 \\ 0 \end{pmatrix} \longleftrightarrow \begin{pmatrix} 0 \\ -i \\ 0 \\ 0 \end{pmatrix} = \overrightarrow{\gamma}$ $\eta = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \longmapsto \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} * -\eta$ $\mathbf{k} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \longmapsto \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix} = -\mathbf{i}$ $\underline{k} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \longmapsto \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \underline{k}$ $\vec{F} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \longrightarrow \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \end{pmatrix} = \vec{1}$ VOILING AT THE AXES LOCKING AT A SET OF AXES FROM THE POSITIVE Z AXIS, STROND ROTATION ABOUT ROTATION BY 90° CLOCKWISE

 $\begin{bmatrix} 0 & 0 \end{bmatrix}$

1 0

C: rotation about z axis, 180°

0 -1

1)

0

0

Question 67 (***+)

The 3×3 matrix **A** is given below.

$$\mathbf{A} = \begin{pmatrix} 1 & 1 & 0 \\ 3 & -3 & 1 \\ 0 & 3 & 2 \end{pmatrix}.$$

a) Show that

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$$13\mathbf{A} - \mathbf{A}^3 = 15\mathbf{I} \ .$$

b) Hence find an expression for A^{-1} in terms of other matrices.

c) Use this expression to find A^{-1} .

$$\mathbf{A}^{-1} = \frac{1}{15} (13\mathbf{I} - \mathbf{A}^2), \quad \mathbf{A}^{-1} = \frac{1}{15} \begin{pmatrix} 9 & 2 & -1 \\ 6 & -2 & 1 \\ -9 & 3 & 6 \end{pmatrix}$$

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Question 68 (***+)

The 3×3 matrix **A** is given below.

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$$\mathbf{A} = \begin{pmatrix} 1 & 0 & 4 \\ 0 & 5 & 4 \\ 4 & 4 & 3 \end{pmatrix}.$$

a) Verify that $\begin{vmatrix} 2 \end{vmatrix}$ is an eigenvector of A and state the corresponding eigenvalue.

b) Show that -3 is an eigenvalue of **A** and find the corresponding eigenvector.

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c)	Given further that -2	is another eigenvector of A	, find 3×3 matrices P

and **D** such that

$\mathbf{D} = \mathbf{P}^{\mathrm{T}} \mathbf{A} \mathbf{P}$.

$$\boxed{\lambda = 9}, \begin{bmatrix} 2\\1\\-2 \end{bmatrix}, \begin{bmatrix} 9 & 0 & 0\\0 & -3 & 0\\0 & 0 & 3 \end{bmatrix}, \begin{bmatrix} -1\\2\\2\\-2 & 1 & -2\\2\\-2 & 1 \end{bmatrix}$$

(a) $\begin{pmatrix} \varphi \\ \varphi $	$ \begin{array}{c} \textbf{C} \textbf{)} \begin{pmatrix} 1 & \mathbf{o} & \mathbf{i} \\ 0 & \mathbf{C} & \mathbf{i} \\ 0 & \mathbf{C} & \mathbf{i} \\ 4 & \mathbf{i} & \mathbf{C} \end{pmatrix} \begin{pmatrix} 2 \\ -2 \\ -2 \\ 1 \end{pmatrix} = \begin{pmatrix} C \\ -2 \\ -3 \end{pmatrix} = \begin{pmatrix} 2 \\ -2 \\ -1 \end{pmatrix} $
$ \begin{array}{c} \textbf{(b)} \\ & \begin{vmatrix} 1+3 & 0 & 4 \\ 0 & 5+3 & 4 \\ 4 & 4 & 5+5 \end{vmatrix} = \begin{vmatrix} 4 & 0 & 4 \\ 0 & 8 & 4 \\ 4 & 4 & 6 \end{vmatrix} $	$\begin{pmatrix} 1\\ 1\\ 1\\ 2\\ 1\\ 2\\ 3\\ 3\\ 3\\ 3\\ 3\\ 3\\ 3\\ 3\\ 3\\ 3\\ 3\\ 3\\ 3\\$
$ c_{(k-1)} \begin{pmatrix} 4 & 0 & 0 \\ 0 & 8 & 4 \\ 4 & 4 & 2 \end{pmatrix} = 4 \begin{vmatrix} 8 & 4 \\ 4 & 2 \end{vmatrix} $ $ = 4 \left((6-4) \right) = 0$ $ = 6 = 6 = 0 $	$D = \begin{pmatrix} \frac{1}{2} & \frac{5}{2} & \frac{3}{2} \\ \frac{1}{2} & \frac{1}{2} & -\frac{5}{2} \\ \frac{1}{2} & -\frac{5}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{5}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{5}{2} & \frac{1}{2} \\ \frac{2}{2} & \frac{2}{2} & \frac{2}{2} \\ \frac{2}{2} & \frac{2}{2} & \frac{2}$
2x + 42 = - 3x 42=-42 Sy+42=-3y 14 42=-8y 4x+44+32=-32	
$\begin{array}{c} \overline{u}_{\underline{k}\underline{l}} & \underline{\lambda} = -\underline{z} \\ \underline{y} = -\underline{k} \\ \underline{z} \\ \underline{z} \end{array} \begin{pmatrix} -\underline{z} \\ -\underline{k} \\ \underline{z} \\ \underline{z} \end{pmatrix} \sim \begin{pmatrix} 2 \\ 1 \\ -\underline{z} \\ 2 \end{pmatrix}$	

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Question 69 (***+)

A system of equations is given below in terms of the scalar parameters t and s.

$$2x + y + 3z = t + 1$$

$$5x - 2y + (t + 1)z = 3$$

$$tx + 2y + 4z = s$$

- a) Show that if t = -5 or t = 2, the system does not have a unique solution.
- **b**) Determine the value of s is the system is to have infinite solutions with t = 2.

(t-4)(t+7)+18 = +2+3t-10

s = 4

Question 70 (***+)

The 3×3 matrix **A** is defined in terms of a scalar constant k by

$$\mathbf{A} = \begin{pmatrix} k & 8 & 1 \\ 1 & 1 & 1 \\ 3 & 4 & 1 \end{pmatrix}.$$

The straight line L is a line of invariant points under A.

Determine, in any order, ...

a) ... the value of k.

b) ... the Cartesian equation of L, giving the answer in the form

 $\frac{x}{l} = \frac{y}{m} = \frac{z}{n},$

where l, m and n are integers to be found.

 $\frac{x}{4} = \frac{y}{-3} = \frac{z}{-4}$ =8

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Question 71 (***+)

The three planes defined by the equations

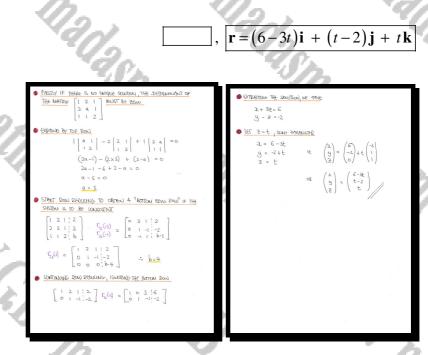
x + 2y + z = 2 2x + ay + z = 1x + y + 2z = b

where a and k are constants, intersect along a straight line L.

Determine an equation of L.

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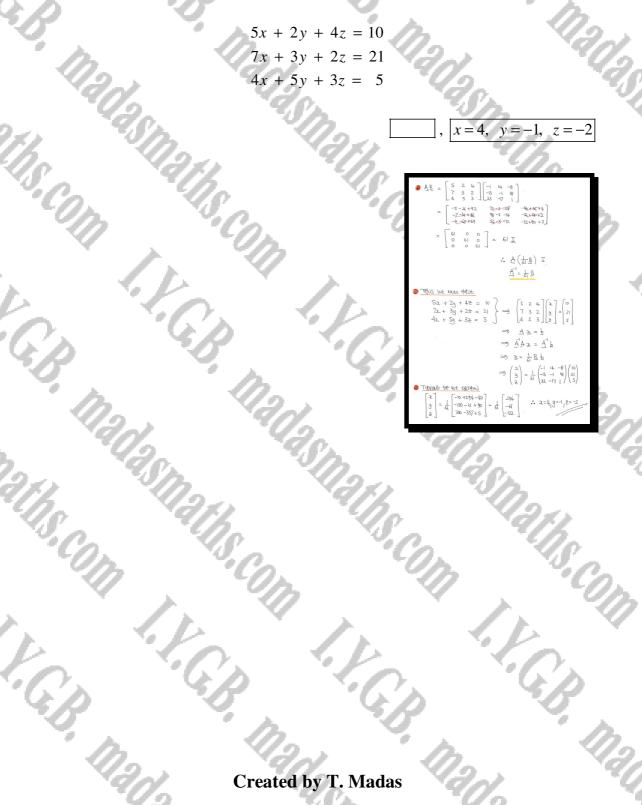
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Question 72 (***+)

The 3×3 matrices **A** and **B** are given below.

14 5 2 4` -12 -13 18 3 **B** = 7 and -1 5 3 23 4 -17

Find an expression for **AB** and use it to solve the following system of equations.



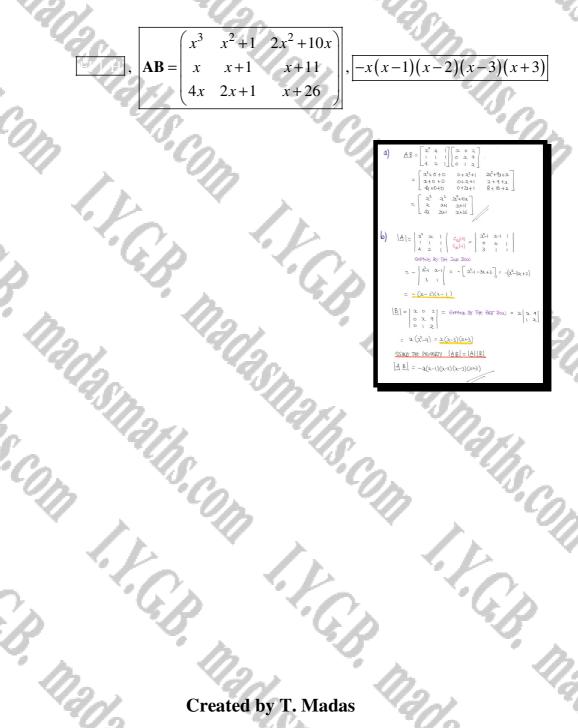
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Question 73 (***+)

The 3×3 matrices **A** and **B**, are defined in terms of the scalar constants x as follows.

$$\mathbf{A} = \begin{pmatrix} x^2 & x & 1 \\ 1 & 1 & 1 \\ 4 & 2 & 1 \end{pmatrix} \text{ and } \mathbf{B} = \begin{pmatrix} x & 0 & 2 \\ 0 & x & 9 \\ 0 & 1 & x \end{pmatrix}$$

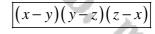
- **a**) Find an expression for AB, in terms of x
- b) By considering the properties of the determinants, or otherwise, find det(AB) in fully factorized form.



(***+) Question 74

Factorize fully the following 3×3 determinant.





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Question 75 (***+)

The 3×3 matrix **A** is given below.

$$\mathbf{A} = \begin{pmatrix} 4 & -1 & 1 \\ -1 & 6 & -1 \\ 1 & -1 & 4 \end{pmatrix}$$

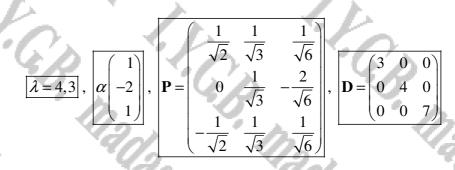
- a) Show that $\lambda = 7$ is an eigenvalue of A and find the other two eigenvalues.
- **b**) Find the eigenvector associated with the eigenvalue $\lambda = 7$.

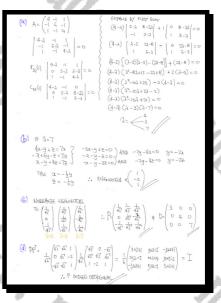
The other two eigenvectors of A are

$$\mathbf{u} = \mathbf{i} - \mathbf{k}$$
 and $\mathbf{v} = \mathbf{i} + \mathbf{j} + \mathbf{k}$

where the eigenvalue of \mathbf{v} is greater than the eigenvalue of \mathbf{u} .

- c) Find a 3×3 matrix **P** and a 3×3 diagonal matrix **D** such that $\mathbf{D} = \mathbf{P}^{\mathrm{T}} \mathbf{A} \mathbf{P}$.
- d) Show that **P** is an orthogonal matrix.





Question 76 (***+)

x + y - 2z = 2 3x - y + 6z = 26x + 5y - 9z = k

- a) Show that the system of equations does not have a unique solution.
- **b**) Show that there exists a value of k for which the system is consistent.
- c) Show, by reducing the system into row echelon form, that the consistent solution of the system can be written as

$$x = 1 - t$$
, $y = 3t + 1$, $z = t$

where t is a scalar parameter.

