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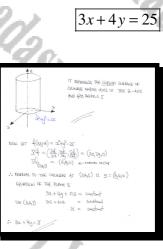
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Question 1

A surface S is given by the Cartesian equation

 $x^2 + y^2 = 25.$

- **a**) Draw a sketch of S, and describe it geometrically.
- b) Determine an equation of the tangent plane on S at the point with Cartesian coordinates (3,4,5).



Question 2

A Cartesian position vector is denoted by \mathbf{r} and $r = |\mathbf{r}|$

Show by detailed workings that

proof

- $\overline{\Delta} \ r \ = \ \overline{\Delta} \left[\left(x_1^2 + y_2^2 + z_3 \right)_2^2 \right] \ = \ \left[\frac{3}{2\pi} \left[\left(z_1^2 + y_1^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \frac{1}{2\pi} \right]_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \frac{1}{2\pi} \left[\left(x_1^2 + y_3^2 + z_3 \right)_2^2 \frac{1}{2\pi} \right]_2^2 \frac$
 - $= \left(\frac{1}{2} (x^2 + y^2 + z^2)^{\frac{1}{2}} 2\lambda_1 + \frac{1}{2} (x^2 + y^2 + z^2)^{\frac{1}{2}} x 2y_1 + \frac{1}{2} (x^2 + y^2 + z^2)^{\frac{1}{2}} x z_E \right)$
 - $= \left[\left(\frac{\chi_1}{2}, \frac{\eta_1}{2}, \frac{\eta_2}{2} \right)_{\frac{1}{2}} + \left(\frac{\chi_1^2 + \eta_2^2 + \eta_2^2}{2} \right) \cdot \left(\frac{\chi_1^2 + \eta_2^2 + \eta_2^2}{2} \right)_{\frac{1}{2}} = \left[\left(\frac{\chi_1}{2}, \frac{\eta_1}{2}, \frac{\eta_2}{2} \right)_{\frac{1}{2}} \right]$
 - $=\frac{1}{\Gamma}(x_iy_iz)=\frac{\Gamma}{\Gamma}$

∇(a · r)

Question 3

A Cartesian position vector is denoted by \mathbf{r} and $r = |\mathbf{r}|$.

Given that \mathbf{a} is a constant vector find

 $\nabla(\mathbf{a}\cdot\mathbf{r}) = \mathbf{a}$

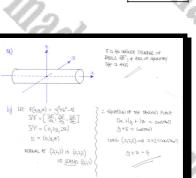
$$\begin{split} & \left(\mathfrak{G}_{\mathbf{t}} \right) = \left[\mathfrak{G}_{\mathbf{t}} (\mathfrak{g}_{\mathbf{t}}, \mathfrak{g}_{\mathbf{t}}) \right] \mathfrak{G}_{\mathbf{t}} = \left[\mathfrak{G}_{\mathbf{t}} (\mathfrak{g}_{\mathbf{t}}, \mathfrak{g}_{\mathbf{t}}) \mathfrak{g}_{\mathbf{t}} \right] \mathfrak{G}_{\mathbf{t}} = \left(\mathfrak{g}_{\mathbf{t}}, \mathfrak{g}_{\mathbf{t}} \mathfrak{g}_{\mathbf{t}} \right) \mathfrak{G}_{\mathbf{t}} \mathfrak{g}_{\mathbf{t}$$

Question 4

A surface S is defined by the Cartesian equation

 $y^2 + z^2 = 8.$

- **a**) Draw a sketch of S, and describe it geometrically.
- **b**) Determine an equation of the tangent plane on S at the point with Cartesian coordinates (2,2,2).



y + z = 4

Question 5

The scalar function V is defined as

 $V(x, y, z) = (y + z)^{2} + y^{2}(x + y) + xyz + 1.$

Determine the value of the directional derivative of V at the point P(1,-1,1), in the direction $-\mathbf{i} + \mathbf{j} + \mathbf{k}$.

• $V = (9+2)^{2} + 9^{2}(249) + 292 + l = (9+2)^{2} + 29^{2} + 9^{2} + 292 + l$ • $P(1_{j-(1)})$

 $\sqrt{3}$

- $\underline{U} = (-I_1I_1)$
 - FINITLY: $\sum V = \begin{pmatrix} 3V \\ 3\alpha \\ 3\alpha \end{pmatrix} \begin{pmatrix} 3V \\ 3z \\ 3z \end{pmatrix}$
 - $$\begin{split} & \sum V = \begin{bmatrix} y^2 + y^2 \\ -y^2 + y^2 \end{bmatrix} & (y_1 + 2 + 2 + y + 2 y^2 + x_{2-1} 2 (y_1 + 2) + 2 y \end{bmatrix} \\ & \sum V \begin{bmatrix} z \\ -y \end{bmatrix} & (y_1 + 2 + y + 1) \end{bmatrix} \\ & = \begin{bmatrix} (y_1 2 + 3 + 1) \\ -y \end{bmatrix} & (y_1 + y) \end{bmatrix} \end{split}$$
 - $\mathbb{Z} \wedge [(-1)] = (0^{1} S)$
 - ((⊣(1) גד: <u>1</u> = (⊣(1,1
 - (<u>u</u>) = N3
 - $\hat{\underline{G}} = \frac{1}{\sqrt{3}} \left(-l_1 l_1 \right)$
 - DIEGTIONAL DROUTHULF AT THE REQUISED POINT AND DIEGTION $\overline{SV} \cdot \underline{0} = (Q_{21}) \cdot \frac{1}{15} (U_{11}) = \frac{Q_{42} + 1}{45} = \frac{3}{45} = \sqrt{3}$

Question 6

The scalar function φ is defined as

 $\varphi(x,y,z) = \mathrm{e}^{x-y}\sin z \, .$

Determine the value of the directional derivative of φ at the point P(1,1,0), in the direction $\mathbf{i} + \mathbf{j} + \mathbf{k}$.

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- (ALYZ) = e^{2-y} ANZ

 $\sqrt{3}$

- $\underline{a} = (I_1 I_1 I) \longrightarrow \underline{\underline{a}} = \frac{1}{\sqrt{2}} (I_1 I_1 I)$
- $\begin{array}{c} & & & \\ &$
- $\frac{1}{2} \sum_{k=0}^{\infty} \sum_{j=1}^{\infty} \frac{1}{j} = |x_j| \times \frac{1}{2^k} = 0 \text{ solution} \frac{1}{2^k} \sum_{j=1}^{\infty} \frac{1}{2^k}$

Question 7

The point P(1,2,3) lies on the surface with Cartesian equation

$$2z^2 = 6x^2 + 3y^2.$$

The scalar function u is defined as

$$u(x, y, z) = x^2 yz + x^2 y.$$

Determine the value of the directional derivative of u at the point P in the direction to the normal at P.

	6√3
$ \begin{array}{l} \underbrace{ \begin{pmatrix} U_{i} = \frac{2}{4}U_{i} \frac{1}{2} + \frac{2}{3}U_{i} \\ U_{i} = \frac{2}{4}U_{i} \frac{1}{2} + 1 \end{pmatrix} \\ \nabla u = \begin{pmatrix} 2u_{i} & u_{i} & u_{i}^{2} \\ 2u_{i} & u_{i} & u_{i}^{2} \\ 2u_{i} & u_{i} & u_{i}^{2} \\ U_{i} & u_{i} & u_{i}^{2} \\ U_{i} & u_{i} & u_{i}^{2} \\ U_{i} & u_{i} \\ U_{i} & u_{i} \\ \underbrace{ \int}_{u_{i}} & u_{i} & u_{i} \\ \underbrace{ \int}_{u_{i}} & u_{i} \\ \\ \underbrace{ \int}_{u_{i}} & u_{i} \\ \underbrace{ \int}$	$\begin{array}{c} \sum_{i=1}^{n} \frac{1}{C_{i}} \left(c_{i} t_{i}^{-1} \right) \\ \sum_{i=1}^{n} \frac{1}{C_{i}} \left(c_{$
=	with the AT $(j_1 \ell_1 j_2)$ $(k_1 \ell_2 \ell_3) = \frac{1}{63} C_1 \ell_1 - 1)$ $\frac{(k_1 \ell_2)}{63} = \frac{1}{63} \frac{k_1 \ell_2^{-1}}{3}$ 643^{-1}

Question 8

F.G.B.

.K.C.

The point $P(1, y_0, z_0)$ lies on both surfaces with Cartesian equations

 $x^{2} + y^{2} + z^{2} = 9$ and $z = x^{2} + y^{2} - 3$.

The two surfaces intersect each other at an angle θ , at the point P.

Given further that P lies in the first octant, determine the exact value of $\cos \theta$.

2	$\cos\theta = \frac{\sigma}{3\sqrt{21}}$
20	h.
P(10,2) 22+42 22+43	$ \begin{array}{ccc} +2^2 = 9 \\ = 2+3 \end{array} \xrightarrow{ \left[1+y^2 = 9 - 2^2 \right]} \\ \left[+y^2 = 2+3 \right] \end{array} $
	$a^{2}+u^{2}+2^{2}=9$ $(+u)^{\frac{3}{2}}+4 \approx 9$
$(\underline{z}_{\pm}3)(\underline{z}-\underline{z})=0$ $\underline{z}= \overset{2}{\overset{2}{\overset{2}{\overset{2}{\overset{2}{\overset{2}{\overset{2}{\overset{2}$	$y^{2} = 4$ $y^{2} < \frac{2}{2}$ $\Rightarrow P(t_{1}22)$
$\begin{array}{llllllllllllllllllllllllllllllllllll$	$ \begin{array}{ccc} \overset{2-9}{} & \overset{2}{\overrightarrow{A}} & & & & & \\ & & & & & \\ \overset{2}{\overrightarrow{b}} & & & & \\ & & & & \\ \overset{2}{\overrightarrow{b}} & & & & \\ & & & & \\ & & & & \\ & & & &$
$\overline{\eta}^{\delta} = (\alpha^{\dagger} \vec{n}^{\dagger} \vec{s})$ $\overline{\eta}^{\delta} = (\alpha^{\dagger} \vec{n}^{\dagger} \vec{s})$	$\sum_{n=1}^{n} \frac{1}{2n} = (2n^{1}2n^{1}-1)$
AT P	AT P
$\underline{h}\underline{q} = (l_1 2_1 2)$	$\left\langle \frac{\eta}{m^{2}} = \left(S^{I} \theta^{I} - 1 \right) \right\rangle$
TOUGHF TOF FIT VE	
$(1_12_12) \cdot (2_14_1 - 1)$	$= [1_1 z_1 2] [2_1 4_1 - 1] \cos \Theta$
	8200 1+61+4 N 4+1++
8 = 3 121 0051	÷
$\cos \theta = -\frac{8}{3\sqrt{2}}$	/

K.C.A.

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Question 9

A Cartesian position vector is denoted by \mathbf{r} and $r = |\mathbf{r}|$.

Given that $\varphi(r) = \ln r$, show that

 $\nabla \varphi(r) = \frac{\mathbf{1}}{r^2}.$

 $\begin{array}{l} \left(\frac{1}{2} \langle x_1 y_1 z \rangle = b_1 \left[z_1^{-1} \frac{1}{2} - \zeta_1^{-1} z_1^{-1} z_1^{-1} \right] \\ \left(\frac{1}{2} \langle x_1 y_1 z \rangle = \frac{1}{2} b_1 \left(z_1^{-1} y_1^{-1} z_2^{-1} \right) \\ \left(\frac{1}{2} \langle x_1 y_1 z \rangle = \frac{1}{2} b_1 \left(z_1^{-1} y_1^{-1} z_2^{-1} \right) \\ \left(\frac{1}{2} \langle x_1 y_1 z \rangle = \frac{1}{2} b_1 \left(z_1^{-1} y_1^{-1} z_2^{-1} \right) \\ \left(\frac{1}{2} \langle x_1 y_1 z \rangle = \frac{1}{2} b_1 \left(z_1^{-1} z_2^{-1} z_2^{-1} \right) \\ \left(\frac{1}{2} \langle x_1 y_1 z \rangle = \frac{1}{2} b_1 \left(z_1^{-1} z_2^{-1} z_2^{-1} \right) \\ \left(\frac{1}{2} \langle x_1 y_1 z \rangle = \frac{1}{2} b_1 \left(z_1^{-1} z_2^{-1} z_2^{-1} z_2^{-1} \right) \\ \left(\frac{1}{2} \langle x_1 y_1 z \rangle = \frac{1}{2} b_1 \left(z_1^{-1} z_2^{-1} z_2^{-1}$

Question 10

A Cartesian position vector is denoted by \mathbf{r} and $r = |\mathbf{r}|$.

Show by detailed workings that

 $\nabla r^3 \equiv 3r\mathbf{r}$.

proof

proof

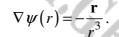
 $= \left[3\alpha (2^{\frac{1}{2}} y_{1}^{2} + \overline{v}^{2})^{\frac{1}{2}}, 3y (2^{\frac{1}{2}} + y_{1}^{2} + \overline{v}^{2})^{\frac{1}{2}}, 3z (2^{\frac{n}{2}} + y_{1}^{2} + \overline{v}^{2})^{\frac{1}{2}} \right]$

= 3(2²+y²+2²)² [2(3)=] = 3(1)[

Question 11

A Cartesian position vector is denoted by \mathbf{r} and $r = |\mathbf{r}|$.