 $\begin{array}{c}2\\-\frac{1}{4}\\k \cdot \psi\end{array} \begin{array}{c} \widetilde{V}_{2}(-\frac{1}{4})\\ \end{array} \begin{pmatrix} 1 & 1 & -2 & 2\\ 0 & 1 & -3 & 1\\ 0 & -1 & 5 & k & 12 \\ \end{array} \begin{array}{c} \widetilde{V}_{2}(-1)\\ \end{array} \begin{array}{c} \widetilde{V}_{2}(-1)\\ \end{array}$ $\begin{smallmatrix} 0 & l & l \\ l & -3 & l \end{smallmatrix}) \quad \ \ \overset{(n-1)}{\vdash} \quad \ \ \overset{(n-1)}{\vdash} \overset{(n-1)$

k =11

Question 77 (***+)

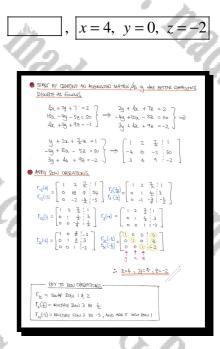
F.G.B.

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4x + 2y + 7z = 2 10x - 4y - 5z = 504x + 3y + 9z = -2

Solve the above system of simultaneous equations by manipulating their augmented matrix into reduced row echelon form.

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(***+) Question 78

T.Y.C.B. HARASHAHS CON T.Y.C.B. HARASHAHS CON Factorize fully the following 3×3 determinant. L I.Y.G.B. MARASINANSCOM I.Y.G.B. MARASINAN

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Question 79 (***+)

The 3×3 matrices **A** and **B** are given below.

$$\mathbf{A} = \begin{pmatrix} 2 & 2 & -4 \\ 0 & 6 & -2 \\ 1 & 0 & -3 \end{pmatrix} \text{ and } \mathbf{B} = \begin{pmatrix} 9 & -3 & -10 \\ 1 & 1 & -2 \\ 3 & -1 & -6 \end{pmatrix}$$

a) Find the matrix composition AB.

The point P has been transformed by A into the point Q(30,18,20).

b) Determine the coordinates of P

			- A	1 A 4 4 4 4	<u>i</u>
		8	0	0)	212
•	AB =	0	8	0	, P(2,1,-6)
12	AB =	0	0	8)	S'a
Ć	2				10
(0	$AB_{z} \begin{pmatrix} 2 & 2 \\ 0 & 6 \end{pmatrix}$	-4)(9. -2)(1	-3 -lo	$= \begin{pmatrix} 18+2-12\\ 0+2+21 \end{pmatrix} =$	-64244 -20-F-124

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(a) $AB_{2} \begin{pmatrix} 2 & 2 & -2 & -2 & -2 & -2 & -2 & -2 &$	$ \begin{array}{c} \mathcal{L} \\ \mathcal$	
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1110	$ \Rightarrow \qquad $	
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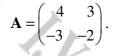
Question 80 (***+)

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I.C.B.

The 2×2 matrix A maps $\mathbb{R}^2 \mapsto \mathbb{R}^2$ and is given by



a) Determine an equation of an invariant straight line under A.

b) Find an equation of a straight line of invariant points under A.

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$ a) \begin{cases} A_{1} = \begin{bmatrix} 4 & 3 \\ -3 & -2 \end{bmatrix} & i \in \begin{pmatrix} X \\ Y \end{pmatrix} = \begin{pmatrix} 4 & 3 \\ -2 & -2 \end{pmatrix} \begin{pmatrix} 2 \\ 3 \\ -2 \end{pmatrix} \begin{pmatrix} 2 \\ 2 \\ -2 \end{pmatrix} \begin{pmatrix} 2 \\ 2$	R
LOCHING GE INDARIAS LINES LE G=MOLEC ; GOES	ONTO Y= MX+C
$\begin{pmatrix} X \\ Y \end{pmatrix} = \begin{pmatrix} 4 & 3 \\ -3 & -2 \end{pmatrix} \begin{pmatrix} \infty \\ 4x + c \end{pmatrix} = \begin{pmatrix} 4z + 5wx + 3c \\ -3z - 2wx - 2c \end{pmatrix} = \begin{pmatrix} 2z \\ -2z \end{pmatrix}$	
By $Y = y_1 X_{+C}$	
$ \begin{array}{l} \Longrightarrow & (-2u-3)x-2c \ = \ \text{Im}\left[(3u+4)x+3c\right]+c \\ \Rightarrow & (-2u-3)x-2c \ = \ (3u_1^2+4u_1)x+(3u_0+c) \end{array} $	
Thus	
$-2m-3 = 3m^2 + 4m$ $0 = 3m^2 + 6m + 3$ 8 is m-1	
	-2c = 3mc +C
$O = (m_{-1})^2$	-2c = -3c+c -2c = -2c
W= -1	S C - ARBITRARY
	utust landes
30	- JL+ C C ARBITRARY
WHERE A CALLY GET WHERE	onlo (21)
$\begin{pmatrix} 4 & 3 \\ -3 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix}$	
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	UNFOF INVARIAN POINS

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y = -x + c

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y = -

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Question 81 (***+)

N.C.

The 2×2 matrix A is defined below in terms of the scalar constants p, q and r

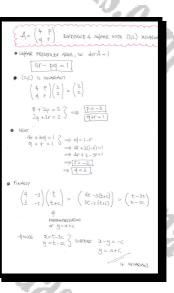
 $\mathbf{A} = \begin{pmatrix} 4 & p \\ q & r \end{pmatrix}.$

It is further given that A represents a shear under which the point (2,2) is invariant.

y = x + c,

Show that all straight lines of the form

where c is a constant, are invariant under the shear represented by A.



proof

Question 82 (***+)

The 3×3 matrix **A** is given below.

$$\mathbf{A} = \begin{pmatrix} -1 & k & 0 \\ k & 0 & 2 \\ 0 & 2 & 1 \end{pmatrix}.$$

- a) If one of the eigenvalues of A is 3, find the possible values of k.
- **b**) Determine the other two eigenvalues of **A**, given that k > 0.
- c) Find an eigenvector corresponding to the eigenvalue 3.

-1-2 2 0 2 0-2 2 0 2 1-2 -21)=0 4(1-1)=0

 $k = \pm 2$, $\lambda = 0$, $\lambda = -3$, $\mathbf{v} = \alpha (\mathbf{i} + 2\mathbf{j} + 2\mathbf{k})$

α = ½y ≆ = y Set y=2

 $\underline{V} = \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix}$

Question 83 (***+)

Consider the following matrix equation

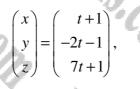
$$\begin{pmatrix} k & 1 & 0 \\ 3 & -2 & k-3 \\ 10k & 3 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} a \\ b \\ 15 \end{pmatrix}$$

where a, b and k are scalar constants.

a) Find the values of k for which the equation has a unique solution.

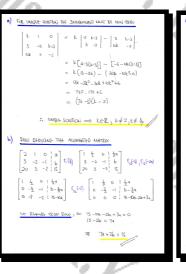
It is further asserted that k = 2.

- **b**) Express a in terms of b if the matrix equation is to be consistent.
- c) Show that if a=1 and b=4, the solution of the matrix equation is



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where t is a scalar parameter.



 $k \neq 2 \bigcup k \neq \frac{3}{7}$

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 $\begin{pmatrix} \alpha \\ \frac{y}{2} \\ \frac{z}{2} \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ t \end{pmatrix} + TE \begin{pmatrix} \frac{y}{2} \\ -1 \\ 1 \end{pmatrix}$ $\begin{pmatrix} \alpha \\ \frac{y}{2} \\ \frac{z}{2} \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} + E \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix}$ $\begin{pmatrix} \alpha \\ \frac{y}{2} \\ \frac{y}{2} \end{pmatrix} = \begin{pmatrix} 1+E \\ -1-2E \\ 1-2E \\ 1-2E \end{pmatrix}$

2a + 7b = 15

FRANK LET 11=7t.

Question 84 (***+)

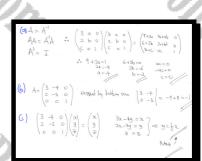
The 3×3 matrix **A** is defined as

$$\mathbf{A} = \begin{pmatrix} 3 & a & 0 \\ 2 & b & 0 \\ c & 0 & 1 \end{pmatrix}$$

where a, b and c are scalar constants.

- **a**) If $\mathbf{A} = \mathbf{A}^{-1}$, find the value of a, b and c,
- b) Evaluate the determinant of A.
- c) Determine an equation of a plane of invariant points under the transformation described by A.

a = -4, b = -3, c = 0, det A = -1, plane: x = 2y



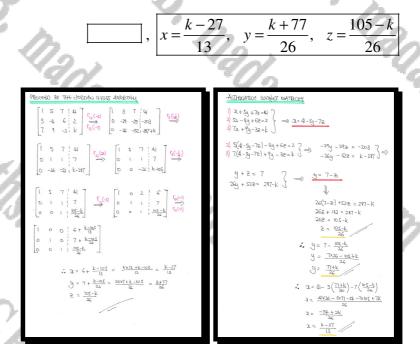
Question 85 (***+)

F.G.B.

I.C.B.

x + 5y + 7z = 41 5x - 4y + 6z = 27x + 9y - 3z = k

Find the solution of the system of simultaneous equations above, giving the answers in terms of the constant k.



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Question 86 (***+)

The matrices A and B, where k is a scalar constant, are given below.

$$\mathbf{A} = \begin{pmatrix} 1 & 2 & -1 \\ 4 & k & -2 \\ 0 & 0 & -1 \end{pmatrix} \text{ and } \mathbf{B} = \begin{pmatrix} -k & 2 & k-4 \\ 4 & -1 & -2 \\ 0 & 0 & k-8 \end{pmatrix}.$$

a) Find AB in its simplest form.

b) Hence, or otherwise, find the inverse of \mathbf{A} in terms of k, stating the condition for its existence.

and

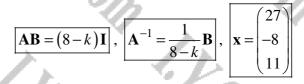
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c) Use the inverse of A to solve the equation Ax = c where

 $\begin{pmatrix} x \\ y \end{pmatrix}$

Z.

x =



Question 87 (****)

A 3×3 matrix A has characteristic equation

$$2\lambda^3 - 7\lambda^2 + \lambda + 10 = 0.$$

- a) Show that $\lambda = 2$ is an eigenvalue of A and find the other two eigenvalues.
- **b**) Show further that

$$2\mathbf{A}^4 + 71\mathbf{A}^2 = 27\mathbf{A}^3 + 100\mathbf{I} \,.$$

An eigenvector corresponding to $\lambda = 2$ is **u**.

It is further given that $\mathbf{u} = \begin{pmatrix} 2 \\ -4 \\ -5 \end{pmatrix}$, $\mathbf{v} = \begin{pmatrix} 0.4 \\ -0.8 \\ -1 \end{pmatrix}$ and $\mathbf{x} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$.

c) Evaluate each of the following expressions.

- i. Au.
- ii. A^2

d) Solve the equation Ax = v.

$$\left| \begin{array}{c} \lambda = -1, \quad \lambda = \frac{5}{2} \\ \lambda = -1, \quad \lambda = -1, \quad \lambda = \frac{5}{2} \\ \lambda = -1, \quad \lambda =$$

Question 88 (****)

x -2y + az = 5(a+1)x +3y = a 2x + y + (a-1)z = 3

- a) Determine the two values of the constant *a* for which the above system of equations does **not** have a unique solution.
- **b**) Show clearly that the system is consistent for one of these values and inconsistent for the other.

 $a = -1, \frac{5}{3}$ $(a_H)\left[-2(-a_H)-54\right]$

(****) Question 89

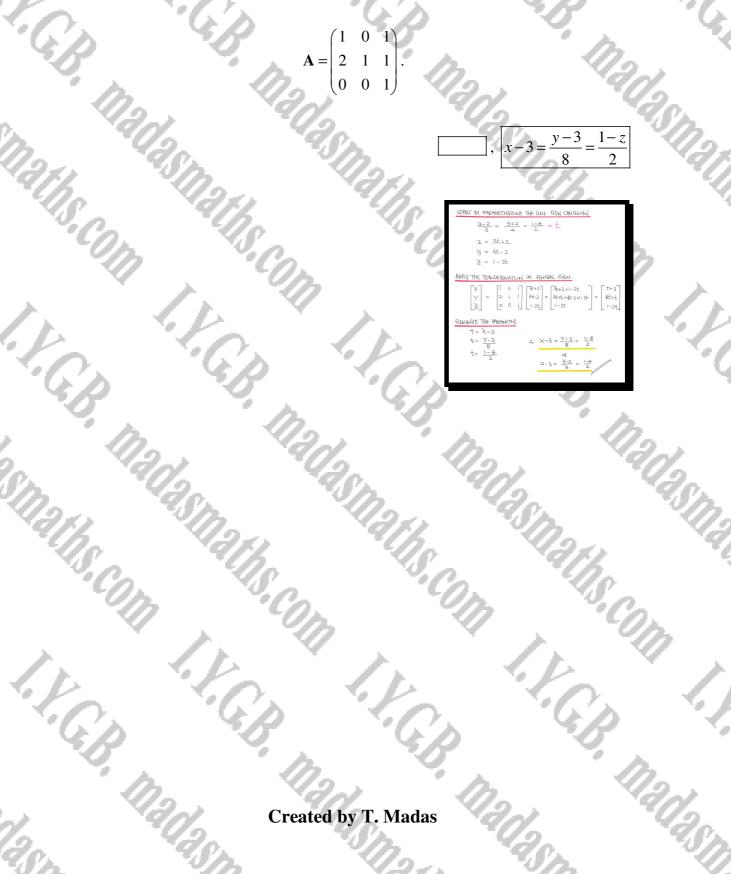
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Find in Cartesian form the image of the straight line with equation

$$\frac{x-2}{3} = \frac{y+2}{4} = \frac{1-z}{2},$$

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under the transformation represented by the 3×3 matrix A, shown below.

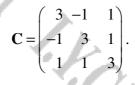


Question 90 (****)

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I.C.B.

The 3×3 matrix **C** represents a geometric transformation $T : \mathbb{R}^3 \mapsto \mathbb{R}^3$.

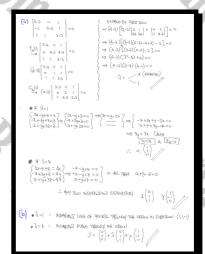


- a) Find the eigenvalues and the corresponding eigenvectors of C.
- b) Describe the geometrical significance of the eigenvectors of C in relation to T.

$$\boxed{\lambda = 1, \ \alpha \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}, \ \lambda = 4, \ \beta \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}, \ \gamma \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}}$$

 $\lambda = 1 \Leftrightarrow$ invariant line of points through the origin

 $\lambda = 4 \Leftrightarrow$ invariant plane through the origin



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M2(12)

Question 91 (****)

A 3×3 determinant, Δ , is given below.

$$\Delta = \begin{vmatrix} n(n+1) & n+1 & -1 \\ 0 & 1 & n \\ 1 & -n-1 & 1 \end{vmatrix}.$$

a) Show that

$$\Delta = \left(an^2 + bn + c\right)^2,$$

where a, b and c are constants.

b) Show further that

F.C.B.

$$\Delta = [n(n+1)]^2 + n^2 + (n+1)^2.$$

c) Hence or otherwise express 24649 as the sum of three square numbers.

 $\Delta = (n^{2} + n + 1)^{2}, \quad \boxed{24649 = 156^{2} + 13^{2} + 12^{2}}$

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Question 92 (****)

3x - y + 5z = 52x + y - 5z = 10x + y + kz = 7

where k is a constant.

a) Given that $k \neq -5$ find the unique solution of the system of equations.

b) Given instead that k = -5 show, by reducing the system into row echelon form, that the consistent solution of the system can be written as

x = 3, y = 5t + 4, z = t.

	2
$ \underbrace{ \textcircled{O}}_{1} = \begin{pmatrix} 3 & -l & s & s \\ 2 & l & -s & r_0 \\ -1 & l & k & \gamma \end{pmatrix} \xrightarrow{\bullet}_{1} \underbrace{ \overbrace{\Gamma}_{1k}}_{1k} \begin{pmatrix} 2 & l & -s & r_0 \\ 3 & -l & s & s \\ l & l & k & \gamma \end{pmatrix} \underbrace{ \overbrace{\Gamma}_{1}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ 3 \\ l \\ l \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ k \\ k \end{pmatrix}}_{1k} \underbrace{ \begin{pmatrix} l & l \\ $	$\left[\begin{array}{c} -\frac{5}{2} & 5\\ 1 & 5 & 5\\ 1 & k & 7\end{array}\right]$
$ \underbrace{ L^{(c)}_{\Gamma}(c)}_{L^{(c)}} \begin{pmatrix} 0 & \mp & Fr = \frac{\pi}{2} & \zeta \\ 0 & -\frac{\pi}{2} & \frac{\pi}{2} & -i \circ \\ 0 & -\frac{\pi}{2} & \frac{\pi}{2} & -i \circ \\ 0 & 1 & -\frac{\pi}{2} & -\frac{\pi}{2} & \zeta \\ 0 & 1 & -\frac{\pi}{2} & -\frac{\pi}{2} & \zeta \\ 0 & 1 & -\frac{\pi}{2} & -\frac{\pi}{2} & \zeta \\ 0 & 1 & -\frac{\pi}{2} & -\frac{\pi}{2} & \zeta \\ 0 & 1 & -\frac{\pi}{2} & -\frac{\pi}{2} & \zeta \\ 0 & 1 & -\frac{\pi}{2} & -\frac{\pi}{2} & \zeta \\ 0 & 1 & -\frac{\pi}{2} & -\frac{\pi}{2} & \zeta \\ 0 & 1 & -\frac{\pi}{2} & -\frac{\pi}{2} & \zeta \\ 0 & 1 & -\frac{\pi}{2} & -\frac{\pi}{2} & \zeta \\ 0 & 1 & -\frac{\pi}{2} & -\frac{\pi}{2} & \zeta \\ 0 & 1 & -\frac{\pi}{2} & -\frac{\pi}{2} & \zeta \\ 0 & 1 & -\frac{\pi}{2} & -\frac{\pi}{2} & \zeta \\ 0 & 1 & -\frac{\pi}{2} & -\frac{\pi}{2} & \zeta \\ 0 & 1 & -\frac{\pi}{2} & -\frac{\pi}{2} & -\frac{\pi}{2} & \zeta \\ 0 & 1 & -\frac{\pi}{2} & -\frac{\pi}{2} & -\frac{\pi}{2} & \zeta \\ 0 & 1 & -\frac{\pi}{2} & -\frac{\pi}{2} & -\frac{\pi}{2} & -\frac{\pi}{2} & \zeta \\ 0 & 1 & -\frac{\pi}{2} & -\frac{\pi}$	- 1
$\begin{pmatrix} l & \frac{1}{2} & -\frac{1}{2} & s \\ 0 & l & -5 & q \\ 0 & 0 & 2kH0 & 0 \end{pmatrix} \qquad \begin{array}{c} \vdots & 2=0 \\ y=4 \\ y=4 \\ \end{array} $	
$\frac{1}{2} = \frac{1}{2} + \frac{1}{2} = 2$	
$ \begin{pmatrix} \mathbf{b} \\ \mathbf{c} \\ \mathbf{c}$	
$\begin{array}{ccc} \ddots & 2z = 3 \\ & \underbrace{9}{-} & 5z = 4 \\ & \underbrace{2z}{+} & \underbrace{2z}{+} & \underbrace{3z}{+} &$	-
: 2 c3 yest +4 zet	

11+

x = 3, y = 4, z = 0

Question 93 (****)

The 3×3 matrix **A**, where *a* is a scalar constant, is given below.

$$\mathbf{A} = \begin{pmatrix} a & -1 & 1 \\ 1 & 0 & -1 \\ 3 & -2 & 1 \end{pmatrix}$$

a) Find the elements of \mathbf{A}^{-1} , in terms of *a* where appropriate.

The straight line L_1 was mapped onto another straight line L_2 by the following 3×3 matrix.

$$\begin{pmatrix} 2 & -1 & 1 \\ 1 & 0 & -1 \\ 3 & -2 & 1 \end{pmatrix}.$$

b) Given that L_2 has vector equation

vector equation
$$[\mathbf{r} - (4\mathbf{i} + \mathbf{j} + 7\mathbf{k})] \land (4\mathbf{i} + \mathbf{j} + 3\mathbf{k}) = \mathbf{0}$$

find a vector equation for L_1 .

$$\mathbf{A}^{-1} = \frac{1}{2 - 2a} \begin{pmatrix} -2 & -1 & 1 \\ -4 & a - 3 & a + 1 \\ -2 & 2a - 3 & 1 \end{pmatrix}, \quad \mathbf{r} = \mathbf{i} - 2\mathbf{j} + \lambda(3\mathbf{i} + 4\mathbf{j} + 2\mathbf{k})$$

$$\begin{split} & A \stackrel{A}{\rightarrow} = \begin{bmatrix} a & -1 & 1 \\ 1 & a & -1 \\ 1 & a & -1 \\ 0 & -1$$

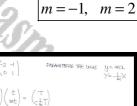
Question 94 (****)

The 2×2 matrix **D** shown below, represents a linear transformation in the x-y plane.

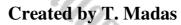
$$\mathbf{D} = \begin{pmatrix} -2 & -1 \\ 0 & 1 \end{pmatrix}$$

The straight line with equation y = mx is rotated by 90° about the origin under the transformation represented by **D**.

Determine the possible values of m.







 $\mathbf{C} = \begin{pmatrix} 2 & 1 \\ 2 & 3 \end{pmatrix}.$

Question 95 (****)

The 2×2 matrix **C** is given below.

- a) Find the eigenvalues of C and their corresponding eigenvectors.
- **b**) Find a 2×2 matrix **P** such that $P^{-1}CP$ is a diagonal 2×2 matrix and evaluate $\mathbf{P}^{-1}\mathbf{C}\mathbf{P}$ explicitly.
- c) Hence show that

12

F.C.B.

$$C^7 = \begin{pmatrix} 349526 & 349525 \\ 699050 & 699051 \end{pmatrix}$$

$$\lambda_1 = 1, \quad \mathbf{u} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \quad \lambda_2 = 1, \quad \mathbf{v} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \quad \mathbf{P} = \begin{pmatrix} 1 & 1 \\ -1 & 2 \end{pmatrix}, \quad \mathbf{D} = \begin{pmatrix} 1 & 0 \\ 0 & 4 \end{pmatrix}$$



- PCP

- 3576) ± (2 ()

Question 96 (****)

Consider the system of simultaneous equations

kx + ky - z = -1ky + 2z = 2kx + 2y + z = 1

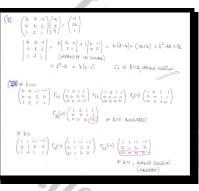
where the constant k can only take the values 0, 1 and 2.

Determine for each of the possible values of k whether the system ...

- i. ... has a unique solution
- ii. ... has no unique solution, but it is consistent.
- **iii.** ... is inconsistent.

 $a = 0 \Rightarrow$ incosistent, $a = 1 \Rightarrow$ no unique solution/consistent

 $a = 2 \Rightarrow$ unique solution



Question 97 (****)

The 2×2 matrix **A** is given below.

A straight line with equation y = mx, where *m* is a constant, remains invariant under the transformation represented by **A**.

 $\mathbf{A} = \begin{pmatrix} 7 & 6 \\ 6 & 2 \end{pmatrix}.$

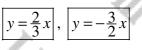
a) Show that

P.C.P.

 $7 + 6m = \lambda$ $6 + 2m = \lambda m$

where λ is a constant.

b) Hence find the two possible equations of this straight line.



29

$\begin{pmatrix} 7 & 6 \\ 6 & 2 \end{pmatrix} \begin{pmatrix} \chi \\ w \chi \end{pmatrix} = \begin{pmatrix} \times \\ w \chi \end{pmatrix} \Rightarrow$	6)	ELLINNING & BY DUSHN
$\begin{pmatrix} 7 & 6 \\ 6 & 2 \end{pmatrix} \begin{pmatrix} x \\ w_2 \end{pmatrix} = \Im \begin{pmatrix} x \\ w_3 \end{pmatrix} = 3$		$\frac{\overline{1+6m}}{6+2m} = \frac{\chi}{\chi_{m}} \Rightarrow$ $\overline{7m+6m}^{2} = 6+2m \Rightarrow$
Ta+6wa= Aa } ⇒		(3m - 2)(2m + 3) = 0 = 0
7 + Guy = A 6 + 2uy = Auy		m= <2/3
15 Equatro		* y= 3x or y=-3x

Question 98 (****)

A plane Π is defined parametrically by

 $\mathbf{r} = \mathbf{i} + \mathbf{k} + \lambda (\mathbf{i} + \mathbf{j} - 2\mathbf{k}) + \mu (\mathbf{i} - \mathbf{j} + \mathbf{k}),$

where λ and μ are a scalar parameters.