Given that $\psi(r) = \frac{1}{r}$, show that



$$\begin{split} & \left[\left(\frac{1}{2} \left(y_{1}^{2} y_{1}^{2} \right)^{2} - \frac{1}{2} \right) \left(\frac{1}{2} \left(y_{1}^{2} y_{1}^{2} \right)^{2} - \frac{1}{2} \right) \left(\frac{1}{2} \left(y_{1}^{2} y_{1}^{2} y_{1}^{2} \right)^{2} \right) \right) \\ & = \frac{1}{(2^{2} (y_{1}^{2} y_{1}^{2} y_{1}^{2}))} \left(\frac{1}{2} \left(\frac{y_{1}^{2} y_{1}^{2} y_{1}^{2} y_{1}^{2} \right)^{2} \right) \left(\frac{y_{1}^{2} y_{1}^{2} y_{1}^{2} y_{1}^{2} \right) \right) \\ & = \frac{1}{(2^{2} (y_{1}^{2} y_{1}^{2} y_{1}^{2}))} \left(\frac{1}{2} \left(\frac{y_{1}^{2} y_{1}^{2} y_{1}^{2} y_{1}^{2} \right) \right) \left(\frac{y_{1}^{2} y_{1}^{2} y_{1}^{2} y_{1}^{2} y_{1}^{2} \right) \\ & = \frac{1}{(2^{2} (y_{1}^{2} y_{1}^{2} y_{1}^{2}))} \left(\frac{1}{2} \left(\frac{y_{1}^{2} y_{1}^{2} y_{1}^{2} \right) \right) \left(\frac{y_{1}^{2} y_{1}^{2} y_{1}^{2} y_{1}^{2} \right) \\ & = \frac{1}{(2^{2} (y_{1}^{2} y_{1}^{2} y_{1}^{2}))} \left(\frac{y_{1}^{2} y_{1}^{2} y_{1}^{2} y_{1}^{2} + \frac{y_{1}^{2} y_{1}^{2} y_{1}^{2} y_{1}^{2} y_{1}^{2} \right) \\ & = \frac{1}{(2^{2} (y_{1}^{2} y_{1}^{2} y_{1}^{2}))} \left(\frac{y_{1}^{2} y_{1}^{2} y_{1}^{2} y_{1}^{2} + \frac{y_{1}^{2} y_{1}^{2} y_{1}^{2} y_{1}^{2} y_{1}^{2} y_{1}^{2} y_{1}^{2} + \frac{y_{1}^{2} y_{1}^{2} y_{1$$

Question 12

A Cartesian position vector is denoted by \mathbf{r} and $r = |\mathbf{r}|$.

Show clearly that

 $\nabla(r^n) = nr^{n-2}\mathbf{r} \ .$

proof

proof

$$\begin{split} & \widetilde{Y}[T] = \sum_{i=1}^{n} \left[\frac{\partial_{i}^{i} u_{i}^{i} u_{i}^{i} u_{i}^{i} u_{i}^{i}}{\partial_{i}^{i} u_{i}^{i} u_$$

Question 13

F.G.B.

I.C.B.

The surface S has Cartesian equation

f(x, y, z) = constant,

where f is a smooth function.

Given that $\nabla f \neq \mathbf{0}$, show that ∇f is a normal to S.

Software the quartices of the construct a $\{Q_{\rm QQ}, U\}$ = construct of a calle C, lit as the data integrated subtract A calle is a local index translation caller on the dataset of A dataset measuring of C (that the translation is a construction of A dataset measuring

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proof

 $\frac{f(\partial(\partial f) = f(a(t)^{\dagger}\partial(f) S(t))}{0 (f + f(t))} = \frac{f(a(t)^{\dagger}\partial(f) S(t))}{0}$

Diffectivities wert t, the normal that $f(a_1y_1z) = constant$ <math>O = 2f dx + 2f dy. If de

 $O = \sum \frac{1}{\sqrt{2}} \cdot \frac{1}{\sqrt{2}}$

BIT de is a tradest to the weak (unce sufficiention) So If is rearrance to the tradest

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i.C.p.

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 $\nabla f(r) = \frac{\mathbf{r}}{r} f'(r) \, .$

Question 14

I.F.G.B.

, Y.G.B.

I.V.G.B.

A Cartesian position vector is denoted by \mathbf{r} and $r = |\mathbf{r}|$.

Given that f(r) is a differentiable function, show that

nana,

$$\begin{split} \underbrace{\mathsf{MANAPUATE}}_{\mathsf{C}} & \mathsf{A} \text{ Excount}} \\ & \boldsymbol{\nabla} \left\{ (\sigma) = \begin{bmatrix} \frac{2}{2k}, \frac{2}{2k}, \frac{2}{2k}, \frac{2}{2k} \end{bmatrix} = \begin{bmatrix} \frac{2}{2k}, \frac{2}{2k} \end{bmatrix} \\ & = \frac{2}{2k} \begin{bmatrix} \frac{2}{2k}, \frac{2}{2k}, \frac{2}{2k}, \frac{2}{2k}, \frac{2}{2k} \end{bmatrix} \\ & = \frac{2}{2k} \begin{bmatrix} \frac{2}{2k}, \frac{2}{2k}, \frac{2}{2k}, \frac{2}{2k}, \frac{2}{2k} \end{bmatrix} \\ & \Rightarrow f = (x_{2k})_{(k}^{2k}) \\ & \Rightarrow f = (x_{2k})_{(k}^{2k}) \\ & \Rightarrow \frac{2}{2k} = \frac{1}{2k} (x_{1}^{2}x_{1}^{2}x_{2}^{2})^{\frac{1}{2k}} \\ & \Rightarrow \frac{2}{2k} = \frac{1}{2k} (x_{1}^{2}y_{1}^{2}x_{2}^{2})^{\frac{1}{2k}} \\ & \Rightarrow \frac{2}{2k} (x_{1}^{2}y_{1}^{2}x_{2}^{2})^{\frac{1}{2k}} \\ & = \frac{2}{2k} (x_{1}^{2}y_{1}^{2}x_{2}^{2})^{\frac{1}{$$

I.C.B.

proof

.C.D.

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Question 15

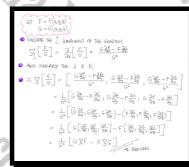
The smooth functions F(x, y, z) and G(x, y, z) are given.

Show that

1

$$\nabla \left[\frac{F}{G}\right] = \frac{G(\nabla F) - F(\nabla G)}{G^2}$$

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Question 16

 $\Psi(x, y, z) = (x^2)$ $\int x^2 + v^2 + z^2$ $(z^{2} + z^{2})e$

Show that

ŀ.C.p.

$$\nabla \left[\Psi(x, y, z) \right] = (x\mathbf{i} + y\mathbf{j} + z\mathbf{k}) \left(2 - \sqrt{x^2 + y^2 + z^2} \right) e^{-\sqrt{x^2 + y^2 + z^2}}.$$

proof

proof

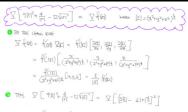
min	
(2143) = (2+y+2) = 12+y+227	
$ \begin{array}{c} & & & \\ \Gamma = \left\lfloor z \right\rfloor_{a} \left(\mathbf{z}^{2} \mathbf{t}^{2} \mathbf{t}^{2} \mathbf{t}^{2} \mathbf{t}^{2} \mathbf{t}^{2} \mathbf{t}^{2} \right) \\ & & & \\ \end{array} \right\} \begin{array}{c} & & \\ \Psi(\tau) = \mathbf{t}^{2} \mathbf{e}^{\tau} \end{array} $	
$ \left\{ \begin{array}{c} \text{NOW WAINS THE STRUDGED BOUT OF GRADINT} \\ & \\ &$	
$\nabla \left[\psi(r) \right] = \psi(r) \frac{r}{r} = \left[2re^{r} - r^{2}e^{-r} \right] \frac{r}{r}$	
$2^{\frac{1}{2}} (n-2) - 2\left[\frac{1}{2}n - \frac{1}{2}S\right] =$	
$\nabla \psi(x_1x_2) = \left[2 - \sqrt{x^2 + y^2 + z^2}\right] e^{-\sqrt{x^2 + y^2 + z^2}} \left[3y_1z\right]$	

Question 17

A Cartesian position vector is denoted by \mathbf{r} and $r = |\mathbf{r}|$.

Show that

 $\nabla \left(9r^2 + \frac{4}{r} - 12\sqrt{r}\right) = 2\left(3 - 2r^{-\frac{3}{2}}\right)\left(3 + r^{-\frac{3}{2}}\right)\mathbf{r}.$



proof

 $= 2\left[\frac{3|E| - 2||E|^{-\frac{1}{2}}}{2}\right]\left[\frac{3+|E|^{-\frac{1}{2}}}{2}\right]\frac{E}{|E|}$ = 2 $\left[3-2||E|^{-\frac{1}{2}}\right]\left[\frac{3+|r|^{-\frac{1}{2}}}{2}\right]\frac{E}{r}$

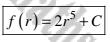
Question 18

A Cartesian position vector is denoted by \mathbf{r} and $r = |\mathbf{r}|$.

The smooth function f(r) satisfies

 $\nabla \left[f\left(r\right) \right] = 10r^{3}\mathbf{r} \,.$

Determine a simplified expression for f(r)



$ \left\{ \begin{array}{c} (\zeta_{1},\zeta_{1}) = \zeta_{2} \\ (\zeta_{1},\zeta_{2}) = \zeta_{$
ST THE OFAN RULE
∑[f(n] = f(n) ∑r = f(n [號, 鍔(罪]
$ = \int_{t}^{t} \langle r \rangle \left[\frac{2}{r_{1}^{2}} \frac{1}{r_{1}^{2}} \frac{1}{r$
$ \text{ for } \operatorname{tor}^{3} \mathfrak{L} = \operatorname{tor}^{4} \left(\frac{\mathfrak{L}}{r} \right) = \dots \underbrace{\nabla} \left(2r^{5} \right) \underbrace{f(r)}_{r} $
$\therefore f(r) = 2r^{r} + C$

DIVER. $div \mathbf{F} \equiv \nabla \cdot \mathbf{A}$ ASTRAILS COM I. Y. C.B. MARIASINALIS.COM I. Y. C.B. MARIASIN

 $abla \cdot \mathbf{r}$.

Question 1

A Cartesian position vector is denoted by \mathbf{r} .

Determine the value of



 $\sum \cdot \frac{1}{2} = \left(\frac{\partial z}{\partial z}\right) \frac{\partial z}{\partial z} \left(\frac{\partial z}{\partial z}\right) \cdot \left(\frac{\partial z}{\partial z}\right) \frac{\partial z}{\partial z} = \frac{\partial z}{\partial z} + \frac{\partial z}{\partial z} + \frac{\partial z}{\partial z} = 1 + 1 + 1 + 2$

Question 2

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I.G.B.

A Cartesian position vector is denoted by \mathbf{r} .

Given that **a** is a constant vector, find

 $\nabla \cdot (\mathbf{a} \wedge \mathbf{r})$.



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(215) -	$= \begin{pmatrix} 1 \\ \overline{\partial_{\alpha}} & \frac{1}{\partial \partial_{\beta}} & \frac{1}{\partial \partial_{\beta}} \end{pmatrix} \cdot \begin{vmatrix} 1 & 0 & k \\ a_{1} & a_{1} & a_{1} \\ a_{2} & a_{1} & a_{2} \\ x & y & z \end{vmatrix} = \begin{vmatrix} \frac{1}{\partial \alpha} & \frac{1}{\partial \alpha} & \frac{1}{\partial \alpha} & \frac{1}{\partial \alpha} \\ a_{1} & a_{2} & a_{3} \\ x & y & z \end{vmatrix}$
	$= \frac{\partial \mathcal{L}}{\partial \mathcal{L}} \Big(d_2 \mathcal{L} - d_3 \mathcal{L} \Big) + \frac{\partial}{\partial \mathcal{L}} \Big(d_3 \mathcal{L} - \partial_1 \mathcal{R} \Big) + \frac{\partial}{\partial \mathcal{L}} \Big(d_1 \mathcal{H} - d_2 \mathcal{L} \Big)$
-	0+0+0
2	•

Question 3

A Cartesian position vector is denoted by \mathbf{r} .

Given that \mathbf{a} is a constant vector, show that

 $\nabla \cdot \left[\left(\mathbf{a} \cdot \mathbf{r} \right) \mathbf{r} \right] = 4 \mathbf{a} \cdot \mathbf{r} \, .$

$\underline{1} \cdot (\underline{1} \cdot \underline{2}) \underline{\nabla} + \underline{1} \cdot \underline{\nabla} (\underline{1} \cdot \underline{0}) = \begin{bmatrix} \underline{1} (\underline{1} \cdot \underline{0}) \\ \underline{1} \cdot \underline{1} \end{bmatrix}$	
$\left[\nabla \left[\varphi \Delta \right] = \phi \nabla \cdot \Delta + \nabla \phi \cdot \Delta \right]$	
$= \left[\left[(a^{\dagger} a^{\dagger} a^{\dagger} a^{\dagger}) \cdot (a^{\dagger} a^{\dagger} s^{\dagger}) \right] \left(\begin{array}{c} \overset{\otimes}{\Rightarrow} & \overset{\otimes}{\Rightarrow} & \overset{\otimes}{\Rightarrow} \\ \overset{\otimes}{\Rightarrow} & \overset{\otimes}{\Rightarrow} & \overset{\otimes}{\Rightarrow} \\ \end{array} \right) \cdot (a^{\dagger} a^{\dagger} s^{\dagger}) + \sum \left(s^{\dagger} a^{\dagger} a^{\dagger} s^{\dagger} s^{\dagger}$	$(\underline{r}) \cdot (\underline{x}_1 \overline{s}_1 \overline{s})$
$= \left[a_{1}x + a_{2}y + a_{3}z \right] \left[\frac{2x}{2x} + \frac{2y}{2y} + \frac{2x}{2z} \right] + \nabla (g \cdot r)$) • ભાષા છે.
$= (a_{12} + a_{23} + a_{3}2) \times 3 + (a_{11} a_{21} a_{3}) \cdot (a_{13} a_{2})$	$\frac{\partial g}{\partial t}(\mathbf{q}\cdot\mathbf{r}) + \frac{\partial g}{\partial t}(\mathbf{q}\cdot\mathbf{r})$
$= \exists (a_1 \chi + a_2 y + a_3 z) + (a_1 \chi + a_2 y + a_3 z)$	
$= 4(a_1 + a_2 + a_3)$	
$= \notin (\alpha^{i} (\theta^{j}) \theta^{j})^{*} (\alpha^{i} \theta^{i} S)$	
= 4 <u>a</u> · <u>r</u>	

proof

Question 4

Y.C.B.

A Cartesian position vector is denoted by \mathbf{r} .