Determine a Cartesian equation for the transformation of Π under the matrix

1 1

0

 $\begin{array}{ccc} 1 & 0 \\ 1 & 0 \end{array}$

1)	2.	
$\begin{bmatrix} 1 \\ 0 \end{bmatrix}$.	72.	90
0)	405	282
	Sh	~ (D)
2.	4x+3y-	-z=6
Ch.	· · O	<u>p</u>
Nºn	$\begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} \\ \end{array} \end{array} \\ \begin{array}{c} \begin{pmatrix} X \\ \\ \end{array} \end{array} \\ \begin{array}{c} \\ \end{array} \end{array} = \begin{pmatrix} i & i & i \\ 0 & i & 0 \\ \end{array} \\ \begin{array}{c} \\ \\ \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \begin{array}{c} \\ \end{array} \\ $	
-0	$\begin{pmatrix} \mathbf{z} \\ \mathbf{y} \\ \mathbf{z} $	3
	$ \begin{pmatrix} X \\ Y \\ Z \end{pmatrix} = \begin{pmatrix} 2 + \mu \\ \lambda - \gamma \\ 2 + 3\lambda + \mu \end{pmatrix} $	
	Eliminate the mean etcles into checking $X = 24\mu$ $Y = \lambda - \mu$ $Y = X - 2$	
D_	$\begin{array}{c} \gamma = \lambda - \frac{1}{4} \\ \overline{Z} = 2 + 3\lambda + \mu \end{array} \left(\begin{array}{c} \longrightarrow \mu = X - 2 \\ substruct into the Offlet two \\ \overline{Y} = \lambda - (X - 2) \\ \overline{Z} = 2 + 3\lambda + X - 2 = 3 + X \\ \overline{Z} = 2 + 3\lambda + X - 2 = 3 + X \end{array} \right)$	
n.	Sourt THE TOP" ADUATION DE 2 2 x X+Y-2	
58	$\frac{3.46mm \sqrt{4}}{7} = 0 + 3.4(x+7-x) + x - 2}$ $\frac{2}{7} = 2 + 3.4(x+7-x) + x - 2}$ $\frac{2}{7} = 2 + 3.4(x+3) - 6 + x - 22$ $\frac{2}{7} = 4.4(x+3) - 6$	
	9x + 3y - 2 = 6	20 .
	420	""O"
3	420	"Sh
arr		

Ĉ.Ŗ.

Question 99 (****)

P.C.P.

The 3×3 matrix **C** is defined by

 $\mathbf{C} = \begin{pmatrix} 1 & 2 & 0 \\ 1 & 0 & 1 \\ 1 & 1 & 1 \end{pmatrix}.$

Find, in Cartesian form, the image of the plane with Cartesian equation

2x + y - z = 12

under the transformation defined by C

STALL BY PARAMETRIZENG THE PLANE - TAKE ANY 3 POINT ON THE PLANE SAY $A(6 0,0)$, $B(0,12,0)$ a $C(0,0,-12)$
the folde diff Acology Statistics of a cityp-izi
$ \frac{1}{AC} = \frac{1}{2} - $
HONG WE HAVE
$\begin{bmatrix} 1\\ 2\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\$
$\begin{bmatrix} a \\ g \\ z \end{bmatrix} = \begin{bmatrix} c - \lambda + \eta \\ 2\lambda \\ 2\eta \end{bmatrix}$
NOW TOANSDU THE PARAMETORIZED TUANT
$ \begin{bmatrix} X \\ Y \\ Z \end{bmatrix} = \begin{bmatrix} 1 & 2 & 0 \\ 1 & 0 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} c - \lambda + \mu \\ 2\lambda \\ -\lambda \\ 2 \end{bmatrix} = \begin{bmatrix} c - \lambda + \mu + d\lambda \\ 6 - \lambda + \mu + 2\mu \\ c - \lambda +$
X = 6+3λ+µ ≕> <u>Y = X - 6-52</u> X = 6-2λ+3µ Z - 6+h+3µ
SUBSTITUTING WHO THE CITER TWO EQUATIONS
THUS $Y = 6 - \lambda + 3(x - 6 - 3\lambda)$ $Z < 6 + \lambda + 3(x - 6 - 3\lambda)$

Y= 6-2 + 3X-118 - 92 } →
Y = 3x -12 -10A } 2 = 3x -12 -8A } ⇒
10) = 3x-y-12 7 == βλ = 3x-Z-2 1
40λ = 12x-4Y-48 Z ⇒ 4Qλ = 15x-5Z-60 J ⇒
12X - 47 - 48 = 15X - 5Z - 60 -3x - 47 + 5Z = -12
$\frac{3x + 4y + 52}{3x + 4y + 52} = 12$

, 3x + 4y - 5z = 12

i.G.B.

Question 100 (****)

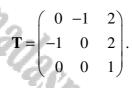
A linear transformation T, acting in the x-y plane, consists of ...

... a reflection about the line y = -x,

followed by

• ... a translation such that $(x, y) \mapsto (x+2, y+2)$.

a) Show that the matrix that represents T is given by the matrix



b) Determine the invariant line under T.

<u></u>	1
a) THE Two WATRICES REQUIRE ARE	
$\underline{A} = \begin{pmatrix} \overline{0} & -1 & 0 \\ -1 & 0 & 0 \\ \hline 0 & 0 & 1 \end{pmatrix} \qquad \underline{A} = \begin{pmatrix} 1 & 0 & 2 \\ 0 & 0 & 2 \\ \hline 0 & 0 & 1 \end{pmatrix}$	
$\underline{B} \underbrace{A} = \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 + 0 + 0 & -1 + 0 + 1 \\ 0 - 1 + 0 & 0 + 0 + 1 \\ 0 + 0 + 0 & 0 + 0 + 0 \\ 0 + 0 + 0 & 0 + 0 + 0 \\ 0 + 0 + 0 & 0 \\ 0 + 0 + 0 & 0 \\ 0 + 0 + 0 & 0 \\ 0 + 0 + 0 & 0 \\ 0 + 0 + 0 & 0 \\ 0 + 0 + 0 & 0 \\ 0 + 0 + 0 & 0 \\ 0 + 0 + 0 & 0 \\ 0 + 0 + 0 & 0 \\ 0 + 0 + 0 & 0 \\ 0 + 0 + 0 & 0 \\ 0 + 0 + 0 & 0 \\ 0 + 0 & 0$	
$= \begin{pmatrix} 0 & -i & 2 \\ -i & 0 & 2 \\ 0 & 0 & i \end{pmatrix}$	-18 equireb)
b) $\begin{pmatrix} \circ & -i & 2 \\ -i & \circ & 2 \\ \circ & \circ & i \end{pmatrix} \begin{pmatrix} \underline{x} \\ \underline{y} \\ \overline{i} \end{pmatrix} \approx \begin{pmatrix} \circ & -y+2 \\ -\lambda + \circ + 2 \\ i \end{pmatrix} = \begin{pmatrix} -\frac{y+2}{2} \\ -\frac{2x+2}{2} \\ 1 \end{pmatrix}$	·
COMPARING YIELAS 32=- 32431	-y+2 =2//
$\begin{array}{c} \underline{CQ} & \cdot \\ \begin{pmatrix} 0 & -i & 2 \\ -i & 0 & 2 \\ 0 & o & i \\ \end{pmatrix} \begin{pmatrix} \infty \\ M2 + C \\ i \\ \end{pmatrix} = \begin{pmatrix} \sigma - M2 - C + 2 \\ -x + o + 2 \\ 0 + v + 1 \\ \end{pmatrix} = \begin{pmatrix} -M2 + 2 \\ -2 + i \\ 1 \\ 1 \\ \end{pmatrix}$	2-C
COMPHING Matc with -2+2 M=-1 C=2	
$V_{\text{R}}(M_{\text{C}}) = M_{\text{R}} + 2 - C$ becomes $-(-1)x + 2 - 2 = x$	
y=-3+5 x+A=5	

y + x = 2

Ĉ.B.

Question 101 (****)

The matrices **A** and **B** are defined as

$$\mathbf{A} = \begin{pmatrix} 1 & 1 \\ -1 & 1 \\ 0 & 0 \end{pmatrix} \quad \text{and} \quad \mathbf{B} = \begin{pmatrix} 1 & 0 & 1 \\ 2 & 2 & k \end{pmatrix}$$

where k is a scalar constant.

a) Without calculating AB, show that AB is singular for all values of k.

b) Show that **BA** is non singular for all values of k.

When k = -2 the matrix **BA** represents a combination of a uniform enlargement with linear scale factor \sqrt{a} and another transformation *T*.

c) Find the value of a and describe T geometrically.

, a=8, rotation about *O*, clockwise, by 45°

 $\underline{A} = \begin{pmatrix} 1 & 1 \\ -1 & 1 \\ 0 & 0 \end{pmatrix}$ ON MUCTIPULATION: AB = (* MATRIX WITH A ZENO ROW (OR COLUMN) HAS ZEND DETNRMINIANT (NOT THAT THE ODDORESE IS NOT TRUE DUE TO THE WAY MATTRICES $\underline{\underline{B}} \underline{\underline{A}} = \begin{pmatrix} 1 & 0 & 1 \\ 2 & 2 & k \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -1 & 1 \\ 1 & 1 \end{pmatrix}$ der (BA) = 840 Re AU L, 50 NON SINGOLAR IF k=- $\underline{B} \underbrace{\underline{A}}_{i} = \begin{pmatrix} 2 & 2 \\ -2 & 2 \end{pmatrix} = 2 \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} = 2 \underbrace{\underline{I}}_{i} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$ = V2 (2 0) (1/2 1/2)

?

Question 102(****)The equation of a plane Π is given by

$$\mathbf{r} = \begin{pmatrix} 1\\2\\1 \end{pmatrix} + \lambda \begin{pmatrix} 2\\1\\0 \end{pmatrix} + \mu \begin{pmatrix} 1\\0\\2 \end{pmatrix}$$

where λ and μ are parameters.

The plane Π is transformed to the plane Π' by the matrix

 $\mathbf{A} = \begin{pmatrix} 1 & 0 & 2 \\ 1 & 1 & 0 \\ 1 & 2 & 1 \end{pmatrix}.$

Find a Cartesian equation of Π' .

WRITH THE FLADE IN FARMLETRIC CUMMUT FORM
$\int = \begin{pmatrix} \chi \\ \mu \\ z \end{pmatrix} = \begin{pmatrix} 1+2\lambda+\mu \\ 2+\lambda \\ \mu \geq \mu \end{pmatrix}$
TRADISFORM THE VECTOR UNA THE MATRIX A
$ \begin{pmatrix} X \\ y \\ Z \end{pmatrix} = \begin{pmatrix} 1 & 0 & 2 \\ 1 & 1 & 0 \\ 1 & 2 & 1 \end{pmatrix} \begin{pmatrix} 1+2j+\mu \\ 2kj \\ 1k \\ 0 \end{pmatrix} = \begin{pmatrix} 1+2j+\mu+2+4\mu \\ 1+2j+\mu+2+2j \\ 1+2k+\mu+2k+1+2\mu \end{pmatrix} $
$ \begin{pmatrix} \times \\ \neg \\ c + 4\lambda + \neg \mu \end{pmatrix} = \begin{pmatrix} \times \\ - \\ \gamma \\ c + 4\lambda + \neg \\ - \\ \gamma \\ \neg \\ \neg$
ELIMINATE THE PARAMETERS & g p - Use I : p = X-3-32 -AND
SUBSTITUTE INTO THE OHRE TWO
$ \left\{ \begin{array}{c} X = 3 + 2\lambda + 5(Y - 3 - 3\lambda) \\ Z = 6 + 4\lambda + 3(Y - 3 - 3\lambda) \end{array} \right\} \xrightarrow{(X = 3 + 2\lambda + 5Y - 15 - 15\lambda)} Z = 6 + 4\lambda + 3Y - 9 - 9\lambda $
$= \int_{Z} \sum_{z=-3}^{Z} \frac{1}{z} + \frac{1}{z} \sum_{z=-3}^{Z} 1$
=> { UZ = -60 -627 + 25 Y } => { UZ = -60 -627 + 25 Y }
100005 THE BRUATIONS 5X-137-5-21-144
$\therefore \ \underline{\nabla}X + 14\gamma - 13\Xi = -21$
12 5x+144-132+21-0

5x+14y-13z+21=0

Question 103 (****)

The Cartesian equation of a plane Π is given by

x + 2y + z = 2.

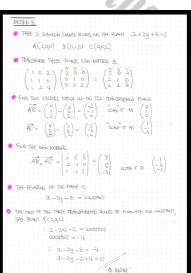
The plane Π is transformed to the plane Π' by the matrix

 $\mathbf{A} = \begin{pmatrix} 1 & 0 & 2 \\ 1 & 1 & 0 \\ 1 & 2 & 4 \end{pmatrix}.$

Find a Cartesian equation of Π' .

I.C.B.

 $\underline{A} = \begin{bmatrix} 1 & 0 & 2 \\ 1 & 1 & 0 \\ 1 & 2 & 4 \end{bmatrix}$ 17: x+2y+2=2 AMETROFFE THE PLANE 21=2-24-2 KT y=A Z=H HENCE $\overline{L} = \begin{pmatrix} S \\ \eta \\ z \end{pmatrix} = \begin{pmatrix} \gamma \\ z - z \gamma - h \end{pmatrix}$ $\begin{pmatrix} l & 0 & 2 \\ l & l & 0 \\ l & 2 & f \end{pmatrix} \begin{pmatrix} 2 - 1 \\ \lambda \\ \gamma \end{pmatrix}$ $\begin{pmatrix} 2\\2\\2 \end{pmatrix} + \lambda \begin{pmatrix} -2\\-1\\0 \end{pmatrix} + \gamma \begin{pmatrix} 1\\-1\\3 \end{pmatrix}$ wit for p ju = X-2+22 $= \begin{cases} Y = 2 - \lambda - (X - 2 + 2\lambda) \\ Z = 2 + 3(X - 2 + 2\lambda) \end{cases}$ $= \left\{ \begin{array}{c} Y = 4 - 3\lambda - X \\ Z = -4 + 0\lambda + 3X \end{array} \right\} \times 1$



x - 2y - z + 4 = 0

E.B.

100

Question 104 (****)

A linear transformation T, acting in the x-y plane, consists of ...

... a reflection about the line y = -x,

followed by ...

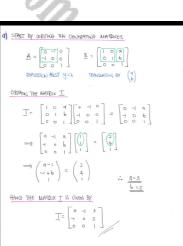
• ... a translation such that $(x, y) \mapsto (x+a, y+b)$.

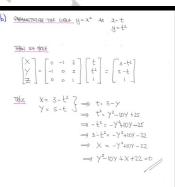
The transformation T is represented by the matrix \mathbf{T} .

- **a**) Given the point (1,1) is mapped to (2,4), find the matrix **T**.
- **b**) Determine the equation of the image of the curve with equation $y = x^2$, under the transformation represented by **T**.

T =

0 0





 $y^2 - 10y + x + 22 = 0$

3

5

Question 105 (****)

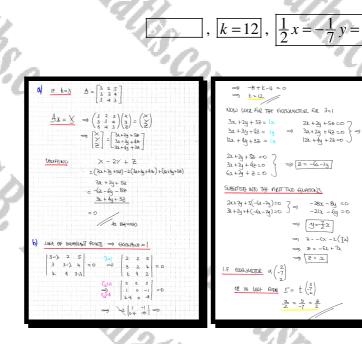
The 3×3 matrix **A**, is defined in terms of a scalar constant k, below.

$$\mathbf{A} = \begin{pmatrix} 3 & 2 & 5 \\ 3 & 3 & 4 \\ k & 4 & 3 \end{pmatrix}.$$

a) If k = 3, verify that A maps every point of the three dimensional space onto the plane with Cartesian equation

$$x - 2y + z = 0.$$

b) If $k \neq 3$, determine the value k so that the transformation represented by A has a line of invariant points, and state the Cartesian equation of this line.



Question 106 (****)

The 2×2 matrix **M** satisfies $\mathbf{M} = \mathbf{P}\mathbf{D}\mathbf{P}^{-1}$ where

$$\mathbf{P} = \begin{pmatrix} -1 & 4 \\ 3 & 1 \end{pmatrix} \quad \text{and} \quad \mathbf{D} = \begin{pmatrix} 1 & 0 \\ 0 & 27 \end{pmatrix}$$

- a) Determine the elements of M.
- b) State the eigenvalues, and the corresponding eigenvectors of M.
- c) Find an equation of the straight line of invariant points under the transformation described by M.

It is further given that

$$\mathbf{M}^{n} = \frac{1}{13} \begin{pmatrix} 4 \times 3^{3n+1} + 1 & 4 \times 3^{3n} - 4 \\ 3^{3n+1} - 3 & 3^{3n} + 12 \end{pmatrix}$$

d) Deduce that $3^{3n+2} + 4$ is divisible by 13, for all positive integers *n*.

$$\boxed{\mathbf{M} = \begin{pmatrix} 25 & 8 \\ 6 & 3 \end{pmatrix}}, \quad \boxed{\lambda_1 = 1, \quad \lambda_2 = 27, \quad \mathbf{u}_1 = 4\mathbf{i} + \mathbf{j}, \quad \mathbf{u}_2 = -\mathbf{i} + 3\mathbf{j}}, \quad \boxed{y = -3x}$$

(****) Question 107

Factorize fully the following 3×3 determinant.



Question 108 (****)

A system of equations is given below

$$3x+2y - z = 10$$

$$5x - y - 4z = 17$$

$$x+5y + pz = q$$

where p and q are constants.

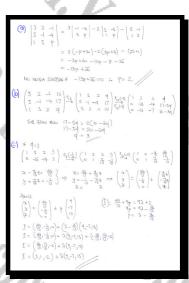
- a) Find the value of p so that the above system does not have a unique solution.
- **b**) Show that for this value of p the system is consistent if q = 3.

c) Show that the general solution of the system can be written as

$$\mathbf{r} = 2\mathbf{i} + \mathbf{j} - 2\mathbf{k} + \lambda (9\mathbf{i} - 7\mathbf{j} + 13\mathbf{k}),$$

where λ is a scalar parameter.

p = 2



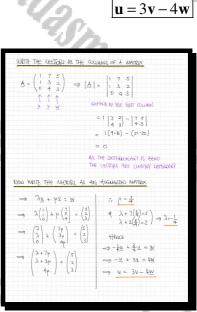
Question 109 (****)

I.C.B.

The following three vectors are given.

 $\mathbf{u} = \begin{bmatrix} 2\\-1\\1 \end{bmatrix}, \quad \mathbf{v} = \begin{bmatrix} -1\\1\\2 \end{bmatrix}, \quad \mathbf{w} = \begin{bmatrix} 1\\-1\\-1 \end{bmatrix}.$

- a) Show that **u**, **v** and **w** are linearly dependent.
- b) Find a linear relationship, with integer coefficients, between **u**, **v** and **w**.



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Question 110 (****)

The 2×2 matrix **A** is defined in terms of a constant k.

$\mathbf{A} = \begin{pmatrix} 2 & 7 \\ 4 & k \end{pmatrix}$

a) Given that $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$ is an eigenvector of **A**, find ...

i. ... the corresponding eigenvalue to the eigenvector.

- **ii.** ... the value of k
- b) Find another eigenvector and the corresponding eigenvalue of A.

It is further given that $\mathbf{A} = \mathbf{P}\mathbf{D}\mathbf{P}^{-1}$, where \mathbf{D} is a diagonal matrix and \mathbf{P} is another matrix.

- c) Write down possible forms for the matrices **D** and **P**.
- **d**) Hence show clearly that

$$\mathbf{A}^{7} = \begin{pmatrix} 1739180 & 3043789 \\ 1739308 & 3043661 \end{pmatrix}$$

$$\lambda = 9$$
, $k = 5$, $\lambda = -2, \mathbf{u} = \begin{pmatrix} 7 \\ -4 \end{pmatrix}$, $\mathbf{D} = \begin{pmatrix} 9 & 0 \\ 0 & -2 \end{pmatrix}$,

P =

 $\times \frac{1}{0} \begin{pmatrix} 4 & 7 \\ l & -l \end{pmatrix}$

(e)
$$A = \begin{pmatrix} 2 & 7 \\ 4 & k \end{pmatrix}$$
 $\begin{pmatrix} 2 & 7 \\ 4 & k \end{pmatrix}$ $\begin{pmatrix} 2 & 7 \\ 4 & k \end{pmatrix}$ $\begin{pmatrix} 1 \\ 4 & k \end{pmatrix}$ $\begin{pmatrix} 1 \\ 4 & k \end{pmatrix}$ $\begin{pmatrix} 2 & 7 \\ 4 & k \end{pmatrix}$ $\begin{pmatrix} 1 \\ 2 & 4 & k \end{pmatrix}$ $\begin{pmatrix} 2 & 7 \\ 4 & k \end{pmatrix}$ $\begin{pmatrix} 2$

Question 111 (****) The 3×3 matrix A is given below.

$$\mathbf{A} = \begin{pmatrix} 1 & -1 & 1 \\ 3 & -3 & 1 \\ 3 & -5 & 3 \end{pmatrix}.$$

a) Given that $\mathbf{u} = \begin{vmatrix} 1 \end{vmatrix}$ is an eigenvector of **A**, find the corresponding eigenvalue.

b) Given that $\lambda = -2$ is an eigenvalue of **A**, find a corresponding eigenvector **v**.

The vector \mathbf{w} is defined as $\mathbf{w} = \mathbf{u} + \mathbf{v}$.

2

c) Determine the vector $\mathbf{A}^{7}\mathbf{w}$.

[128] $\mathbf{A}^7 \mathbf{w} =$ $\lambda = 2$, 0 $\mathbf{v} =$ 1 128 {= y=2 x=0 3x-5(3x+2)+52=0 i. V. = 0) $\underline{A} \underline{w} = \underline{A} \left(\underline{u} + \underline{v} \right) = \underline{A}^{2} \underline{u} + \underline{A}^{2} \underline{v}$ $= \underline{A}^{6} \left[\underline{A} \underline{u} + \underline{A} \underline{v} \right] = \underline{A}^{4} \left[2\underline{u} - 2\underline{v} \right]$ $= \underline{A}^{5} \left[\underline{A} 2\underline{u} - \underline{A} 2\underline{v} \right] = \underline{A}^{5} \left[4\underline{u} + 4\underline{v} \right]$ $= A^{\mu} \left[\underline{A} 4\underline{u} + \underline{A} 4\underline{v} \right] = \underline{A}^{\mu} \left[8\underline{u} - 8\underline{v} \right]$ $= A \left[\underline{A} 2^{\underline{s}} \underline{\underline{u}} + \underline{A} (\underline{z}_{1}^{\underline{s}} \underline{\underline{v}}] = A \left[\underline{2^{\underline{s}}} \underline{\underline{u}} + (\underline{z}_{1}^{\underline{s}} \underline{\underline{v}}] \right]$ $= 2^{7}\underline{u} + (-z)^{7}\underline{v} - 128 \begin{pmatrix} 1\\ 1\\ 2 \end{pmatrix} - 128 \begin{pmatrix} 0\\ 1\\ 1 \end{pmatrix}$ $= \begin{pmatrix} 128\\ 128\\ 256 \end{pmatrix} \rightarrow \begin{pmatrix} 0\\ 128\\ 128\\ 128 \end{pmatrix} = \begin{pmatrix} 128\\ 0\\ 128\\ 128 \end{pmatrix}$

Question 112 (****)

R,

I.C.B.

The following four vectors are given.

$$\mathbf{u} = \begin{bmatrix} 2\\-1\\1 \end{bmatrix}, \quad \mathbf{v} = \begin{bmatrix} -1\\1\\2 \end{bmatrix}, \quad \mathbf{w} = \begin{bmatrix} 1\\-1\\-1 \end{bmatrix}, \quad \mathbf{p} = \begin{bmatrix} 1\\1\\1 \end{bmatrix}.$$

a) Show that **u**, **v** and **w** are linearly independent.

b) Express **p** in terms of **u**, **v** and **w**.

NDENCE IT SOFFICES TO WRITE THE DECEDER AS STRACTING THE SUNTAN THE DEFERMINANT IS NOT RENDO $\lambda + 2\mu = v = 1$ - 27 = 2 TRACAPADON YUSAANU JAA SOB NOU $\Rightarrow \Im \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} + \mu \begin{pmatrix} -1 \\ 2 \\ 2 \end{pmatrix} + \Im \begin{pmatrix} 1 \\ -1 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$

 $\mathbf{p} = 2\mathbf{u} - 4\mathbf{v} - 7\mathbf{w}$

X-8+7=1 2 = 2

F.C.P.

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y - 20 = 1 $-\frac{1}{2}c = \frac{7}{2}$

P = 24 - 44 - 7m

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Question 113 (****)

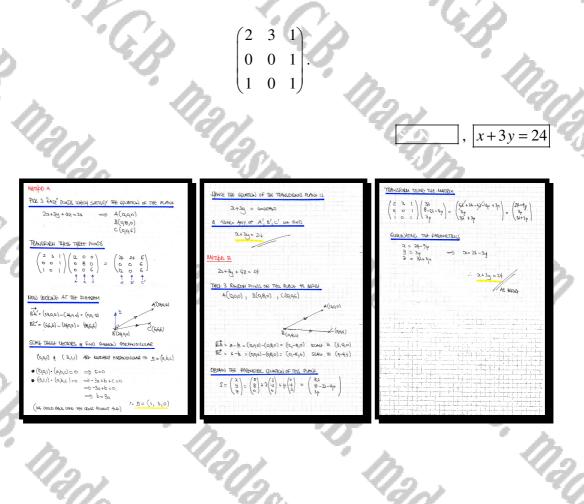
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I.V.G.p

A plane Π has Cartesian equation

2x + 3y + 4z = 24.

Determine a Cartesian equation for the transformation of Π under the matrix



Question 114 (****+)

Y.C.

A linear transformation T, acting in the x-y plane, consists of ...

... a translation such that $(x, y) \mapsto (x+2, y+4)$,

followed by ...

• ... an anticlockwise rotation about the origin by $\frac{\pi}{2}$.