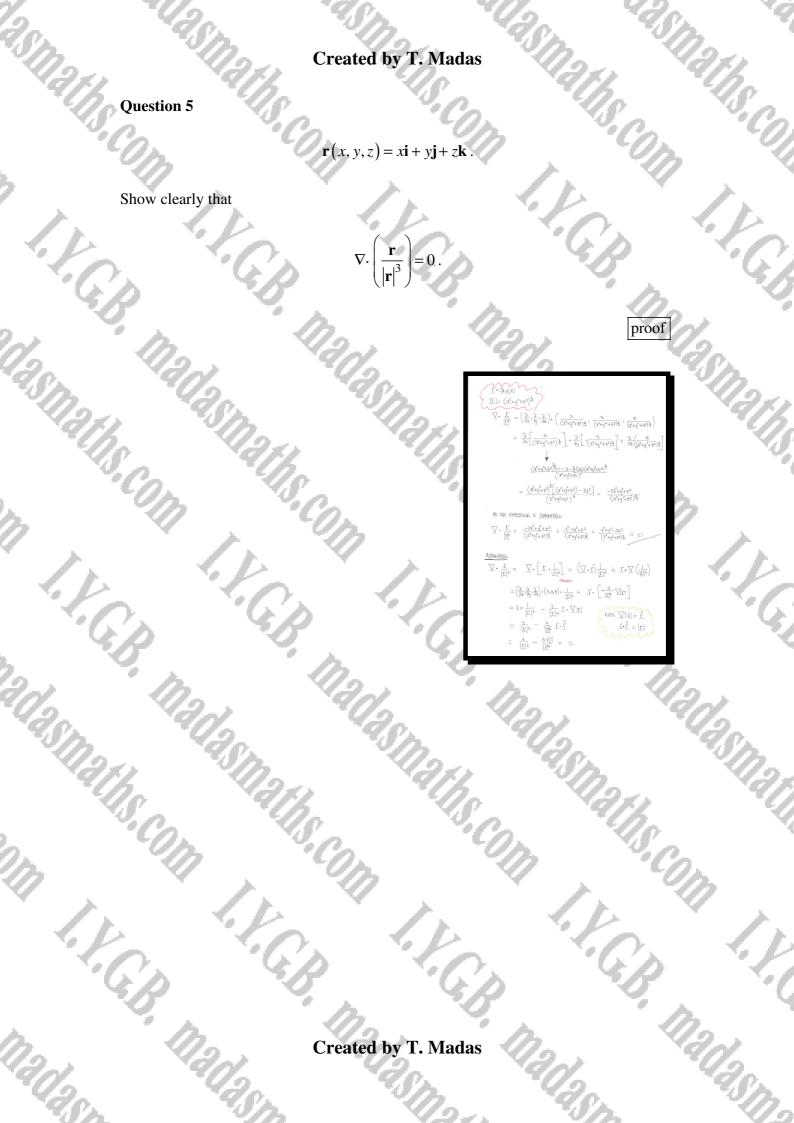
Given that **a** is a constant vector, show that

 $\nabla \cdot \left[\mathbf{r} \wedge (\mathbf{r} \wedge \mathbf{a}) \right] = 2\mathbf{a} \cdot \mathbf{r} \, .$



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$\underline{1} - \underline{1} \underbrace{\nabla}_{\mathbf{x}} \underbrace{(\underline{p}, \underline{1})}_{\mathbf{x}} = \underbrace{[(\underline{p}, \underline{1}), \underline{1}]}_{\mathbf{x}} \cdot \underline{\nabla}_{\mathbf{x}}$	(<i>b</i> , 1), √2 +
$\nabla \cdot (A, B) = B \cdot (\nabla A) - A \cdot (\nabla B)$	
$ \begin{array}{c} \nabla_{A} 1 = \begin{bmatrix} 1 & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \end{bmatrix} = \begin{pmatrix} 0, 0, 0 \end{pmatrix} $	
$= -\underline{\mathbf{f}} \cdot \underline{\nabla}_{\mathbf{A}} (\underline{\mathbf{f}}_{\mathbf{A}} \underline{a}) = \dots$	$\bullet \underline{\Gamma}_{A} \underline{a} = \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ \underline{x} & \underline{y} & \underline{z} \\ \underline{a_{i}} & \underline{a_{2}} & \underline{a_{3}} \end{vmatrix}$
= 21.0	$\left((\theta^{-} x_{\theta}^{*}, y_{\theta^{-}} \cdot s_{\theta}^{*}, e_{\theta}^{*} - s_{\theta}^{*}) \right) =$ $(\theta_{A} \perp x_{\theta}^{*}, y_{\theta^{-}} \cdot s_{\theta}^{*}) = 0$
= 2Q.C	= 1, 1, 2, 2, 3, 4, 4, 4, 4, 4, 4, 4, 4, 4, 4, 4, 4, 4,
}	$= (-a_1 - a_{11} - a_2 - a_{21} - a_3 - a_3)$ = $(-a_1 - a_{11} - a_2 - a_{21} - a_3 - a_3)$ = $(-2a_{11} - 2a_{22} - 2a_{33})$.
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Question 6

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A Cartesian position vector is denoted by **r**.

Given that **m** is a constant vector, show that

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m∧r = 0 .

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$\underline{\mathbf{W}} = (\mathbf{W}_1, \mathbf{W}_2, \mathbf{W}_3)$ • $\underline{r} = (x_1 y_1 z)$ <u>ι</u> μ. μ. α. g (wzz-wzy, wzr-wiz, wig -PUTTING ALL THE DESUGS TOO $\underline{\nabla} \cdot \left(\frac{\mathbf{M}^{*} \mathbf{U}}{\mathbf{b}^{*}} \right) = \underline{\nabla} \cdot \left[\frac{\mathbf{w}^{*} \mathbf{b}^{*} - \mathbf{p}^{*} \mathbf{b}^{*}}{(\mathbf{c}^{*} \mathbf{c}^{*} \mathbf{c}^{*} \mathbf{c}^{*})^{\frac{1}{2}}}, \frac{\mathbf{w}^{*} \mathbf{c}^{*} - \mathbf{w}^{*} \mathbf{b}^{*}}{(\mathbf{c}^{*} \mathbf{c}^{*} \mathbf{c}^{*})^{\frac{1}{2}}}, \frac{\mathbf{w}^{*} \mathbf{b}^{*} - \mathbf{w}^{*} \mathbf{b}^{*}}{(\mathbf{c}^{*} \mathbf{c}^{*} \mathbf{c}^{*})^{\frac{1}{2}}} \right]$ $\frac{\partial z}{\partial x} \left[\frac{(\alpha^2 + y^2 + 2)^{\frac{1}{2}}}{(\alpha^2 + y^2 + 2)^{\frac{1}{2}}} \right] + \frac{\partial z}{\partial x} \left[\frac{(\alpha^2 + y^2 + 2)^{\frac{1}{2}}}{(\alpha^2 + y^2 + 2)^{\frac{1}{2}}} \right] + \frac{\partial z}{\partial x} \left[\frac{(\alpha^2 + y^2 + 2)^{\frac{1}{2}}}{(\alpha^2 + y^2 + 2)^{\frac{1}{2}}} \right] + \frac{\partial z}{\partial x} \left[\frac{(\alpha^2 + y^2 + 2)^{\frac{1}{2}}}{(\alpha^2 + y^2 + 2)^{\frac{1}{2}}} \right] + \frac{\partial z}{\partial x} \left[\frac{(\alpha^2 + y^2 + 2)^{\frac{1}{2}}}{(\alpha^2 + y^2 + 2)^{\frac{1}{2}}} \right] + \frac{\partial z}{\partial x} \left[\frac{(\alpha^2 + y^2 + 2)^{\frac{1}{2}}}{(\alpha^2 + y^2 + 2)^{\frac{1}{2}}} \right] + \frac{\partial z}{\partial x} \left[\frac{(\alpha^2 + y^2 + 2)^{\frac{1}{2}}}{(\alpha^2 + y^2 + 2)^{\frac{1}{2}}} \right] + \frac{\partial z}{\partial x} \left[\frac{(\alpha^2 + y^2 + 2)^{\frac{1}{2}}}{(\alpha^2 + y^2 + 2)^{\frac{1}{2}}} \right] + \frac{\partial z}{\partial x} \left[\frac{(\alpha^2 + y^2 + 2)^{\frac{1}{2}}}{(\alpha^2 + y^2 + 2)^{\frac{1}{2}}} \right]$ (m2-m4)(-3)/22)(2+4+22 (my-m2) (-2)(22)(2+g+2)2 $3(3^{2_{3}}y_{1}^{4}z^{2})^{\frac{p}{2}} \left[2(w_{3}y - w_{2}z) + g(w_{1}z - w_{3}z) + 2(w_{1}z - w_{1}y) \right]$

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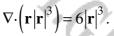
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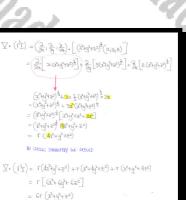
 $\mathbf{r}(x, y, z) = x\mathbf{i} + y\mathbf{j} + z\mathbf{k} \, .$

Show, with a detailed method, that



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Question 9

A Cartesian position vector is denoted by \mathbf{r} and $r = |\mathbf{r}|$.

Show that

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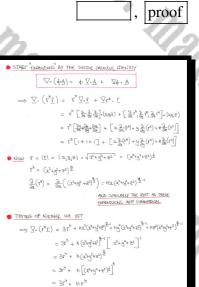
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 $\nabla \cdot \left(r^n \mathbf{r} \right) = (n+3) r'$

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= (h+3)rn As exputed

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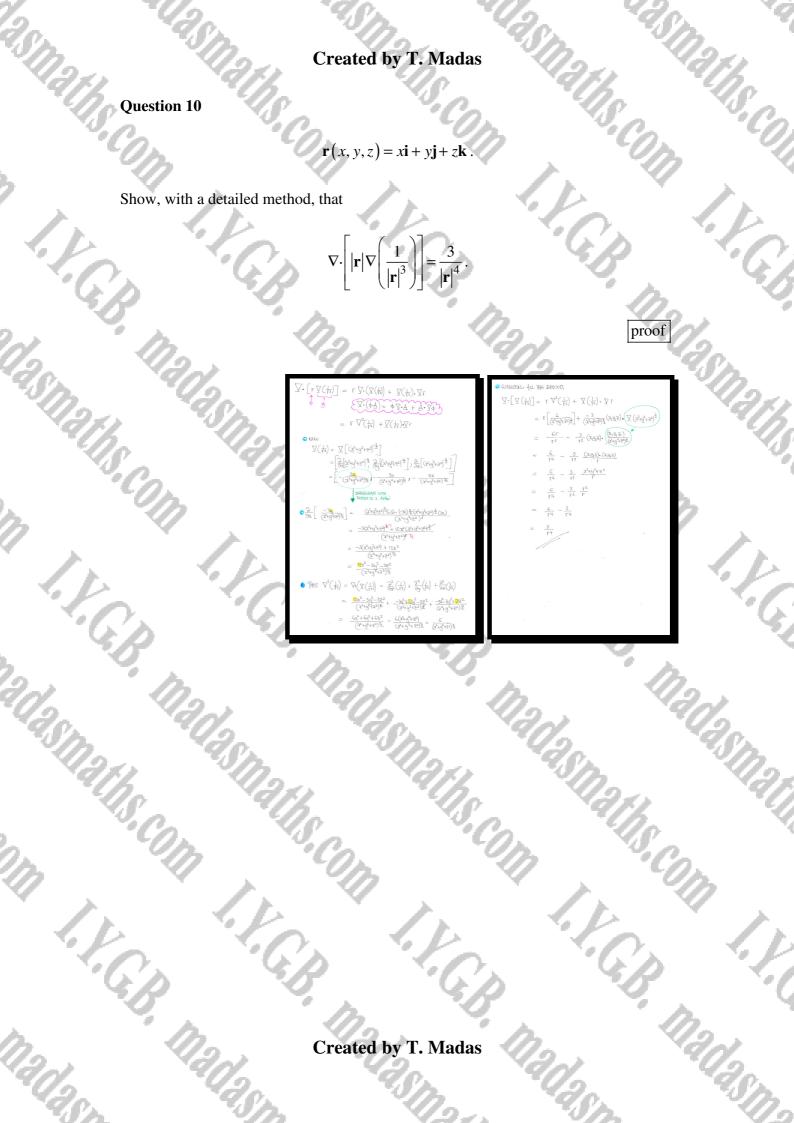
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Created by T. Madas

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$\mathbf{F}_{\mathbf{F}}$ ASTRAILS COM I. Y. C.B. MARIASINALIS.COM I. Y. C.B. MARIASIN

Question 1

A Cartesian vector is denoted by

 $\mathbf{A} = A_1 \mathbf{i} + A_2 \mathbf{j} + A_3 \mathbf{k} ,$

where $A_i = f(x, y, z), i = 1, 2, 3$

Given that A_i are differentiable functions, show that

 $\nabla \cdot \nabla \wedge \mathbf{A} = 0 \ .$





Question 2

A function φ is denoted by

$$\varphi = \varphi(x, y, z).$$

Given that φ is differentiable show that

 $\nabla_{\wedge}\nabla\varphi=\mathbf{0}.$



$$\begin{split} & \sum_{A} \sqrt{2} \dot{\Phi} = - \sum_{A} \left[\frac{2\dot{A}}{2\dot{A}} + \frac{2\dot{A}}{2\dot{A$$

 $\nabla_{\wedge}\mathbf{r}$

Question 3

A Cartesian position vector is denoted by \mathbf{r} and $r = |\mathbf{r}|$.

Determine the value of

 $\nabla \wedge \mathbf{r} = \mathbf{0}$

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 $(q_0 q_0) = \begin{pmatrix} z_0 & z_0 \\ z_$

Question 4

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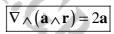
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A Cartesian position vector is denoted by \mathbf{r} and $r = |\mathbf{r}|$

Maria

Given that **a** is a constant vector, find

 $\nabla_{\wedge}(\mathbf{a}_{\wedge}\mathbf{r}).$



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(a^t) = ∆	1 1 K a ₁ a ₂ a ₃ = a y z	∑n [a₂z-a₃y, a	^g 2-015 1 010 -0157]
- (1 3 02-	્યુલ વુર-વૃત્ર	a'ri - a'r	
), a2-(-a2), a3-(.2a2 , 2a3)
= 2(a, a	2,93) = 2 <u>a</u>	// .	

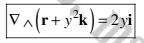
Question 5

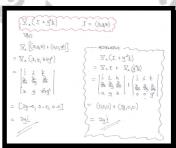
A Cartesian position vector is denoted by \mathbf{r} and $r = |\mathbf{r}|$.

Determine

 $\nabla \wedge (\mathbf{r} + y^2 \mathbf{k})$

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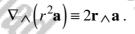


Question 6

Y.C.B.

A Cartesian position vector is denoted by \mathbf{r} and $r = |\mathbf{r}|$.