Determine the coordinates of the invariant point under T

We the functions the matrix is that define the formation of the formation

(-3,-1)

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Question 115 (****+)

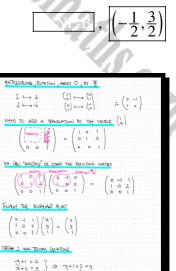
A linear transformation T, acting in the x-y plane, consists of ...

• ... an anticlockwise rotation about the origin by $\frac{\pi}{2}$

followed by ...

• ... a translation by the vector $\begin{pmatrix} 1 \\ 2 \end{pmatrix}$.

Determine the coordinates of the invariant point under T.



 $\left(-\frac{1}{2},\frac{3}{2}\right)$

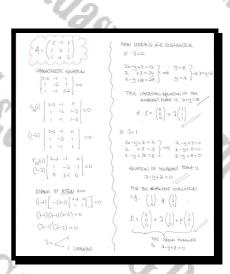
Question 116 (****+)

The 3×3 matrix **A** is given below.

$$\mathbf{A} = \begin{pmatrix} 1 & -1 & 1 \\ 3 & 0 & 1 \\ 1 & -1 & 2 \end{pmatrix}$$

Find in Cartesian and parametric form the equation of the invariant line and the equation of the invariant plane under the transformation represented by A.

 $\mathbf{r} = \lambda \mathbf{i} + \lambda \mathbf{j} + \lambda \mathbf{k}, \ x = y = z \ , \ \mathbf{r} = (\lambda + \mu)\mathbf{i} + (\lambda + 2\mu)\mathbf{j} + \mu\mathbf{k}, \ x - y + z = 0$



Question 117 (****+)

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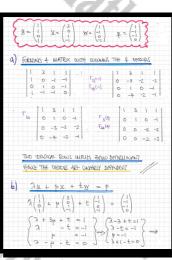
i C.B.

The following four vectors are given.

$$\mathbf{u} = \begin{bmatrix} 1\\1\\0\\1 \end{bmatrix}, \quad \mathbf{v} = \begin{bmatrix} 3\\0\\1\\-1 \end{bmatrix}, \quad \mathbf{w} = \begin{bmatrix} 1\\-1\\0\\-1 \end{bmatrix}, \quad \mathbf{p} = \begin{bmatrix} 1\\-1\\-1\\0 \end{bmatrix}.$$

a) Show that these four vectors are linearly dependent.

b) Express \mathbf{p} in terms of \mathbf{u} , \mathbf{v} and \mathbf{w} .



λ+t=4 λ-t=-1 μ=-1	h=-1 y= 2 y= 2
$P = \frac{3}{2} \begin{pmatrix} 1\\ 1\\ 0\\ 1 \end{pmatrix} = \frac{3}{2} \begin{pmatrix} 1\\ 0\\ 1 \end{pmatrix} = \frac{3}{2} \frac{1}{2} \frac$	
ACHWATWH TAKING IT FROM THE AND IGNORING THE	5 DW BENCTION OF PART (a BOTTOM ZOW
$\begin{bmatrix} 1 & 3 & 1 & 1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & -2 & -5 \end{bmatrix}$	$\Rightarrow \begin{cases} 3 + 3\mu + t = 1 \\ \mu & -1 \\ -2t & -s \end{cases}$
	$ = \begin{cases} \lambda - 3 + \frac{5}{2} \in I \\ \eta = -I \\ t = \frac{5}{2} \end{cases} $
	-)= ÷

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 $\mathbf{p} = \frac{3}{2}\mathbf{u} - \mathbf{v} + \frac{5}{2}\mathbf{w}$

Question 118 (****+)

A linear transformation T, acting in the x-y plane, consists of ...

... a translation such that $(x, y) \mapsto (x+2, y-3)$,

followed by ...

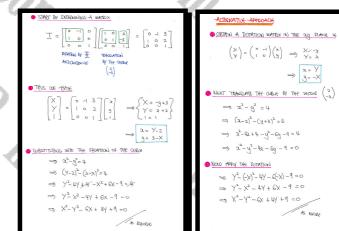
. a rotation about the origin, by $\frac{1}{2}\pi$, anticlockwise.

Show that under T, the curve with equation

is mapped onto the curve with equation

 $x^2 - y^2 - 6x + 4y + 9 = 0.$

 $x^2 - y^2 = 4$,



proof

⇒ y=-×

- 4Y + 6X - 9 = 0

Question 119 (****+)

The 2×2 matrix **C** is defined as

$$C = \begin{pmatrix} a & b+a \\ b-a & -a \end{pmatrix},$$

where a and b are constants.

START BY THE CHARL

a-> b+a =0

 $\Rightarrow (\alpha - \lambda)(-a - \lambda) - (b - a)(b + a) = 0$ $\Rightarrow - (a - \lambda)(a + \lambda) - (b^2 - a^2) = 0$ $\Rightarrow (\lambda - a)(\lambda + a) - b^2 + a^2 = 0$

22 - a2 - b2 + a2 22 = b2

, . ⇒ a= <"-b

ax + Cotaly = bas

(b-a)x - ay = by/

(a-b)x +(b+a)y =0 (b-a)z - (a+b)y=0

 $\underline{u} = \begin{pmatrix} 1 \\ \underline{b} - a \\ \underline{b} - a \end{pmatrix} = 0 \begin{pmatrix} 1 \\ \underline{b} - a \\ \underline{b} - a \end{pmatrix}$

y= b-9

12+(6+0)g=-6x

(b-a)x - ay = - by

(a+b)x + (a+b)y = a

-a)a + (b-a)y =0,

IF a=b

a) Determine the eigenvalues of C and their corresponding eigenvectors, giving the answers in terms of a and b where appropriate.

It is further given that $C = PDP^{-1}$, where D is a diagonal matrix and P is another 2×2 matrix.

b) Write down the possible form of **D** and the possible form of **P** and hence show that

 $\mathbf{C}^9 = b^8 \mathbf{C}.$

b+a

b-a

D =

b

0

0

b

or $\mathbf{u} =$

 $\lambda = -b$

P

 $\Rightarrow \subseteq^{q} = -\frac{1}{2b} \begin{bmatrix} b^{q}(b+a) & -b^{q}\\ b^{q}(b-a) & b^{q} \end{bmatrix} \begin{bmatrix} -1 & -1\\ a-b & a+b \end{bmatrix}$

 $\Rightarrow \underline{C}^{q} = -\frac{1}{2b} \times \begin{bmatrix} 0 \\ 0 \end{bmatrix} \begin{bmatrix} b+q & -1 \\ b-q & 1 \end{bmatrix} \begin{bmatrix} -1 & -1 \\ a-b & a+b \end{bmatrix}$

 $\Rightarrow \underline{C}_{a}^{d} = -\frac{1}{2} \begin{bmatrix} -p + a + a - b \\ -p + a + a - b \end{bmatrix} \begin{bmatrix} -p + a + a + b \\ -p + a + a + b \end{bmatrix}$

AS PHONIPHO

 $\Rightarrow \underline{c}^{\dagger} = -\frac{1}{2} b^{\theta} \begin{bmatrix} -2a & -2a-2b \\ 2a-2b & 2a \end{bmatrix}$

 $\Rightarrow \leq^{q} = b^{B} \begin{bmatrix} a & a+b \\ b-a & -a \end{bmatrix}$

⇒ cª = be c

 $\mathbf{v} =$

b+a

1

b-a

b + a

STARDARD DIAGONAUZATION REPORTS

 $\underline{\underline{P}}^{I} = -\frac{1}{2b} \begin{pmatrix} -1 & -1 \\ a-b & a+b \end{pmatrix}$

FINALLY WE HAVE

⇒ C = PDP

 $\Rightarrow \underline{C}^{q} = \underline{P} D^{q} \underline{P}^{-1}$

 $\underline{\underline{P}} = \begin{pmatrix} b+a & l \\ b-a & -l \end{pmatrix} \qquad \underline{\underline{D}} = \begin{pmatrix} b & 0 \\ 0 & -b \end{pmatrix}$

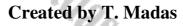
 $\underbrace{\underline{p}}_{-}^{-1} = \underbrace{\frac{1}{-b-a-b+a}}_{-b-a-b+a} \begin{pmatrix} -1 & -1 \\ a-b & b+a \end{pmatrix} = -\frac{1}{2b} \begin{pmatrix} -1 & -1 \\ a+b & a+b \end{pmatrix}$

 $\Longrightarrow \underline{\subseteq}^q = (\underline{P} \underline{P} \underline{P}^{-1})^q = (\underline{P} \underline{D} \underline{P}^{-1}) (\underline{P} \underline{D} \underline{P}^{-1}) (\underline{P} \underline{D} \underline{P}^{-1}) \dots (\underline{P} \underline{P} \underline{P}^{-1})$

 $\Rightarrow \underline{\zeta}^{q} = \begin{bmatrix} b+a & i \\ b-a & -i \end{bmatrix} \begin{bmatrix} b & 0 \\ 0 & -b \end{bmatrix}^{q} \times \frac{-i}{2b} \begin{bmatrix} -i & -i \\ a+b & a+b \end{bmatrix}$ $\Rightarrow \underline{\zeta}^{q} = -\frac{i}{2b} \begin{bmatrix} b+a & i \\ b-a & -i \end{bmatrix} \begin{bmatrix} bq & 0 \\ 0 & -b \end{bmatrix} \begin{bmatrix} -i & -i \\ -b & a+b \end{bmatrix}$

 $\Rightarrow C^q = \underline{P} \underline{D} \underline{I} \underline{D} \underline{I} \underline{D} \underline{I} \dots \underline{I} \underline{D} \underline{P}^{-1}$

 $\lambda_1 = b$, **u** =



Question 120 (****+)

A system of equation is given below

$$3x - 2y - 18z = 6$$
$$2x + y - 5z = 25$$

a) Show, by reducing the system into row echelon form, that the solution of the system can be written as

$$\mathbf{r} = 8\mathbf{i} + 9\mathbf{j} + \lambda (4\mathbf{i} - 3\mathbf{j} + \mathbf{k}),$$

where λ is a scalar parameter.

A new system is now given

3x-2y-18z = 62x + y -5z = 257x+ky + 2z = 20

where k is a constant.

b) Determine if the system has solutions for different values of k.

 $k \neq 10 \Rightarrow$ unique, otherwise incosistent

 $\begin{pmatrix} 3 & -2 & -48 & 6 \\ 2 & (& -5 & 25 \end{pmatrix} = \Gamma_1 \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} \begin{pmatrix} 1 & -\frac{3}{2} & -6 & 2 \\ 2 & (& -5 & 25 \end{pmatrix} = \Gamma_1 \frac{1}{2} \begin{pmatrix} 1 & -\frac{3}{2} & -6 \\ 0 & \frac{3}{2} & 7 \end{pmatrix}$ $\begin{array}{c} \Gamma_2 \begin{pmatrix} 3 \\ 7 \end{pmatrix} \begin{pmatrix} 1 & -\frac{2}{3} & -6 & 2 \\ 0 & 1 & 3 & 9 \end{pmatrix} \quad \Gamma_2 \begin{pmatrix} 3 \\ 3 \end{pmatrix} = \begin{pmatrix} 1 & 0 & -4 & 8 \\ 0 & 1 & 3 & 9 \end{pmatrix} \end{array}$ $\begin{array}{c} \begin{array}{c} y + 3 & g = 0 \\ y + 3 & g = 0 \end{array} \end{array} \xrightarrow{} \begin{array}{c} y = & g - 3 & f \\ y = & g - 3 & f \\ \end{array} \xrightarrow{} \begin{array}{c} \left(f - 3 & g \\ y \end{array} \right) \xrightarrow{} \left(f - 3 & g \\ g + & g \\ \end{array} \end{array}$ · <u>Γ</u> = (8,9,0) + 7(4,3,1) + 5 είφυιευ 9 = r13(-7)

Question 121 (****+)

The following vectors, given in terms of a scalar constant n, are linearly dependent.

$$\mathbf{a} = n\mathbf{i} + 2n\mathbf{j} + (n-1)\mathbf{k},$$

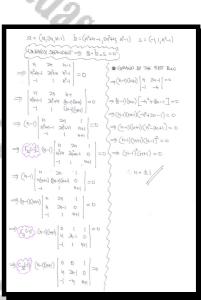
$$\mathbf{b} = (n^2 + n-1)\mathbf{i} + (2n^2 + n)\mathbf{j} + (n^2 - 1)\mathbf{k},$$

$$\mathbf{c} = -\mathbf{i} + \mathbf{j} + (n^2 - 1)\mathbf{k}.$$

Determine possible values of n.

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I.C.P.



 $n = \pm 1$

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Question 122 (****+)

A linear transformation T, acting in the x-y plane, consists of ...