Given that \mathbf{a} is a constant vector, show that





$$\begin{split} V_{A}\left(\Gamma^{2}\underline{a}\right) &= \left| \begin{array}{ccc} \underline{i} & \underline{j} & \underline{k} \\ \frac{2}{2a} & \frac{2}{2g} & \frac{2}{3g} \\ (\overline{c}^{1}\underline{a}^{1}\underline{c}^{2}\underline{c}^{2}\underline{a}^{2}\underline{c$$

Question 7

A vector function A is defined as

 $\mathbf{A} = A_1(x, y, z)\mathbf{i} + A_2(x, y, z)\mathbf{j} + A_3(x, y, z)\mathbf{k}.$

Given that the standard Cartesian position vector is denoted by ${\boldsymbol{r}}$, show that

 $\nabla \cdot (\mathbf{A} \wedge \mathbf{r}) \equiv \mathbf{r} \cdot \nabla \wedge \mathbf{A} \; .$



Question 8

The smooth vector functions, \mathbf{A} and \mathbf{B} , are both irrotational.

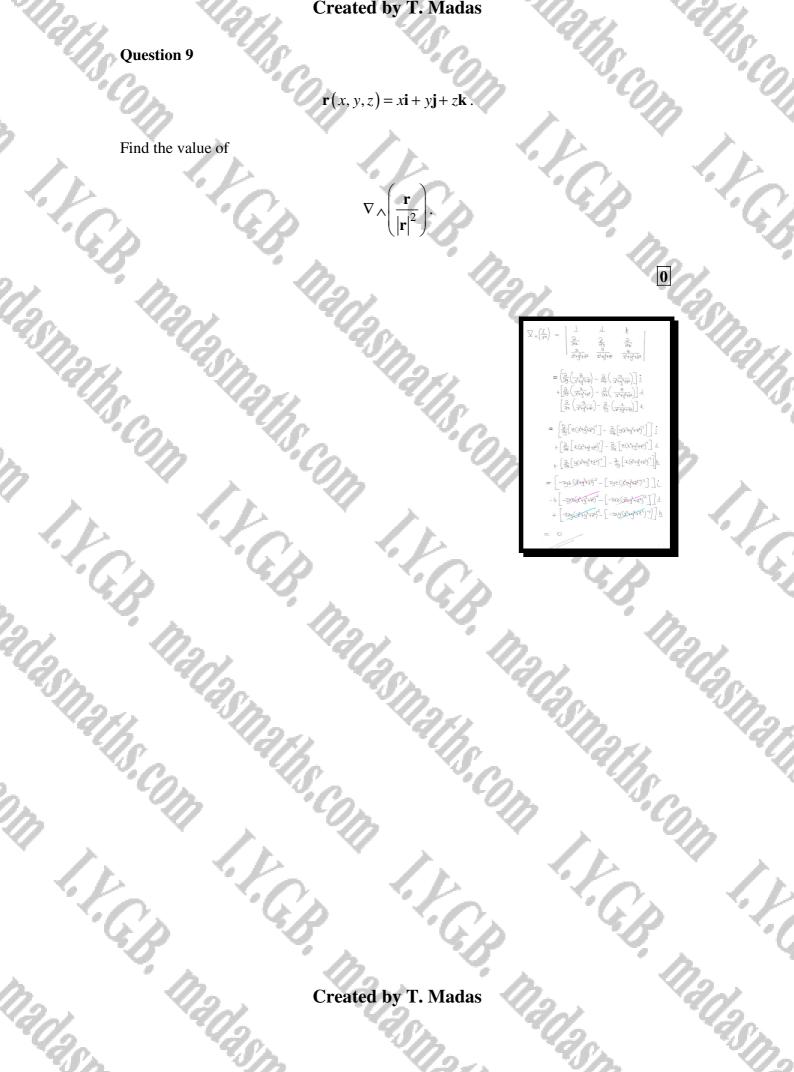
Show that $A \wedge B$ is solenoidal.



proof

 $\begin{array}{l} \text{Identify} \left(\begin{array}{c} \sum \\ \\ \end{array} \right) \left(\begin{array}{c} \sum \\ \\ \\ \\ \end{array} \right) \left(\begin{array}{c} \sum \\ \\ \\ \\ \end{array} \right) \left(\begin{array}{c} \sum \\ \\ \\ \\ \end{array} \right) \left(\begin{array}{c} \sum \\ \\ \\ \\ \end{array} \right) \left(\begin{array}{c} \sum \\ \\ \\ \\ \\ \end{array} \right) \left(\begin{array}{c} \sum \\ \\ \\ \\ \end{array} \right) \left(\begin{array}{c} \sum \\ \\ \\ \\ \end{array} \right) \left(\begin{array}{c} \sum \\ \\ \\ \\ \\ \end{array} \right) \left(\begin{array}{c} \sum \\ \\ \\ \\ \end{array} \right) \left(\begin{array}{c} \sum \\ \\ \\ \\ \end{array} \right) \left(\begin{array}{c} \sum \\ \\ \\ \\ \end{array} \right) \left(\begin{array}{c} \sum \\ \\ \\ \\ \end{array} \right) \left(\begin{array}{c} \sum \\ \\ \\ \\ \end{array} \right) \left(\begin{array}{c} \sum \\ \end{array} \right) \left(\begin{array}{c} \sum \\ \\ \end{array} \right) \left(\begin{array}{c} \sum \end{array} \right) \left(\begin{array}{c} \sum \\ \end{array} \right) \left(\begin{array}{c} \sum \end{array} \right) \left(\begin{array}{c} \end{array} \right) \left(\end{array} \right) \left(\end{array} \right) \left(\begin{array}{c} \end{array} \right) \left(\end{array} \right) \left($

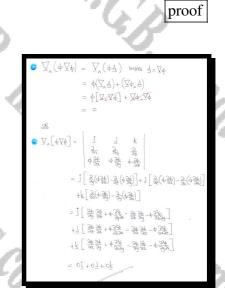
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Question 10

If $\varphi = \varphi(x, y, z)$ is a smooth function, prove that.

 $\nabla_{\wedge}(\varphi\nabla\varphi)=\mathbf{0}.$



Question 11

i C.B.

$$\mathbf{r}(x, y, z) = x\mathbf{i} + y\mathbf{j} + z\mathbf{k} \, .$$

Given that \mathbf{a} is a constant vector, find the value of

 $\nabla_{\wedge}\nabla_{\wedge}(\mathbf{r}_{\wedge}\mathbf{a}).$

$\begin{array}{llllllllllllllllllllllllllllllllllll$
$ \begin{array}{c} \sigma R \\ \underline{\Gamma}_{A} \underline{\phi} = \left \begin{array}{c} \underline{1} & \underline{J}_{A} & \underline{k} \\ \lambda_{A} & \underline{a}_{A} & \overline{a}_{A} \end{array} \right = \left[\underline{a}_{\underline{M}} \underline{\phi}_{-} \underline{a}_{\underline{1}} \underline{a}_{1} & \underline{a}_{2} \underline{a}_{-} \underline{a}_{\underline{1}} \underline{a}_{\underline{1}} \\ \underline{a}_{-} & \underline{a}_{-} \underline{a}_{-} \underline{a}_{\underline{1}} \end{array} \right = \left[\underline{a}_{\underline{M}} \underline{\phi}_{-} \underline{a}_{\underline{1}} \underline{a}_{1} & \underline{a}_{\underline{1}} \underline{a}_{-} \underline{a}_{-} \underline{a}_{\underline{1}} \underline{a}_{\underline{1}} \right] $
$\sum_{\mathbf{A}} \left(\mathbf{f}_{\mathbf{A}} \underline{\mathbf{a}} \right) = \begin{bmatrix} \frac{1}{2} & \underline{\mathbf{b}} \\ \frac{1}{2\mathbf{a}} & \underline{\mathbf{b}}_{\mathbf{a}} \\ \frac{1}{2\mathbf{a}} & \underline{\mathbf{b}} \\ \frac{1}{2\mathbf{a}} \\ \frac{1}{2\mathbf{a}} & \underline{1} \\ \frac{1}$
$= \left[-\alpha_1 - a_{1-1} - a_{2-1} - a_{3-1} - a_{3-1} \right]$ $= \left[-2\alpha_1 - 2\alpha_2 - 2\alpha_3 \right]$
$ \frac{\nabla}{2} \left[\nabla_{\mathbf{A}} \left(\hat{\Gamma}_{\mathbf{A}} \hat{\mathbf{A}}_{\mathbf{A}} \right) \right] \simeq \begin{vmatrix} \hat{\mathbf{I}} & \hat{\mathbf{I}} & \hat{\mathbf{I}} & \mathbf{k} \\ \hat{\mathbf{A}}_{\mathbf{A}} & \hat{\mathbf{A}}_{\mathbf{A}} & \hat{\mathbf{A}}_{\mathbf{A}} \\ -2a_{\mathbf{I}} & -2a_{\mathbf{I}} & -2a_{\mathbf{I}} \end{vmatrix} = 0 $

0

Question 12

The irrotational vector field \mathbf{F} is given by

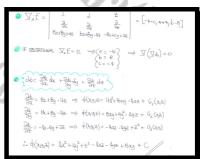
 $\mathbf{F} = (8x + 8y + az)\mathbf{i} + (bx + 8y - 4z)\mathbf{j} + (-4x + cy + 2z)\mathbf{k},$

where a, b and c are scalar constants.

Determine a smooth scalar function $\varphi(x, y, z)$ such that

 $\nabla \varphi = \mathbf{F} \, .$

 $\varphi(x, y, z) = (2x + 2y - x)^2 + \text{constant} = 4x^2 + 4y^2 + z^2 - 4xz - 4yz + 8xy + \text{constant}$



Question 13

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a) Define the vector calculus operators grad, div and curl.

A Cartesian position vector is denoted by \mathbf{r} and $r = |\mathbf{r}|$.

b) Determine the vector

 $\nabla \wedge \left[\mathbf{r} \wedge \mathbf{i} + \nabla \left(\sin e^{xyz} \right) \right].$

, [$\nabla \wedge \left[\mathbf{r} \wedge \mathbf{i} + \nabla \left(\sin e^{xyz} \right) \right] = -2\mathbf{i}$
	Sh
15	(4) GRADING of A SUBOTH READER FOLLOW $\Phi = \Phi(3, q_1 2)$ $\nabla \Phi = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{bmatrix}$ DIVERGENCE A SUBOTH WHERE FOLLS $\Sigma = (F_1, F_1, F_1)$
S	$ \nabla \cdot \mathbf{E} = \left(\begin{array}{c} \frac{1}{2k_{s}} \cdot \frac{1}{2k_{s}} \right) \left(\mathbf{f}_{1}, \mathbf{f}_{2}, \mathbf{f}_{3} \right) = \begin{array}{c} \frac{1}{2k_{s}} \cdot \frac{1}{2k_{s}} \\ \frac$
-1	b) <u>Mydry Afr & Guald</u> $ \begin{array}{c} & & \\$
	$= Y_{h} \begin{bmatrix} r, t \end{bmatrix}_{h} \begin{bmatrix} r & y_{h} \end{bmatrix} \begin{bmatrix} y_{h} \\ y_{h} \end{bmatrix}_{h} \end{bmatrix}$ $= Y_{h} \begin{bmatrix} x & y_{h} \\ x & y_{h} \end{bmatrix} \begin{bmatrix} z \\ z \end{bmatrix}$
5	$= \bigvee_{k} \left(e_{1} e_{1} e_{3} \right)$ $= \begin{vmatrix} \lambda & \lambda \\ B_{k} & B_{3} & B_{k} \\ 0 & k & -3 \end{vmatrix}$
6%	$= (-t-t_1 e_1 e_1)$ $= -2t_1$

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Question 14

The smooth functions f and \mathbf{A} are defined as

f = f(x, y, z) and $\mathbf{A} = A_1(x, y, z)\mathbf{i} + A_2(x, y, z)\mathbf{j} + A_3(x, y, z)\mathbf{k}$.

a) Define the vector calculus operators grad, div and curl with reference to f and A.

A Cartesian position vector is denoted by \mathbf{r} and $r = |\mathbf{r}|$

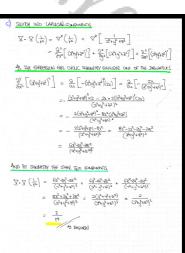
b) Determine the vector

 $\nabla \wedge [\mathbf{r} \wedge \mathbf{i} + (x+y)\mathbf{k}].$

 $\nabla \cdot \nabla \left(\frac{1}{r^2} \right) =$

c) Show that

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	2t = (発,発,影)
	THE INVERSION OF THE WOTOR FILLS A= [A, (243), J(243), A, (24,2)]
	$\overline{Y} \cdot \underline{A} = \frac{2A_{1}}{2M_{1}} + \frac{2A_{2}}{2M_{2}} + \frac{2A_{1}}{2M_{2}}$
	THE CUEL OF THE VECTOR FICE A= [A, (A4, 7), A2(3,4,2), A3(3,4,4)]
	∑_±= 1 ± €
6)	STALL BY COND X (3+3) = XA+XA
	$ \mathbb{Z}^{[\underline{1}^{\dagger}]} = \mathbb{Z}^{(\underline{1}^{\dagger}]} + \mathbb{Z}^{[\underline{1}^{\dagger}]} = \mathbb{Z}^{(\underline{1}^{\dagger})} + \mathbb{Z}^{[\underline{1}^{\dagger}]} $
	100 0 0 2mg エア 2 2 1 7 5 + 1 7 7 5
	= \[0 = 1] + [1] + []
	$= \begin{bmatrix} 1 & 2 & -1 \\ 2 & 2 & 0 \\ 2 & 2 & 0 \\ 2 & 2 & 0 \\ 2 & 2 & 0 \\ 2 & 0 & 0 \\ 2 & 0 & 0 \\ 2 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 &$
	$= (-l-l_1 \circ_1 \circ) + (l_1-l_1 \circ)$
	= (-1,-1,0)
	= - <u>i</u> - <u>j</u>



-i - j

Question 15

I.C.B.

Y.G.B. May

I.G.B.

A Cartesian position vector is denoted by \mathbf{r} and $r = |\mathbf{r}|$.

Given that **a** is a constant vector, show that

 $\nabla_{\wedge} \left[(\mathbf{a} \cdot \mathbf{r}) \mathbf{r} \right] = \mathbf{a}_{\wedge} \mathbf{r}.$

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proof

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- $= \sum_{i=1}^{n} (a_i a_j a_j) \cdot (x_i a_i a_j) \xrightarrow{i} (x_i a_j a_j)$
- $= \sum \left(a_{(2_1}+a_{2_2}+a_{3_3}) \right)_{(2_1} \left((x_1 y_1 z_3) \right)$ $= \left[\frac{2}{2_1} (a_{(2_1}+a_{(2_1)}+a_{(3_2)}) \right]_{(2_1} \left((a_{(2_1)}+a_{(2_1)}+a_{(2_2)}) \right)_{(2_1)} \left((a_{(2_1)}+a_{(2_1)}+a_{(2_2)}) \right)_{(2_1)} \left((a_{(2_1)}+a_{(2_1)}+a_{(2_2)}) \right)_{(2_1)} \left((a_{(2_1)}+a_{(2_1)}) \right)_{(2_1)} \left((a_{(2_1)}+a_{(2_1$
- $= \left(\left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{32} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} + a_{3} \right)_{A} \left(\frac{1}{2^{2}} \left(a_{12} + a_{23} \right)_{A}$
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Created by T. Madas

2017

Question 16

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The smooth functions $\mathbf{A} = \mathbf{A}(x, y, z)$, $\mathbf{B} = \mathbf{B}(x, y, z)$ and $\varphi = \varphi(x, y, z)$ are defined

 $\mathbf{A} = yz\mathbf{i} - x^2 y\mathbf{j} + xz^2 \mathbf{k} ,$ $\mathbf{B} = x^2 \mathbf{i} + yz \mathbf{j} - xy \mathbf{k}$ and $\varphi = x y z$

Find, in simplified form, expressions for

- $(\mathbf{A}\cdot\nabla)\boldsymbol{\varphi}$. a)
- b) $(\mathbf{B} \cdot \nabla) \mathbf{A}$.

 $(\mathbf{A} \wedge \nabla) \varphi$ c)

 $(\mathbf{A} \cdot \nabla) \boldsymbol{\varphi} = y^2 z^2 - x^3 y z + x^2 y z^2$

 $(\mathbf{B}\cdot\nabla)\mathbf{A} = (yz^2 - xy^2)\mathbf{i} + (-2x^3y - x^2yz)\mathbf{j} + (x^2z^2 - 2x^2yz)\mathbf{k}$ $(\mathbf{A} \wedge \nabla) \boldsymbol{\varphi} = \left(-x^3 y^2 - x^2 z^3\right) \mathbf{i} + \left(xyz^3 - xy^2 z\right) \mathbf{j} + \left(xyz^2 + x^2 y^2 z\right) \mathbf{k}$

$\underline{A} = (\underline{y}\underline{z}_{j} - \underline{x}\underline{y}_{j}, \underline{z}\underline{z}^{2}) \quad \underline{a} \quad \underline{B} = (\underline{a}_{1}^{2}\underline{y}\underline{z}_{j} - \underline{x}\underline{y})$ +(2,4,2):

- a) $(\underline{A} \cdot \underline{\nabla}) \phi = (\underline{y}_{\overline{a}_1} \underline{x}_{\overline{a}_1}^2 + \underline{z}_{\overline{a}_2}^2) \cdot (\underline{a}_{\overline{a}_2}^2 + \underline{a}_{\overline{a}_2}^2 + \underline{a}_{\overline{a}_2}^2) (\underline{x}_{\underline{a}_2}^2 + \underline{z}_{\overline{a}_2})$
- = [yz = = xg = +xz2=] (xyz) $= \widehat{hs} \stackrel{q}{=} (\widehat{shs}) - \widehat{sh} \stackrel{q}{=} (\widehat{shs}) + \widehat{sg} (\widehat{shs})$
 - = $y^2 z^2 x^2 y(xz) + xz^2(xy)$
 - = y22- xy2 + xy22

 $\left(\underbrace{\mathbb{B}}_{\mathbf{x}}, \underbrace{\mathbb{D}}_{\mathbf{x}} \right) \underbrace{\mathbb{A}}_{\mathbf{x}} = (x_{1}^{2} \underbrace{\mathbb{A}}_{\mathbf{y}} - x_{\mathbf{y}}) \underbrace{(x_{2}^{2}, x_{3}^{2}, x_{3}^{2})}_{\mathbf{x}} \underbrace{[y_{2}^{2} - x_{3}^{2}, x_{3}^{2}]}_{\mathbf{x}} \right)$

- $= \left[\underbrace{\mathcal{X}^2}_{\partial 1} + \underbrace{\mathcal{Y}^2}_{\partial y} \underbrace{\mathcal{A}_1}_{\mathcal{A}_2} \underbrace{\mathcal{A}_2}_{\partial y} \underbrace{\mathcal{A}_2}_{\mathcal{A}_2} \right] \left(\underbrace{\mathcal{Y}^2}_{\mathcal{A}_1} \underbrace{\mathcal{A}_2}_{\mathcal{A}_1} \underbrace{\mathcal{X}^2}_{\mathcal{A}_2} \right)$
- = [22 3 (42) + 42 3 (42) 24 3 (42)][
- + [22] = (-24)+45== (-24)-24== (-24)] = $+ \left[\mathcal{X}^2 \frac{1}{2\lambda} (\mathfrak{X} \mathfrak{F}^2) + \mathfrak{g}_{\mathfrak{F}} \frac{1}{2\lambda} (\mathfrak{X} \mathfrak{F}^2) - \mathfrak{X} \mathfrak{g}_{\mathfrak{F}} (\mathfrak{X} \mathfrak{F}^2) \right] \overset{\mathrm{k}}{=}$
- = [yz2-2y2, -2xy-2y2, 222-2xyz]
- $\begin{array}{c} (\underline{\mathbb{A}}_{A}\underline{\mathbf{Y}})\varphi \ = \ \left| \begin{array}{c} \underline{\mathbb{1}} & \underline{\mathbb{1}} & \underline{\mathbb{1}} \\ g_{\mathcal{B}} & -\underline{\mathbf{x}}g & \underline{\mathbf{x}}g^{2} \\ g_{\mathcal{B}}^{2} & g_{\mathcal{B}}^{2} & g_{\mathcal{B}}^{2} \end{array} \right| \ (3\,gg)$

 - $= \left[-x_{1}^{2}\frac{\partial}{\partial z} x_{2}^{2}\frac{\partial}{\partial y}\right] x_{2}^{2}\frac{\partial}{\partial x} y_{2}\frac{\partial}{\partial z} + y_{3}^{2}\frac{\partial}{\partial y} + x_{3}^{2}\frac{\partial}{\partial x}\right](x_{3}y_{2})$
 - $= \left[-x_{ij}^{2}(x_{ij}) xz^{2}(x_{ik}), xz^{2}(yz) yz(x_{ij}), yz(x_{ik}) + x_{ij}^{2}(yz)\right]$
 - = [-2y2-223, 2y23-2y22, 2y22+2y22=]

Question 17

- a) Define the vector calculus operators grad, div and curl.
- **b**) Given that $\varphi(x, y, z)$ and $\psi(x, y, z)$ are smooth functions, show that

$\nabla_{\wedge} [\varphi \nabla \psi] \equiv \nabla \varphi_{\wedge} \nabla \psi.$

c) Evaluate

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$$\nabla \wedge \left[\nabla \wedge \left[\nabla \wedge \left[\nabla \wedge \left[(x + y + z)^3 \mathbf{i} + (4x^3 - yz) \mathbf{j} + (xyz) \mathbf{k} \right] \right] \right] \right].$$

d) Use the vector function

$$\mathbf{A}(x, y, z) = (e^{x+y})\mathbf{i} + (x \sin z)\mathbf{j} + (4\sqrt{x})\mathbf{k}$$

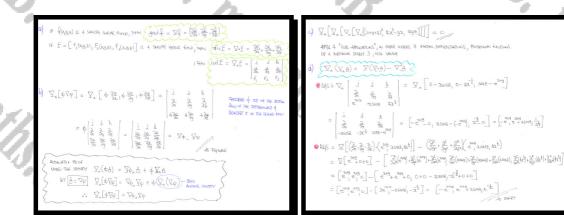
to verify the validity of the identity

$$\nabla \wedge (\nabla \wedge \mathbf{A}) \equiv \nabla (\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A}$$

$$\nabla \wedge \left[\nabla \wedge \left[\nabla \wedge \left[\nabla \wedge \left((x + y + z)^3 \mathbf{i} + (4x^3 - yz) \mathbf{j} + (xyz) \mathbf{k} \right) \right] \right] \right] = \mathbf{0}$$

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Question 18

A Cartesian position vector is denoted by \mathbf{r} and $r = |\mathbf{r}|$.

Given that f(r) is a differentiable function, show that

h.

	$\nabla \wedge [\mathbf{r} f(r)] = 0.$	- G'A -
ip ''	B CB	proof
nad	$\begin{split} & \left[\sum_{k} \left[f_{k}(t) \right] = \left \begin{array}{c} i & \pm & k \\ g_{k} & g_{k}^{2} & g_{k} \\ g_{k} & g_{k}^{2} & g_{k}^{2} \\ g_{k} & g_{k}^{2} & g_{k}^{2} \\ g_{k}^{2} & g_{k}^{2} & g_{k}^{2} & g_{k}^{2} \\ g_{k}^{2} & g_{k}^{2} \\ g_{k}^{2} & g_{k}^{2} & g_{k}^{2} & g_{k}^{2} \\ g_{k}^{2} & g_{k}^{2} & g_{k}^{2} \\ g_{k}^$	$\frac{4 \sqrt{2} \sqrt{2} \sqrt{2} \sqrt{2} + 1_{A} \sqrt{2} \sqrt{2} = \left[(\overline{0} \frac{1}{2}) \right]_{A} \nabla$
1). " "SI	$ \begin{array}{rcl} & = & & \\ & & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & & \\ & & & \\ & & & $	$\begin{array}{c} 2 \wedge \left[\frac{1}{26} \frac{1}{64} + \frac{1}{26} \frac{5}{64} \frac{1}{64} + \frac{5}{66} \frac{5}{64} \frac{1}{26} + \frac{5}{66} \frac{5}{64} \right] = \\ 1 \wedge \left[\frac{1}{26} \left[\frac{1}{66} + \frac{1}{26} \frac{1}{66} \frac{1}{26} \frac{1}{66} \frac{1}{26} \frac{1}{64} \frac{1}{26} \frac{1}{26} \frac{1}{64} \frac{1}{26} \frac{1}{26} \frac{1}{64} \right] \frac{1}{66} = \\ 1 \wedge \left[\frac{1}{26} \frac{1}$
".Com	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	$=\frac{1}{1}\frac{A_{1}^{2}}{GT}\int_{T} A_{1}A_{2}$ $= 0$ $= 0$ $M_{11} \frac{Q_{12}}{2K} = \frac{3}{2K} \left[\frac{Q_{1}^{2}}{Q_{1}^{2}} \frac{A_{2}^{2}}{Q_{1}^{2}} \right]_{T}^{2} = \frac{1}{2} \frac{A_{1}^{2}}{Q_{1}^{2}} \frac{A_{2}^{2}}{Q_{1}^{2}} \frac{A_{2}^{2}}{$
	$\begin{array}{l} \underline{\lambda} : \underline{x} \stackrel{\mathrm{d}}{\Rightarrow} - x \stackrel{\mathrm{d}}{\Rightarrow} = x \stackrel{\mathrm{d}}{\Rightarrow} - x \stackrel{\mathrm{d}}{\Rightarrow} = 0 \\ \underline{b} : \underline{y} \stackrel{\mathrm{d}}{\Rightarrow} - x \stackrel{\mathrm{d}}{\Rightarrow} = g \stackrel{\mathrm{d}}{\Rightarrow} - x \stackrel{\mathrm{d}}{\Rightarrow} = 0 \\ \overset{\mathrm{d}}{\Rightarrow} x_{4} \left[x \downarrow (\eta) \right] = 0 \end{array}$	
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Question 19

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I.F.G.p

I.V.G.B.

Given that $\mathbf{A} = \mathbf{A}(x, y, z)$ is a twice differentiable vector function, show that

 $\nabla_{\wedge} (\nabla_{\wedge} \mathbf{A}) \equiv \nabla (\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A} \, .$