... a translation such that $(x, y) \mapsto (x+h, y+k)$,

followed by

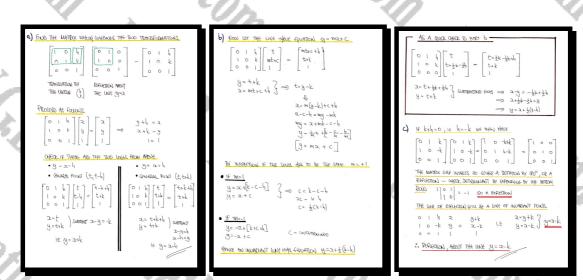
- ... a reflection about the line y = x
- a) Determine, in terms of k and h, the equations of the two straight lines which map onto each other under T.
- **b**) Find, in terms of k and h, the equation of the invariant line under T.
- c) Give a full geometrical description for T, in the case where h+k=0, by considering the single transformation that is equivalent to T applied twice in succession.

y = x - h,

y = x + k

Reflection about the line y = x.

 $y = x + \frac{1}{2}(k-h)$



Question 123 (****+) The 2×2 matrix A is defined as

 $\mathbf{A} = \begin{pmatrix} 1 & 3 \\ 2 & 2 \end{pmatrix}.$

Use linear matrix algebra techniques to show that

$${}^{n} = \frac{1}{5} \begin{pmatrix} \alpha \times 4^{n} + \beta (-1)^{n} & \beta \times 4^{n} - \beta (-1)^{n} \\ \alpha \times 4^{n} - \alpha (-1)^{n} & \beta \times 4^{n} + \alpha (-1)^{n} \end{pmatrix}$$

where α and β are positive constants.

F.C.B.

You may not use proof by induction in this question.

1 C	
• STAPE BY FINDING CLESSINGLES $ \begin{pmatrix} (-\lambda & 3 \\ 2 & 2-\lambda \end{pmatrix} = 0 \qquad \implies ((-\lambda)(2-\lambda) - 4 = 0) \\ \implies (\lambda-1)(\lambda-2) - 4 = 0 \\ \implies (\lambda-1)(\lambda-2) - 4 = 0 \\ \implies (\lambda-1)(\lambda-1) = 0 \\ \implies (\lambda-1)(\lambda-1) = 0 \\ \implies (\lambda-2)(\lambda-1) = 0 \\ \implies (\lambda-2)(\lambda-1) = 0 \\ \implies (\lambda-2)(\lambda-1) = 0 \\ \implies (\lambda-2)(\lambda-2) = 0 $	• We can now there \underline{A} to the flower of n $\rightarrow \underline{A} = \frac{1}{2} \underline{D} \underline{D}^{-1}$ $\rightarrow \underline{A}^{n} = (\underline{P} \underline{D})^{n} \underline{D} \underline{D} \underline{D} \underline{D} \underline{D}^{-1}$ $\rightarrow \underline{A}^{n} = (\underline{P} \underline{D})^{n} \underline{D} \underline{D} \underline{D} \underline{D} \underline{D} \underline{D} \underline{D} D$
$\begin{array}{c} \lambda + 3\eta = 4\alpha \\ \lambda + 2\eta = 4\eta \\ \lambda + 2\eta = 4\eta \\ \eta = -\alpha \\$	$ \overrightarrow{\mathcal{A}}_{p} = \frac{1}{\xi} \begin{pmatrix} 1 \\ -1 \\ 2 \\ -1 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0$
• Now is the definit matrices • $\sum_{i=1}^{n} = \begin{pmatrix} 1 & 3 \\ 1 & -2 \end{pmatrix}$ • $\sum_{i=1}^{n-1} = -\frac{1}{2} \begin{pmatrix} -2 & -3 \\ -1 & -1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 2 & 3 \\ 1 & -1 \end{pmatrix}$ • $\sum_{i=1}^{n} = \begin{pmatrix} 4 & 0 \\ 0 & -1 \end{pmatrix}$	
$\overbrace{\overline{b}}^{-1} \overline{\overline{b}} \stackrel{-1}{=} \overline{\overline{b}} \stackrel{-1}{=} 0 o \overline{\overline{b}} \stackrel{-1}{=} - \overline{\overline{b}} \stackrel{-1}{=} \overline{\overline{b}} \stackrel{-1}{=} - \overline{\overline{b}} \stackrel{-1}{=} \overline{\overline{b}} \stackrel{-1}{=} \overline{\overline{b}} \stackrel{-1}{=} \overline{\overline{b}} \stackrel{-1}{=}$	

 $\alpha = 2, \beta = 3$

A.C.B.

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Question 124 (****+)

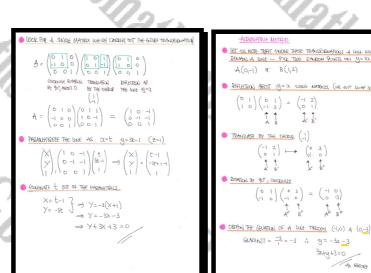
A linear transformation T, acting in the x-y plane, consists of ...

... a reflection about the line y = x,

followed by

- .. a translation such that $(x, y) \mapsto (x+1, y-1)$, followed by
- ... a clockwise rotation about the origin O by 90°.

Find, under T, the equation of the image of the straight line with equation y = 3x - 1



3x + y + 3 = 0

 $\begin{pmatrix} -l & 2 \\ 0 & l \end{pmatrix}$

y = -3x - 3

18 x q y)

Question 125 (****+)

A linear transformation T, acting in the x-y plane, consists of ...

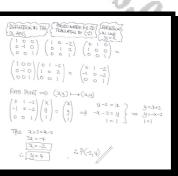
... a reflection about the line y = x,

followed by ...

- ... a translation such that (x, y) → (x-2, y+2),
 followed by ...
- ... a reflection about the line y = 0,

The point P is invariant under T.

Determine the coordinates of P.



P(-2,4)

Question 126 (****+) The 3×3 matrix **T** is given below.

$$\mathbf{T} = \begin{pmatrix} -1 & 0 & -1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{pmatrix}$$

The matrix \mathbf{T} describes a composite transformation in the *x*-*y* plane.

- a) Verify that T consists of ...
 - ... a reflection in the line y = -x,
 - followed by ...
 - ... a translation by the vector $2\mathbf{i} \mathbf{j}$,

followed by ...

• ... a clockwise rotation by $\frac{1}{2}\pi$, about the origin *O*.

b) Determine the inverse of the matrix **T**.

The straight line with equation 2x + y + 1 = 0 is transformed by **T**.

c) Find a Cartesian equation of the image of the line after the transformation.

$$\mathbf{T}^{-1} = \begin{pmatrix} -1 & 0 & -1 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{pmatrix}, \ \underline{y = 2x - 1}$$

(a)
$$T = \begin{pmatrix} 0 & 1 & | & 0 \\ -1 & 0 & 0 \\ 0 & 0 & | & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & | & 1 \\ 0 & 0 & | & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & | & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & | & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & | & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & | & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 & 0 \\ 0 & 0 & | & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 & 0 \\ 0 & 0 & | & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 & 0 \\ 0 & 0 & | & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 & 0 \\ 0 & 0 & | & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 & 0 \\ 0 & 0 & | & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 & 0 \\ 0 & 0 & | & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 & -1 \\ 0 & 0 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 & -1 \\ 0 & 0 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 & -1 \\ 0 & 0 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 & -1 \\ 0 & 0 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 & -1 \\ 0 & 0 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 & -1 \\ 0 & 0 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & -1 \end{pmatrix} \end{pmatrix}$$

Question 127 (****+)

A linear transformation T, acting in the x-y plane, consists of ...

... an anticlockwise rotation about the origin O by a non zero angle θ ,

... followed by ...

• ... a translation such that $(x, y) \mapsto (x+h, y+k)$

Under this transformation $(0,1) \mapsto (1,2)$ and $(3,0) \mapsto (4,3)$.

Find the value of each of the constants θ , k and h.

START BY WRITING THE GRACHATING MATRICES_
$ \begin{pmatrix} l \\ \theta \\ \eta \\ \theta \\ \eta \\ \theta \\ \eta \\ \theta \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0$
TBASLATION BY THE ANTONOQUUE PETHON USBDP (6) BY (0, 19607 O
21010F- 000T ¥HT OT (ADITAMAGAZAART CALABUO) ¥HT KRAA ●
$ \begin{pmatrix} 4 \\ -3m\theta \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ $
$ \begin{pmatrix} b_{1} - \varepsilon \eta \theta_{2} & 3 \cos \theta + b_{1} \\ \cos \theta_{2} + k_{1} & k_{2} - 3 \cos \theta_{2} \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 4_{1} \\ 2_{1} & 3_{2} \\ 0 & 1 \end{pmatrix} $
SOLUTION THE GOURTHON BY MUY SOLUTION OF THE
$ \begin{array}{c} (\mathfrak{A}_{n}); \hspace{0.1cm} h_{-} \hspace{0.1cm} \mathfrak{Sm}\theta = 1 \\ (\mathfrak{A}_{n}); \hspace{0.1cm} \mathfrak{Sm}\mathfrak{Sh} + h = \Psi \end{array} \end{array} \xrightarrow{\hspace{0.1cm}} \mathfrak{Sh}_{n} - 3\mathfrak{sm}\theta = 3 \\ \hspace{0.1cm} \mathfrak{Sm}\mathfrak{Sh} = \mathfrak{Sh}_{-} \mathfrak{Sm}\theta = \mathfrak{Sm}_{-} S$
$\Rightarrow \begin{cases} last 0 = (l_{k}^{2} - l_{k}^{2} + l_{k}^{2}) \Rightarrow \frac{42in_{k}c_{k}}{c_{k}} (s_{k}c_{k}^{2} - 2d_{k} + c_{k}^{2}) \\ last 0 = l_{k}^{2} - \theta_{k} + i \delta \end{cases} \Rightarrow \frac{1}{c_{k}} (s_{k}c_{k}^{2} - 2d_{k} + c_{k}^{2} - s_{k}^{2}) \\ \Rightarrow \frac{1}{c_{k}} (s_{k}c_{k}^{2} - 2d_{k} + c_{k}^{2} - s_{k}^{2}) \\ \Rightarrow \frac{1}{c_{k}} (s_{k}c_{k}^{2} - 2d_{k} + c_{k}^{2} - s_{k}^{2}) \\ \Rightarrow \frac{1}{c_{k}} (s_{k}c_{k}^{2} - 2d_{k} + c_{k}^{2} - s_{k}^{2}) \\ \end{cases}$

(21 - 8)(1 - 1)	
1 = θm2 - μ = <u>23304299 21917</u> × 1 1 = θm2 - 1 Sm2 - 0	
NO ESENTION	
a thrace we three	
$h \sim Sm\Theta = 1$	
$I = \theta m^2 - \frac{\theta}{2}$	
<u>= = 0m2</u>	
$\theta = \operatorname{arcsin}_{\frac{2}{2}} \xrightarrow{\circ e} \operatorname{arccos}_{\frac{1}{2}} \xrightarrow{\circ e} \operatorname{arcbus}_{\frac{2}{2}}$	
FINALLY USING	
$k + \cos \theta = 2$	
$k + \frac{4}{5} = 2$	
$k = \frac{-5}{6}$	
4	
Las ke E. Geordan 3	

 $\theta = \arctan \frac{3}{4}, h =$

 $\frac{6}{5}$

k =

Question 128 (*****)

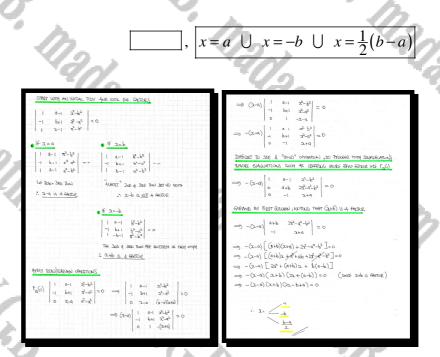
R,

I.F.C.P.

An equation in x is summarized by the following determinant.

$$\begin{vmatrix} 1 & a-1 & (x-b)(x+b) \\ -1 & b+1 & (x-a)(x+a) \\ 1 & x-1 & (a-b)(a+b) \end{vmatrix} = 0$$

Give the solutions in terms of a and/or b where appropriate.



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.F.G.B.

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Question 129 (*****)

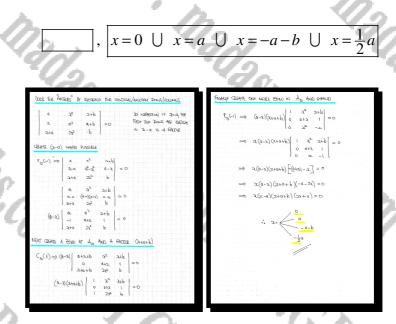
F.G.B. Ma

I.C.B.

An equation in x is summarized by the following determinant.

$$\begin{vmatrix} a & x^2 & x+b \\ x & a^2 & a+b \\ x+a & 2x^2 & b \end{vmatrix} = 0$$

Give the solutions in terms of a and/or b where appropriate.