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	$ \begin{array}{c} \left \end{array}{c} \right \\ \left \begin{array}{c} \left \end{array}{c} \right \\ \left \begin{array}{c} \left \begin{array}{c} \left \begin{array}{c} \left \begin{array}{c} \left \end{array}{c} \right \\ \left \end{array}{c} \\ \left \end{array}{c} \\ \left \end{array}{c} \\ \left \begin{array}{c} \left \begin{array}{c} \left \end{array}{c} \right \\ \left \end{array}{c} \right \\ \left \end{array}{c} \\ \left \\ \left \\ \left \end{array}{c} \\ \left \\ \left \\ \left \end{array}{c} \\ \left \\ \left \end{array}{c} \\ \left \\ \left \end{array}{c} \\ \left \\ \left \end{array}{c} \\ \left \end{array}{c} \\ \left \\ \left \\ \left \end{array}{c} \\ \left \\$	$\begin{split} &= \left(-\frac{2^{2}}{2^{2}} - \frac{2^{2}}{2^{2}y^{2}} - \frac{2^{2}}{2^{2}y^{2}}\right) \left(\lambda_{1} \left[\pm i \frac{1}{y^{2}} \pm \lambda_{1} \pm i\right] \\ &+ \frac{2}{2^{2}y^{2}} \left(\nabla A \right) \left[\pm i + \frac{2}{2^{2}y^{2}} \left(\nabla A \right) \pm \frac{1}{2^{2}y^{2}} \left(\nabla A \right) \pm \frac{1}{2^{2}y^{2}} \left(\nabla A \right) \pm \frac{1}{2^{2}y^{2}} \left(\frac{1}{y^{2}} + \frac{1}{2^{2}y^{2}}\right) \left(\lambda_{1} \left[\lambda_{2} \right] \lambda_{1}\right) + \left(\frac{2}{2^{2}y^{2}} + \frac{2}{2^{2}y^{2}}\right) \left(\frac{1}{y^{2}} + \frac{1}{2^{2}y^{2}}\right) \left(\frac{1}{y^{2}} + \frac{1}{2^{2}y^{2}} + \frac{1}{2^{2}y^{2}}\right) \left(\lambda_{1} \left[\lambda_{2} \right] \lambda_{1}\right) + \left(\frac{2}{2^{2}y^{2}} + \frac{2}{2^{2}y^{2}} + \frac{1}{2^{2}y^{2}}\right) \left(\frac{1}{y^{2}} + \frac{1}{2^{2}y^{2}} + \frac{1}{2^{2}y^{$
naths asmal	$= \left(\frac{\partial \lambda_{a}}{\partial \partial \partial$	$ \begin{array}{c} \mbox{Altrouhny:} \\ & \overbrace{\Delta \cap_{n}}^{A} \left(\left\{ \begin{array}{c} B_{n}, \varsigma \right\} \right) = \left(\left\{ \Delta \left\{ \varsigma \right\} \right\} \right\} = \left(\left\{ \delta \left\{ \varsigma \right\} \right\} \right\} \\ & \hline \\ \\ & \hline \\ \\ \\ & \hline \\ \\ & \hline \\ \\ & \hline \\ \\ \\ \hline \\ \\ & \hline \\ \\ \hline \\ \\ \\ \hline \\ \\ \hline \\ \\ \hline \\ \\ \hline \\ \hline$
	$\begin{split} &= \left[\left(-\frac{2A_{2}}{2N} - \frac{2A_{2}}{2N} - \frac{2A_{3}}{2N} - \frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} \right] \underline{k} \\ &= \left(-\frac{2}{2N} - \frac{2}{2N} - \frac{2}{2N} \right) A_{1} \underline{1} + \left(-\frac{2}{2} - \frac{2}{2N} - \frac{2}{2N} - \frac{2}{2N} \right) A_{2} \underline{k} \\ &+ \frac{2}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} + \frac{2A_{3}}{2M} \right] \underline{1} + \frac{2}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} \right] \underline{k} \\ &+ \frac{2}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} + \frac{2A_{3}}{2M} \right] \underline{1} + \frac{2}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} \right] \underline{k} \\ &+ \frac{2}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} \right] \underline{1} + \frac{2}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} \right] \underline{k} \\ &+ \frac{2}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} \right] \underline{1} + \frac{2}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} \right] \underline{k} \\ &+ \frac{2}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} \right] \underline{1} + \frac{2}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} \right] \underline{k} \\ &+ \frac{2}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} \right] \underline{k} \\ &+ \frac{2A_{3}}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} \right] \underline{k} \\ &+ \frac{2A_{3}}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} \right] \underline{k} \\ &+ \frac{2A_{3}}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} \right] \underline{k} \\ &+ \frac{2A_{3}}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} \right] \underline{k} \\ &+ \frac{2A_{3}}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} \right] \underline{k} \\ &+ \frac{2A_{3}}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} \right] \underline{k} \\ &+ \frac{2A_{3}}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} \right] \underline{k} \\ &+ \frac{2A_{3}}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} \right] \underline{k} \\ &+ \frac{2A_{3}}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} \right] \underline{k} \\ &+ \frac{2A_{3}}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} \right] \underline{k} \\ &+ \frac{2A_{3}}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2N} \right] \underline{k} \\ &+ \frac{2A_{3}}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2M} \right] \underline{k} \\ &+ \frac{2A_{3}}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2M} \right] \underline{k} \\ &+ \frac{2A_{3}}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2M} \right] \underline{k} \\ &+ \frac{2A_{3}}{2M} \left[\frac{2A_{3}}{2N} + \frac{2A_{3}}{2M} \right] \underline{k} \\ &+ \frac{2A_{3}}{2M} \left[$	
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proof

 $\underline{\mathbf{A}}(\underline{\nabla}\cdot\underline{\nabla}) - \underline{\nabla}(\underline{\mathbf{A}}\cdot\underline{\nabla}) = (\underline{\mathbf{A}}$ $\underline{A}^{2} \nabla = \nabla (\underline{\nabla} \cdot \underline{A}) - \nabla^{2} \underline{A} = (\underline{A} \cdot \underline{\nabla}) \nabla \underline{A} = (\underline{A} \cdot \underline{A} \cdot \underline{A} \cdot \underline{\nabla}) \nabla \underline{A} = (\underline{A} \cdot \underline{A} \cdot \underline{A} \cdot \underline{A} \cdot \underline{A} + \underline{A} \cdot \underline{A} + \underline{A} \cdot \underline{A} + \underline{A} \cdot \underline{A} + \underline{A$

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Question 20

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I.V.G.p

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 $\mathbf{r}(x, y, z) = x\mathbf{i} + y\mathbf{j} + z\mathbf{k} \, .$

Show that $\mathbf{r} f(|\mathbf{r}|)$ is irrotational, where $f(|\mathbf{r}|)$ is differentiable function of $|\mathbf{r}|$.

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F.G.B.

2011

f(r) K DI V. (fr) $\nabla_{\mathbf{A}}(\phi\underline{A}) = \nabla\phi_{\mathbf{A}}\underline{A} + \phi(\nabla_{\mathbf{A}}\underline{A})$ 1,4⊻ =

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I.F.G.B.

 $=\left(\frac{\partial f}{\partial t},\frac{\partial f}{\partial y},\frac{\partial f}{\partial y}\right)_{\wedge}(a_{i}y_{i})$

<u> [(x+g+z)t]</u>

= ____(i)

흙'흙' 븕 $\frac{\chi}{(\chi_{14}^{2}+\eta_{1}^{2}+\eta_{2}^{2})^{\frac{1}{2}}}(\chi_{14}^{2}+\eta_{1$

ŀ.C.p

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Question 21

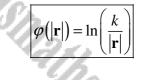
Y.G.B.

The vector function E satisfies

$$\mathbf{E} = \frac{\mathbf{r}}{|\mathbf{r}|^2}, \ |\mathbf{r}| \neq 0,$$

where $\mathbf{r}(x, y, z) = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$.

Show that **E** is irrotational, and find a smooth scalar function $\varphi(|\mathbf{r}|)$, with $\varphi(k) = 0$, so that $\mathbf{E} = -\nabla \varphi(|\mathbf{r}|)$.



 $\overline{E} = -\frac{\Gamma}{\Gamma^2} = -\frac{(3_1 y_1 z_2)}{\lambda^2 + y_1^2 + z_2} = \left[\frac{\chi}{\lambda^4 + y_1^2 + z_2} + \frac{y_1}{\lambda^4 + y_1^2 + z_2} + \frac{\chi}{\lambda^2 + y_1^2 + z_2} \right]$ ©∑_E = a (2+43+22)" y (2+42+24)" z (2+4) = [[-2yz(2+y+z2)]+2yz(2+y+z2)] + 1 [-212(249322)2+212(2+9+22)-+ k [-224 (23497+22) + 224 (23497+23)2 = 01+01+0k Ø E = -∑¢ $-\left(\frac{\partial \phi}{\partial x},\frac{\partial \phi}{\partial y},\frac{\partial \phi}{\partial z}\right) = \left(\frac{\pi}{x^2 \psi^2 t^2},\frac{y}{x^2 \psi^2 t^2},\frac{z}{x^2 \psi^2 t^2}\right)$ $\frac{\partial \varphi}{\partial x} = -\frac{x}{x^2 + y^2 + z^2} + \frac{\partial \varphi}{\partial y} = -\frac{y}{x^2 + y^2 + z^2} + \frac{\partial \varphi}{\partial z} = -\frac{z}{x^2 + y^2 + z^2}$
$$\begin{split} \varphi &= -\frac{1}{2} \ln(x^2 + y^2 + z^2) + f(y_1 z) \\ \varphi &= -\frac{1}{2} \ln(x^2 + y^2 + z^2) + G(y_1 z) \end{split}$$
=> F(g,z)= G(x,z)= #(x,y) = conzernant? $\left(\varphi = -\frac{1}{2} \ln (x^2 + g^2 + z^2) + H(xy) \right)$

- $\begin{array}{l} \bullet & \stackrel{*}{\rightarrow} & \displaystyle \varphi(x; g_i g_i) = h \underbrace{\left[\frac{1}{y^{2+} (y^{2} + g_i) \xi_i} \right]}_{k} + \log h_i \stackrel{'}{=} & \displaystyle h_1 \left(\frac{1}{k} \right) + \; \operatorname{constand}_{k} \\ & \displaystyle \varphi(f) = h_1 \left(\frac{1}{k} \right) + \; \operatorname{constand}_{k} \end{array}$
 - $\begin{array}{c} (q) = 0 & = 0 \\ (q) = 0 \\ (q)$

Question 22

A Cartesian position vector is denoted by \mathbf{r} and $r = |\mathbf{r}|$.

Given that **a** is a constant vector, show that

 $\nabla \wedge \left(\mathbf{a} \wedge \frac{\mathbf{r}}{r^3} \right)$

- Z a a $\begin{array}{l} & \\ \text{NOTE THAT} & \left(\underbrace{B}, \underbrace{\nabla} \right) \underline{A} \end{array} = \\ & \left(\underbrace{B}, \underbrace{B_1}_{M_1} + \underbrace{B_2}_{M_2} + \underbrace{B_3}_{M_2} \underbrace{B_4}_{M_1} \right) \underline{A} \\ & = \underbrace{B, \underbrace{B_4}_{M_2} + \underbrace{B_3}_{M_2} \underbrace{B_4}_{M_2} + \underbrace{B_3}_{M_2} \underbrace{B_4}_{M_2} \\ & \\ \end{array}$ $\left(\frac{1}{2}, \nabla\right) = + \frac{1}{2} \left(\nabla \cdot \mathbf{e}\right) - \left(\underline{e} \cdot \nabla\right) \frac{1}{27} = - \underline{e} \left(\overline{\nabla} \cdot \frac{1}{27}\right) =$ LOOKING AT GOOD OF THE SURVING THEIR SIGNOATTH $\frac{1}{(\overline{\Omega})} \sum_{ijk} (p - \left(\frac{1}{(ij)}\right) \sum_{ijk} (p - \left(\frac{1}{(ij)}\right) \sum_{ijk} (p - \frac{1}{(ij)}\right) = \left(\frac{1}{(ij)}\right) \sum_{ijk} (p - \frac{1}{(ij)} (p - \frac{1}{(ij)}) = \frac{1}{(ij)} (\overline{\Omega} \cdot \overline{n}) = \frac{1}{(ij)} (\overline{\Omega} \cdot \overline{n})$ $\left[-0^{-1}\frac{\partial}{\partial}\left(\frac{(\tilde{z}_{1}^{+}d_{1}^{+}d_{2}^{+})^{\frac{1}{2}}}{2}\right)_{1}-0^{-1}\frac{\partial}{\partial x}\left(\frac{(\tilde{z}_{1}^{+}d_{1}^{+}d_{2}^{+})^{\frac{1}{2}}}{2}\right)_{1}-0^{-1}\frac{\partial}{\partial x}\left(\frac{(\tilde{z}_{1}^{+}d_{2}^{+})^{\frac{1}{2}}}{2}\right)_{1}-0^{-1}\frac{\partial}{\partial x}\left(\frac{(\tilde{z}_{1}^{+}d_{2}^{+})^{\frac{1}{2}}}{2}\right)_{1}-0^{-1}\frac{\partial}{\partial x}\left(\frac{(\tilde{z}_{1}^{+}d_{2}^{+})^{\frac{1}{2}}}{2}\right)_{1}-0^{-1}\frac{\partial}{\partial x}\left(\frac{(\tilde{z}_{1}^{+}d_{2}^{+})^{\frac{1}{2}}}{2}\right)_{1}-0^{-1}\frac{\partial}{\partial x}\left(\frac{(\tilde{z}_{1}^{+}d_{2}^{+})^{\frac{1}{2}}}{2}\right)_{1}-$
- $\begin{cases} \lambda_{234} \\ \frac{2}{344} \left[\frac{\alpha}{(2^{\frac{1}{3}}q^{\frac{1}{3}}k_{2})k_{1}} \right] = \frac{(\alpha^{\frac{1}{3}}q^{\frac{1}{3}}k_{2})^{\frac{1}{3}} \alpha(\underline{\nu})(\alpha^{\frac{1}{3}}q^{\frac{1}{3}}k_{2})^{\frac{1}{3}}}{(\alpha^{\frac{1}{3}}q^{\frac{1}{3}}k_{2})^{\frac{1}{3}}} \frac{\alpha^{\frac{1}{3}}q^{\frac{1}{3}}k_{2}^{\frac{1}{3}}}{(\alpha^{\frac{1}{3}}q^{\frac{1}{3}}k_{2})^{\frac{1}{3}}} \\ \end{array}$ $\begin{array}{l} & \int \partial x \left[\frac{(x_x, d_y^2 + k_y^2) \overline{g}}{\partial \theta} \right] & = - \frac{2\pi d}{2} \left(\frac{x_x^2 + d_y^2 + k_y^2 + k_y^2}{\partial \theta} \right)_{\overline{X}} & = - \frac{(x_y, d_y^2 + k_y^2) \overline{g}}{\partial \theta} \\ & \int \partial x r \left[- \frac{1}{2} \frac{x_y^2 - d_y^2 - k_y^2}{\partial \theta} \right]_{\overline{X}} & = - \frac{(x_y, d_y^2 + k_y^2) \overline{g}}{\partial \theta} \\ & \int \partial x r r \left[- \frac{1}{2} \frac{x_y^2 - k_y^2 - k_y^2}{\partial \theta} \right]_{\overline{X}} & = - \frac{(x_y, d_y^2 + k_y^2) \overline{g}}{\partial \theta} \\ & = - \frac{(x_y, d_y^2 - k_y^2) \overline{g}}{\partial \theta} \\ & = - \frac{(x_y, d_y^2 - k_y^2) \overline{g}}{\partial \theta} \\ & = - \frac{(x_y, d_y^2 - k_y^2) \overline{g}}{\partial \theta} \\ & = - \frac{(x_y, d_y^2 - k_y^2) \overline{g}}{\partial \theta} \\ & = - \frac{(x_y, d_y^2 - k_y^2) \overline{g}}{\partial \theta} \\ & = - \frac{(x_y, d_y^2 - k_y^2) \overline{g}}{\partial \theta} \\ & = - \frac{(x_y, d_y^2 - k_y^2) \overline{g}}{\partial \theta} \\ & = - \frac{(x_y, d_y^2 - k_y^2) \overline{g}}{\partial \theta} \\ & = - \frac{(x_y, d_y^2 - k_y^2) \overline{g}}{\partial \theta} \\ & = - \frac{(x_y, d_y^2 - k_y^2) \overline{g}}{\partial \theta} \\ & = - \frac{(x_y, d_y^2 - k_y^2) \overline{g}}{\partial \theta} \\ & = - \frac{(x_y, d_y^2 - k_y^2) \overline{g}}{\partial \theta} \\ & = - \frac{(x_y, d_y^2 - k_y^2) \overline{g}}{\partial \theta} \\ & = - \frac{(x_y, d_y^2 - k_y^2) \overline{g}}{\partial \theta} \\ & = - \frac{(x_y, d_y^2 - k_y^2) \overline{g}}{\partial \theta} \\ & = - \frac{(x_y, d_y^2 - k_y^2) \overline{g}}{\partial \theta} \\ & = - \frac{(x_y, d_y^2 - k_y^2) \overline{g}}{\partial \theta} \\ & = - \frac{(x_y, d_y^2 - k_y^2) \overline{g}}{\partial \theta} \\ & = - \frac{(x_y, d_y^2 - k_y^2) \overline{g}} \\ & = - \frac{(x_y, d_y^2 - k_y^2) \overline{g}}{\partial \theta} \\ & = - \frac{(x_y, d_y^2 - k_y^2) \overline{g} \\ & = - \frac{(x_y, d_y^2 - k_y^2) \overline{g} \\ & = - \frac{(x_y, d_y^2 - k_y^2) \overline{g} \\ & = - \frac{(x_y, d_y^2 -$ $\begin{cases} \frac{\partial z}{\partial x} \left[\frac{z}{2} \left[\frac{(x_1^2 + y_1^2 + z_2)z}{2} \right] = -3\pi Z \left[(x_1^2 + y_1^2 + z_2)^2 \right] = -\frac{3\pi Z}{2} \left[\frac{(x_1^2 + y_1^2 + z_2)^2}{2} \right] \end{cases}$
- $\left[-q, \frac{q_1^2 u^2 u^2}{(2^4 v_1^2 u^2)^2}, q, \frac{5 u g}{(2^4 v_1^2 v_1^2)}, q, \frac{5 u g}{(2^4 v_1^2 v_1^2)^2} \right] + \left[a, \frac{5 u}{(2^4 v_1^2 v_1^2)^2}, -a, \frac{3^2 3^2 t t^2}{(2^4 v_1^2 v_1^2)^2}, q, \frac{3 u}{(2^4 v_1^2 v_1^2)^2} \right] + \left[a, \frac{1}{2^4 v_1^2}, \frac{3 u}{(2^4 v_1^2 v_1^2)^2}, \frac{3 u}{(2^4 v_1^2 v_1^2)^2} \right] + \left[a, \frac{1}{2^4 v_1^2}, \frac{3 u}{(2^4 v_1^2 v_1^2)^2} \right] + \left[a, \frac{1}{2^4 v_1^2}, \frac{3 u}{(2^4 v_1^2 v_1^2)^2} \right] + \left[a, \frac{1}{2^4 v_1^2}, \frac{3 u}{(2^4 v_1^2 v_1^2)^2} \right] + \left[a, \frac{1}{2^4 v_1^2}, \frac{3 u}{(2^4 v_1^2 v_1^2)^2} \right] + \left[a, \frac{1}{2^4 v_1^2}, \frac{3 u}{(2^4 v_1^2 v_1^2)^2} \right] + \left[a, \frac{1}{2^4 v_1^2}, \frac{3 u}{(2^4 v_1^2 v_1^2)^2} \right] + \left[a, \frac{1}{2^4 v_1^2}, \frac{3 u}{(2^4 v_1^2 v_1^2)^2} \right] + \left[a, \frac{1}{2^4 v_1^2}, \frac{3 u}{(2^4 v_1^2 v_1^2)^2} \right] + \left[a, \frac{1}{2^4 v_1^2}, \frac{3 u}{(2^4 v_1^2 v_1^2)^2} \right] + \left[a, \frac{1}{2^4 v_1^2}, \frac{3 u}{(2^4 v_1^2 v_1^2)^2} \right] + \left[a, \frac{1}{2^4 v_1^2} \right] + \left[a,$ + $\left[a_3 \frac{3\alpha_2}{(2^2+y^3)\xi^2}\right]_{\Sigma}^{\Sigma}$, $a_3 \frac{3y_2}{(2^2+y^3+\xi^2)\xi}$
- $\left(\frac{a_{3}z-a_{3}z}{(z^{4}+q_{3}^{2}+z^{2})_{z}^{2}},\frac{a_{3}z-a_{1}z}{(z^{2}+q_{1}^{2}+z^{2})_{z}^{2}},\frac{a_{1}y-a_{3}z}{(z^{2}+q_{3}^{2}+z^{2})_{z}^{2}}\right)$ $\frac{\underline{x}}{\Gamma^3} = \frac{(\underline{x}_1\underline{u}_1\underline{z})}{(\underline{x}^2 + (\underline{x}^2\underline{u}_1\underline{z}))^{\frac{1}{2}}}$
- $\frac{(x_{1}^{2}+y_{2}^{2}+z_{1})_{2}^{2}}{(x_{1}^{2}+y_{2}^{2}+z_{1})_{2}^{2}} \quad \frac{(y_{1}^{2}-q_{1}^{2}+z_{1})_{2}}{(y_{1}^{2}-q_{1}^{2}+z_{1})_{2}^{2}} \quad \frac{(y_{1}^{2}-q_{1}^{2}-z_{1})_{2}}{(y_{1}^{2}-q_{1}^{2}+z_{1})_{2}^{2}}$ $= \frac{2q_1(2^2y_1^2y_2^2) - (q_1^2-q_2x)(q_2) + q_1(q_1^2y_2^2) + (q_2x-q_1z)(xz)}{(2^2y_1^2+q_2^2)} = \frac{2q_1(2^2y_1^2+q_2^2) - 3q_1y_2^2}{(2^2y_1^2+q_2^2) - 3q_1y_2^2} + 3q_2y_2^2 + 3q_2y_2^2}$
- $= \frac{d_1(3t^2-g^2-\xi^2) + 3a_1\pi y + 3a_3\pi\xi}{(\pi^2+g^2+\xi^2)^{\frac{1}{2}}}$ $\boxed{\begin{array}{c} \begin{array}{c} \frac{1}{2} \left(\frac{\partial g}{\partial x} - \frac{\partial g}{\partial y} \right)}{\partial x} - \frac{1}{2\pi} \left[\frac{\partial g}{\partial x} - \frac{\partial g}{\partial x} \right] = \frac{(2M_{1}^{2}M_{1}^{2})^{2}}{(2M_{1}^{2}-M_{1}^{2}-M_{1}^{2})} \\ \left(\frac{\partial g}{\partial x} - \frac{\partial g}{\partial x} + \frac{\partial g}{\partial x} \right)^{2} \left(\frac{\partial g}{\partial x} - \frac{\partial g}{\partial x} + \frac{\partial g}{\partial x} \right) = \frac{(2M_{1}^{2}M_{1}^{2})^{2}}{(2M_{1}^{2}-M_{1}^{2}-M_{1}^{2})} \\ \left(\frac{\partial g}{\partial x} - \frac{\partial g}{\partial x} + \frac{\partial g}{\partial x} + \frac{\partial g}{\partial x} \right)^{2} \left(\frac{\partial g}{\partial x} + \frac{\partial g}{\partial x} + \frac{\partial g}{\partial x} + \frac{\partial g}{\partial x} \right) \\ = \frac{(2M_{1}^{2}M_{1}^{2}-M_{1}^{2}-M_{1}^{2})^{2}}{(2M_{1}^{2}-M_{1}^{2}-M_{1}^{2}-M_{1}^{2})^{2}} \\ \left(\frac{\partial g}{\partial x} + \frac{\partial g}{\partial x} \right) \\ = \frac{(2M_{1}^{2}M_{1}^{2}-M_{1}^{2}-M_{1}^{2})^{2}}{(2M_{1}^{2}-M_{1}^{2}-M_{1}^{2}-M_{1}^{2})^{2}} \\ \left(\frac{\partial g}{\partial x} + \frac{\partial$ $a_{2\overline{k}} - a_{3}(y) + a_{2}(x^{2}y^{2}y^{2}z^{2}) + (a_{1}y - a_{2}x^{2}y^{2}z^{2}) = 2a_{2}(x^{2}y^{2}y^{2}z^{2}) - 3a_{2}z^{2} + 3a_{3}a_{3} + \frac{1}{2}a_{3}z_{3} - 3a_{4}z^{2}$

I.V.G.B

 $\frac{q_2(-x^2+2y^2-x^2)+3q_3z_9+3q_1z_9}{(x^2+y^2+z^2)^5}$ $\underbrace{(\mathbf{i})}_{(\mathbf{i}^{2}+q_{1}^{2}+2t^{2})} : \frac{a_{1}(2t^{2}+q_{1}^{2}+2t^{2})}{(t^{2}+q_{1}^{2}+2t^{2})^{\frac{1}{2}}} \left\{ \underbrace{(\mathbf{j})}_{(\mathbf{i}^{2}+q_{1}^{2}+2t^{2})} \frac{a_{1}(-t^{2}+q_{1}^{2}+2t^{2})}{(t^{2}+q_{1}^{2}+2t^{2})^{\frac{1}{2}}} \frac{a_{1}(2t^{2}+q_{1}^{2}+2t^{2})}{(t^{2}+q_{1}^{2}+2t^{2})^{\frac{1}{2}}} \right\} \frac{a_{1}(2t^{2}+q_{1}^{2}+2t^{2})}{(t^{2}+q_{1}^{2}+2t^{2})^{\frac{1}{2}}} \left\{ \underbrace{(\mathbf{j})}_{(\mathbf{i}^{2}+q_{1}^{2}+2t^{2})} \frac{a_{1}(t^{2}+q_{1}^{2}+2t^{2})}{(t^{2}+q_{1}^{2}+2t^{2})^{\frac{1}{2}}} \right\} \frac{a_{1}(t^{2}+q_{1}^{2}+2t^{2})}{(t^{2}+q_{1}^{2}+2t^{2})^{\frac{1}{2}}} \left\{ \underbrace{(\mathbf{j})}_{(\mathbf{i}^{2}+q_{1}^{2}+2t^{2})} \frac{a_{1}(t^{2}+q_{1}^{2}+2t^{2})}{(t^{2}+q_{1}^{2}+2t^{2})} \frac{a_{1}(t^{2}+q_{1}^{2}+2t^{2})}{(t^{2}+q_{1}^{2}+2t^{2})^{\frac{1}{2}}} \left\{ \underbrace{(\mathbf{j})}_{(\mathbf{i}^{2}+q_{1}^{2}+2t^{2})} \frac{a_{1}(t^{2}+q_{1}^{2}+2t^{2})}{(t^{2}+q_{1}^{2}+2t^{2})} \frac{a_{1}(t^{2}+q_{1}^{2}+2t^{2})}{(t^{2}+q_{1}^{2}+2t^{2})} \frac{a_{1}(t^{2}+q_{1}^{2}+2t^{2})}{(t^{2}+q_{1}^{2}+2t^{2})}} \left\{ \underbrace{(\mathbf{j})}_{(\mathbf{i}^{2}+q_{1}^{2}+2t^{2})} \frac{a_{1}(t^{2}+q_{1}^{2}+2t^{2})}{(t^{2}+q_{1}^{2}+2t^{2})} \frac{a_{1}(t^{2}+q_{1}^{2}+2t^{2})}{(t^{2}+q_{1}^{2}+2t^{2})}} \frac{a_{1}(t^{2}+q_{1$ $\frac{a_1(-x^2-y^4-z^2) + 3a_1x^4+3a_2xy +3a_2z}{(-x^2+y^3+z^2)^{\frac{5}{2}}}$ a2(-2-y2-22) + 3a, ay - 3a, y + 3a, 2y + 3a, 2y $= \frac{a_{y}(-x^{2}+y^{2}+z^{2}) + 3a_{y}x_{2} + 3a_{y}y_{2}^{2} + 3a_{y}z^{2}}{(x^{2}+y^{2}+z^{2})^{\frac{N}{2}}}$ $\frac{3 \alpha \Big(\alpha_1 \chi + \alpha_2 g + c_3 z \Big) - \alpha_1 (\chi^2 + g^2 + z^2)}{(\chi^2 + g^2 + z^2)^{\frac{5}{2}}}$ $\frac{3g(a_1x+a_2g+a_3z)}{(x^1+q^2+z^2)^{\frac{5}{2}}}$ $=\frac{3 \chi \left(a_1 \chi_1 + a_2 (j_1 + a_3 z)}{\left(\chi^2 + y^2 + 2^2\right) \frac{4}{2}} - \frac{a_1}{\left(\chi^2 + y^2 + 2^2\right) \frac{4}{2}}$ $= \frac{3 \frac{a_1}{a_1} \left(\frac{a_1}{a_1} + \frac{a_2}{a_2} + \frac{a_3}{a_2} \right)}{\left(\frac{a_1}{a_1} + \frac{a_2}{a_2} + \frac{a_3}{a_2} \right)} - \frac{a_2}{\left(\frac{a_1}{a_1} + \frac{a_2}{a_2} + \frac{a_3}{a_2} \right)}$ $\frac{32(a_12+a_2y+a_3z)}{(2^2+y^2+z^2)^{\frac{5}{2}}} - \frac{a_3}{(\overline{r}+y^2+z^2)^{\frac{5}{2}}}$ $= \frac{\partial \sigma}{\partial r_1} - \frac{(\xi_1 \rho_1 \chi) (\xi_1 \rho_{12} \rho_{11} \rho_{12}) (\xi_1 \rho_{12} \rho_{12})}{2 \cdot r} = \frac{\partial \sigma}{2 \cdot r}$ $= \frac{3q(a_1a_2,a_3)(a_3,a_3)}{r^3} - \frac{a_3}{r^3}$ $= \frac{32(\alpha_1\rho_1,\alpha_2)(2,\eta_1^{-1}\theta)}{\Gamma^2} - \frac{\alpha_3}{\Gamma^3}$ $= \frac{3\alpha_{L} \alpha_{*} \Gamma}{\Gamma^{5}} = \frac{\alpha_{L}}{\Gamma^{3}}$ $= \frac{3g\underline{a} \cdot \underline{\Gamma}}{\underline{\Gamma}^2} - \frac{a_2}{3}$ $\frac{1}{12} = \frac{1 \cdot A \mathcal{B}}{1 \cdot A} = \frac{1}{1 \cdot A}$
$$\begin{split} & \left[\frac{c_{r}}{\Omega} - \frac{2 - \frac{2}{12} \delta^{2}}{1 - \frac{2}{12} \delta^{2}} - \frac{\frac{\delta^{2}}{12} - \frac{\delta^{2}}{12}}{1 - \frac{\delta^{2}}{12} \delta^{2}} + \frac{\delta}{12} - \frac{2 - \frac{\delta}{12} \delta^{2}}{1 - \frac{\delta}{12} \delta^{2}} - \frac{\delta}{12} - \frac{\delta}{12} \delta^{2} - \frac{$$