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Question 130 (*****)

A transformation is defined by the 2×2 matrix

$$\mathbf{T} = \begin{pmatrix} -a & b-a \\ a+b & a \end{pmatrix},$$

where a and b are scalar constants.

If n is an **odd** integer prove that

 $\mathbf{T}^n = b^{n-1}\mathbf{T} \, .$

proof

è

b-a-a+b7 b+a+a-b_

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6+a+a+b

 $\frac{1}{2} \int_{a+b}^{b+1} \times 2 \left(\begin{array}{c} -a \\ a+b \end{array} \right)$

 $\begin{pmatrix} -2a & 2b - 2a \\ 2a + 2b & 2a \end{pmatrix}$



I.C.B.

FINALLY WE CAN MANYOURTE
$\longrightarrow \overline{\tau} = \overline{b} \overline{b} \overline{b}_{n}$
$\rightarrow \underline{T}^{n} = (\underline{\underline{P}} \underline{D} \underline{\underline{P}}^{n})^{M}$
$\longrightarrow \overline{I}_{\mu} = (\overline{b}\overline{b}\overline{b}_{\mu})(\overline{b}\overline{b}\overline{b}_{\mu}) \cdots (\overline{b}\overline{b}\overline{b}_{\mu})(\overline{b}\overline{b}\overline{b}_{\mu})$
2HHLT N
$\implies \underline{T}_{N} = \underline{P} \underline{D}_{n} \underline{P}_{-1}$
$\implies \boxed{\Box}^{N} = \begin{pmatrix} b_{-\alpha} & l \\ b_{+\alpha} & -l \end{pmatrix} \begin{pmatrix} b^{N} & o \\ o & -b \end{pmatrix} \begin{pmatrix} b_{-\alpha} & l \\ b_{+\alpha} & -l \end{pmatrix}^{-1}$
FIND THE INVIECE, 2"
$\frac{1}{-b+a-b-a} \begin{bmatrix} -1 & -1 \\ -b-a & b-a \end{bmatrix} = \frac{1}{-2b} \begin{pmatrix} -1 & -1 \\ -a-b & a+b \end{pmatrix} = \frac{1}{2b} \begin{pmatrix} 1 & 1 \\ a+b & a-b \end{pmatrix}$
THIS WE HAVE
$\implies \underline{\top}^{H} = \begin{pmatrix} b_{-A} & I \\ b_{H} & -I \end{pmatrix} \begin{pmatrix} b^{H} & o \\ o & -b^{h} \end{pmatrix} \begin{pmatrix} I & I \\ a_{H} & b & a_{H} \end{pmatrix} \times \frac{1}{2b}$
$\implies \boxed{1}^{*} = \frac{1}{2b} \begin{pmatrix} b - a & i \\ b u a & -i \end{pmatrix} \begin{pmatrix} b^{*} & 0 \\ 0 & -b^{*} \end{pmatrix} \begin{pmatrix} i & 1 \\ q + b & a - b \end{pmatrix}$
$\longrightarrow \prod_{\mu} = \frac{5p}{l} \begin{pmatrix} p+\sigma & -1 \\ p-\sigma & l \end{pmatrix} \begin{pmatrix} -p(p+\rho) & -p_{\mu}(p+\rho) \end{pmatrix}$
$ \implies \underline{\mathbf{I}}^{*} = \frac{\mathbf{k}}{2b} \begin{bmatrix} \mathbf{b} - \mathbf{a} & \mathbf{i} \\ \mathbf{b} \mathbf{r}_{0} & -\mathbf{i} \end{bmatrix} \begin{bmatrix} \mathbf{i} & \mathbf{i} \\ -\mathbf{a} + \mathbf{b} \end{bmatrix} $

[b+a 1][-a-b -a+b]

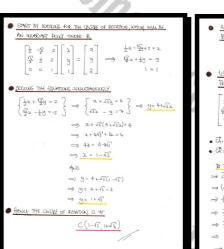
Question 131 (*****)

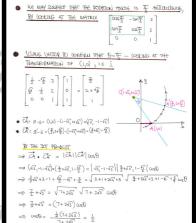
F.C.B.

A rotation R, acting in the x - y plane is given by the following 3×3 matrix.

$$\mathbf{R} = \begin{pmatrix} \frac{1}{2} & -\frac{\sqrt{3}}{2} & 2 \\ \frac{\sqrt{3}}{2} & \frac{1}{2} & 2 \\ 0 & 0 & 1 \end{pmatrix}$$

Find the centre and angle of this rotation.





 $\theta = \frac{1}{3}\pi$

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centre $\left(1-\sqrt{3},1+\sqrt{3}\right)$,

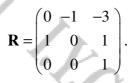
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Question 132 (*****)

F.C.B.

I.C.B.

A rotation R, acting in the x - y plane is given by the following 3×3 matrix.



Find centre and angle of this rotation.

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алоя 2147 — Коптерая на 1906 — 741 20112 1945 — Коптерания торого Тантанания на Стана
$\begin{bmatrix} 0 & -l & -3 & \infty \\ l & 0 & l & q \\ 0 & 0 & l & l \end{bmatrix} = \begin{bmatrix} \infty \\ g \\ 1 \\ 0 \end{bmatrix} \xrightarrow{-g - 3} \begin{array}{c} -g -3 = \infty \\ \Rightarrow \\ 1 - 1 \\ z = l \end{array}$
$\begin{array}{c} \underbrace{\text{SUDNG SHUTMUTUSY}}_{\substack{y=-x-5}} \\ \begin{array}{c} y=x+1 \\ z=-x-3 \\ z=-2 \\ \end{array} & \underbrace{y=-1} \\ \begin{array}{c} x=-2 \\ z=-1 \end{array} & \underbrace{y=-1} \\ \end{array} & \underbrace{(-2,-1)} \end{array}$
THE ANDER OF BOTHTON IS THE SOME AS THAT OF THE TWO INTERSECTIONS WHILL WITH ARE PEOPLISHWINE BY MARCENSY INTRUMETING WEITERS.
TEANSFORM THE GEODE I with E
$\begin{bmatrix} 0 & -i & -\frac{2}{3} \\ 0 & 0 & i \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -3 \\ 2 \\ 1 \end{bmatrix} \qquad (4i)$
$(1_1 \circ) - (-2_1 - 1) = (3_1 \cdot 1)$ $(-3_1 \cdot 2) - (-2_1 - 1) = (-2_1 \cdot 3)$ $(-3_1 \cdot 2) - (-2_1 - 1) = (-2_1 \cdot 3)$ $(-3_1 \cdot 2) - (-3_1 \cdot 3) = -3 + 3 = 0$
二 王 Hinke Qui hetacocuse econtor ey 生, Hearr (-2,1)

ŀ.C.p.

centre $(-2,-1), \ \theta = \frac{\pi}{2}$

Question 133 (*****)

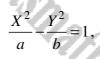
The point P(x, y) is mapped onto the point Q(X, Y) by the rotation described by the matrix transformation

 $\begin{pmatrix} X \\ Y \end{pmatrix} = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$

The above transformation is used to rotate the hyperbola with equation

$$4x^2 - 44xy - 29y^2 = 120$$

onto the hyperbola with equation



where a and b are positive constants.

a) Given that the rotation is by angle θ , such that θ is acute, find the exact value of $\tan \theta$.

b) Determine the value of a and the value of b.

 $\begin{pmatrix} x \\ \gamma \end{pmatrix} = \begin{pmatrix} 000 & -000 \\ sm0 & cos0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$ (X) (BMR BOD) (Y) (BROD BMR-) $\cos\theta = \frac{2}{2N}$ 10 6030-4 รามปีเ $\begin{array}{l} \mathbb{H}_{45}: \left(4n\frac{4}{5} + 44(x\frac{2}{3} - 28x\frac{1}{5})\chi^{2} + 0\chi\gamma + \left(4x\frac{1}{3} - 44(x\frac{2}{3} - 28x\frac{4}{5})\gamma^{2}\right)\chi^{2} \\ \Rightarrow 15\chi^{2} - 40\gamma^{2} = 120 \end{array}$ 4X²co20 + 8XYcos05m0 + 4Y²suit $\Rightarrow \frac{15\chi^2}{120} - \frac{40\gamma^2}{120} = 1$ ialam0-44XYaos?0 - 44Y°sinQual - 29Y2050 X(GiuzPS-OnizBoa44+ Qiai 10+44549-44620)XX 445MAURA - 296020)Y2 mBlosb + 445470 - 44.0634 10- Was All comb.

 $\tan \theta =$

b=3

a = 8

(*****) Question 134

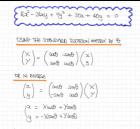
A parabola has the following equation

 $y^2 = Ax, \ x \ge 0, \ A > 0.$

The parabola is rotated about O onto a new parabola with equation

 $16x^2 - 24xy + 9y^2 + 30x + 40y = 0.$

Use algebra to determine the value of A.



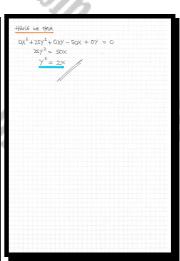
SUBSTITUTE WOD THE EQUATION $\sum_{k=1}^{2} \left(\theta_{k0}X + \theta_{k0}X + \theta_{k0}X + \theta_{k0}X + \theta_{k0}X \right) + 9 \left(\theta_{k0}X + \theta_{k0}X \right) \lambda + \theta_{k0}X + \theta_{k0}$ $+30(X \cos \theta + Y \sin \theta) + 40(-X \sin \theta + Y \cos \theta) = 0$

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C.B.

7622020 + 3224/02000+16429190 24222000-24242020+242429190-2424 922909-18249100+492220 MB) + Y(3051119 + 406058)

$(16 \log \theta + 24 \sin \theta \cos \theta + 9 \sin^2 \theta) X^2$
(-24a30+14a30an0+245m30)×Y
+ (960 - 24embud + 16emb) $\gamma^2 > = 0$
+ ×(19m204 - 1920 0E)
+ (30amθ + 40 unθ)γ
-AR THE WOULL OF THE FORM $Y^2 = AX$
$ \begin{array}{c} \fbox{1} 355m\theta + 40xe \theta = 0 \\ 355m\theta = -40xe \theta \\ but \theta = -\frac{4}{3}. \end{array} $
As Θ is carose single $\frac{\mu}{2} = \theta$ as $\theta = \frac{3}{2}$
$\left[\chi \right] = 30 \left(-\frac{3}{5} \right) - 40 \left(\frac{4}{5} \right) = -\frac{90}{5} - \frac{460}{5} = -50$
$\left[\begin{array}{c} \lambda_{\tau}\\ \end{array}\right] = \left\{\left(\frac{\pi}{52}\right) - 5\pi\left(\frac{\pi}{2}\right)\left(-\frac{\pi}{5}\right) + \mathbb{R}\left(\frac{\pi}{55}\right) = -\frac{81 + 588 + 522}{52} = \frac{552}{52} = 52$
$\left[\sum_{i=1}^{n} \sum_{j=1}^{n} \left[\sum_{i=1}^{n} \left(\frac{4}{2\alpha} \right) + 24 \left(\frac{4}{3} \right) \left(\frac{3}{3} \right) + 4 \left(\frac{R}{23} \right) \right] = \frac{1444 - 2384 + 1444}{23} = 0$
$\left[\chi\chi\right] -2t\left(\frac{3}{22}\right) + tt\left(\frac{1}{2}\right)\left(\frac{3}{2}\right) + \frac{3}{2}t\left(\frac{2}{22}\right) = \frac{-126}{22} - \frac{16}{22} + \frac{3}{24} = 0$



A.C.B.

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A = 2

Question 135 (*****)

Use the properties of determinants to express the following determinant in fully factorized form.

 $b^2 + bc \quad c^2 + bc$ -bc I.F.C.P. $c^2 + ac$ $a^2 + ac - ac$ $a^2 + ab$ $b^2 + ab$ Ś –ab $(ab+bc+ca)^2$ 20 Smaths, LING ROW AND COU OTHER NANIAULATIONS bctab (ab+bc+ca) c+ bc ab-bc-ca C32(-1) ab+bc+ca ab+bc+ca -ab at tab bt ab SEXPANDING BY THE FREST COWMIN (OR BY THE FREST BOD) a, f2 BY b a f3 BY c As THIS OHNCES = (ab+bc+ac) $\begin{vmatrix} o & i \\ -ab-bc-ca & bc+ab \end{vmatrix}$ (ab+bc+ca)NT , INTRODUCE & FACEDE OUTSIDE abc ab2+abc ac2+ab = $(ab + bc + ca) \times (ab + bc + ca) \times (ab + bc + ca)$ ahr. br2+a actabe létrale -alec = $(ab + bc + ca)^3$ C, borror C, & COUT OF C, actab ah+he bc +ak -ab I.C.B. Ma abtbct F21 (i) bc+ab r₃₁(1) act be TACTORIZING DOT 6 P THE FIRST DOU = (ab+bc+ac) ab+b 21/18 23 1. C.B. Madası I.V.C. I.C.B. Created by T. Madas