 $\frac{1}{(\bar{x}^{2}t_{1}^{2}\bar{x}^{2})^{\frac{1}{2}}} \left[-\frac{\alpha_{2}}{3}xy + \alpha_{3}\frac{2}{3}xz - \alpha_{1}(y_{1}^{2}+z^{2}-2z^{2}), -\alpha_{3}\frac{3}{3}xy + \alpha_{3}\frac{3}{3}yz - \alpha_{2}(x_{1}^{2}-2y_{1}^{2}+z^{2}), -\alpha_{1}\frac{3}{3}xz + \alpha_{2}\frac{3}{3}yz - \alpha_{3}(y_{1}^{2}+z^{2}-2z^{2}), -\alpha_{3}\frac{3}{3}xy + \alpha_{3}\frac{3}{3}yz - \alpha_{3}(y_{1}^{2}+z^{2}-2z^{2}), -\alpha_{3}\frac{3}{3}xy + \alpha_{3}\frac{3}{3}xy - \alpha_{3}\frac{3}{3}xy - \alpha_{3}\frac{3}{3}xy + \alpha_{3}\frac{3}{3}xy - \alpha_{3}\frac{3}{3}xy - \alpha_{3}\frac{3}{3}xy + \alpha_{3}\frac{3}{3}xy - \alpha_{3}\frac{3}{3}xy + \alpha_{3}\frac{3}{3}xy - \alpha_{3}\frac{3}{3}xy -$

 $\begin{array}{c} \underbrace{ \prod_{i=1}^{k} \quad \nabla_{\mathbf{x}} \left(\begin{array}{c} \mathbf{g} \\ \mathbf{x} \end{array} \right)_{i} = \underbrace{ \left(\mathbf{g}_{\mathbf{x}} \left(\begin{array}{c} 2 \mathbf{x} \mathbf{g} \end{array} \right)_{i} + \mathbf{g}_{\mathbf{x}} \mathbf{g}_{\mathbf{x}} \mathbf{g}_{\mathbf{x}} - \mathbf{q} \left(\mathbf{x}^{2} \mathbf{y}^{2} \mathbf{y}^{2} \right)_{i} \mathbf{q}_{\mathbf{x}} \mathbf{g}_{\mathbf{x}} \mathbf{g}$

 $\left[\begin{array}{ccc} \underline{s}_{2} & -\overline{s} & \frac{1}{2s} \cdot \underline{b} \\ \frac{1}{s} & -\overline{s} & \frac{1}{s} \cdot \underline{b} \\ \frac{1}{s} & -\overline{s} & -\overline{s} & \frac{1}{s} \cdot \underline{b} \\ \frac{1}{s} & -\overline{s} & -\overline{s} & \frac{1}{s} \cdot \underline{b} \\ \frac{1}{s} & -\overline{s} & -\overline{s} & -\overline{s} \\ \frac{1}{s} & -\overline{s} \\ \frac{1}{s} & -\overline{s} & -\overline{s} \\ \frac{1}{s} & -\overline{s} \\ \frac{1}{s} & -\overline{s} & -\overline{s} \\ \frac{1}{s} \\ \frac{1}{s} & -\overline{s} \\ \frac{1}{s}$

 $\left[\frac{3\varrho_{1}}{r_{1}},\frac{q_{2}}{r_{1}},\frac{1}{r_{1}}\right] - \left[-5\frac{1}{r_{1}}\frac{2}{r_{1}},\frac{1}{r_{2}}\frac{2}{r_{1}},\frac{1}{r_{2}}\frac{2}{r_{1}},\frac{1}{r_{2}}\frac{2}{r_{1}}\right] =$

 $= -\frac{L_2}{2^{\overline{Q} \star \overline{L}}} \left(a^{\dagger} \beta^{\dagger} \xi \right) - \frac{L_2}{T} \left(a^{t\dagger} a^{5\dagger} a^{3} \right)$

<u><u><u>Sa</u>.<u>r</u></u> <u>r</u> <u>a</u> <u>r</u> <u>r</u> <u>a</u> <u>4</u> <u>Repu</u>e</u>

 $\frac{\partial e^{e_{i}}(\mu e^{e_{i}}+x_{j}u_{j}^{2})}{2^{\frac{1}{2}(4e_{i}^{2}\mu_{j}^{2}\chi_{j}^{2})}} - \frac{\mu\left(\underline{\mu}_{j}e^{e_{i}}+\underline{\mu}_{j}\underline{\mu}_{j}^{2}\right)}{2^{\frac{1}{2}(4e_{i}^{2}\mu_{j}^{2}\chi_{j}^{2})}}, \\ \frac{\partial e^{i}_{j}(\mu_{j}^{2}\mu_{j}^{2}\chi_{j}^{2})}{2^{\frac{1}{2}(4e_{j}^{2}\mu_{j}^{2}\chi_{j}^{2})}} - \frac{\mu\left(\underline{\mu}_{j}e^{i}_{j}+\underline{\mu}_{j}\underline{\mu}_{j}^{2}\right)}{2^{\frac{1}{2}(4e_{j}^{2}\mu_{j}^{2}\chi_{j}^{2})}}, \\ \frac{\partial e^{i}_{j}(\mu_{j}^{2}\mu_{j}^{2}\chi_{j}^{2})}{2^{\frac{1}{2}(4e_{j}^{2}\mu_{j}^{2}\chi_{j}^{2})}} - \frac{\mu\left(\underline{\mu}_{j}e^{i}_{j}+\underline{\mu}_{j}\underline{\mu}_{j}^{2}\right)}{2^{\frac{1}{2}(4e_{j}^{2}\mu_{j}^{2}\chi_{j}^{2})}}, \\ \frac{\partial e^{i}_{j}(\mu_{j}^{2}\mu_{j}^{2}\chi_{j}^{2}\chi_{j}^{2})}{2^{\frac{1}{2}(4e_{j}^{2}\mu_{j}^{2}\chi_{j}^{2})}} - \frac{\mu\left(\underline{\mu}_{j}e^{i}_{j}+\underline{\mu}_{j}\underline{\mu}_{j}^{2}\right)}{2^{\frac{1}{2}(4e_{j}^{2}\mu_{j}^{2}\chi_{j}^{2})}}, \\ \frac{\partial e^{i}_{j}(\mu_{j}^{2}\chi_{j}^{$

 $\begin{array}{c} \widehat{\sigma}\left(\overline{\lambda},\frac{h_{2}}{T}\right)= & \widehat{\sigma}\left(-\frac{g_{2}}{2}\left(\frac{g_{2}}{2}\right)\frac{g_{2}}{2}\left(\frac{g_{2}}{2}\left(\frac{h_{2}}{2}+h_{2}\right)^{2}\right) + \left(\frac{g_{1}}{2}+\frac{h_{2}}{2}\right)^{2}\left(\frac{g_{1}}{2}+\frac{h_{2}}{2}+h_{2}\right)^{2}\right) \\ \end{array} \\ \end{array}$

L.C.h.

proof

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V.C.B. Mada

 $\frac{\underline{\alpha}}{\underline{\alpha}} = \frac{\underline{\gamma} \cdot \underline{\alpha}}{\underline{\gamma} \cdot \underline{\gamma}} = \frac{\underline{\alpha}}{\underline{\gamma} \cdot \underline{\gamma}}$

Question 23

$$\nabla_{\wedge} (\mathbf{A}_{\wedge} \mathbf{B}) \equiv (\mathbf{B} \cdot \nabla) \mathbf{A} + (\nabla \cdot \mathbf{B}) \mathbf{A} - (\mathbf{A} \cdot \nabla) \mathbf{B} - (\nabla \cdot \mathbf{A}) \mathbf{B}.$$

- a) Given that $\mathbf{A} = \mathbf{A}(x, y, z)$ and $\mathbf{B} = \mathbf{B}(x, y, z)$ are smooth vector functions, use index summation notation to prove the validity of the above vector identity.
- **b**) Verify the validity of the vector identity if



LAPLAC. $\nabla \cdot \nabla \varphi \equiv \nabla^2 \varphi$ Halfstallstall CASINGUIS COM I. Y. C.B. MARIASINANS.COM I. Y. C.B. MARIASIN

Question 1

I.G.B.

I.C.B.

I.G.B.

A Cartesian position vector is denoted by \mathbf{r} and $r = |\mathbf{r}|$.

F.G.B.

Determine the value of

div $\left[\operatorname{grad} \left(\frac{1}{r} \right) \right], r \neq 0.$

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I.F.C.B.

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Question 2

A smooth scalar field is denoted by $\varphi = \varphi(x, y, z)$ and a smooth vector field is denoted by $\mathbf{A} = \mathbf{A}(x, y, z)$.

a) Use the standard definitions of vector operators to show that

$$\nabla \cdot (\varphi \mathbf{A}) = \nabla \varphi \cdot \mathbf{A} + \varphi \nabla \cdot \mathbf{A}$$

b) Given further that f and g are functions of x, y and z, whose second partial derivatives exist, deduce that

 $\nabla \cdot (f \nabla g - g \nabla f) = f \nabla^2 g - g \nabla^2 f.$

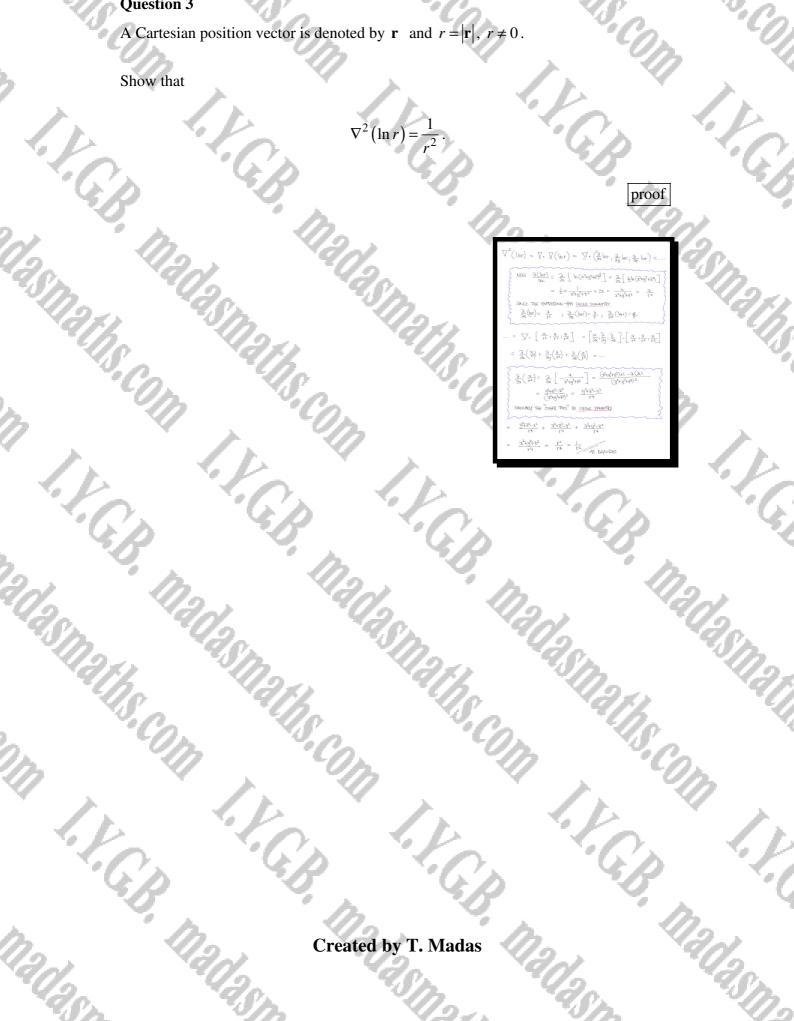
4	DIFINI- SOME PUMPITTIES FUST
	$\underline{\mathcal{A}} = \left(\mathcal{A}_1(\varphi_{ijk}, s) \right) \mathcal{A}_2(x_i y_i s) \int_{\mathcal{A}_2} (x_i y_i s) ds \varphi = \varphi(x_i y_i s)$
	THIN WE HADE
	$\nabla \cdot (\phi \underline{A}) = \nabla \cdot (\phi A_{(1)} \phi A_{(2)} \phi A_{0})$
	$= \left(\frac{2}{32}, \frac{2}{33}, \frac{2}{33}\right) \cdot \left(\psi A_{1,1} \psi A_{2,2} \psi A_{3}\right)$
	BY THE PRODUCT RULE
	$=\frac{2}{9}(\phi Y^{1})+\frac{2}{9}(\phi Y^{2})+\frac{2}{9}(\phi Y^{2})$
	= 發4+++ 發 + 發4+++ 要+ 禁七+ + 教
	$= \begin{bmatrix} \frac{\partial b}{\partial t} A_1 + \frac{\partial b}{\partial t} A_2 + \frac{\partial b}{\partial t} A_3 \end{bmatrix} + \Phi \begin{bmatrix} \frac{\partial c}{\partial A_1} + \frac{\partial b}{\partial t} + \frac{\partial b}{\partial t} \end{bmatrix}$
	$= \left(\begin{array}{c} \underbrace{\partial \varphi} \\ \partial \varphi \end{array} \right) \underbrace{\partial \varphi} \\ \Rightarrow \underbrace{\partial \varphi } \\ \Rightarrow \underbrace{\partial \varphi} \\ \Rightarrow \underbrace{\partial \varphi} \\ \Rightarrow \underbrace{\partial \varphi } \\$
	= Vd·A + + V·A
b)	PROCEED USING THE RESULT OF PHET (a)
	$ \overline{\Delta} \cdot \left[\left\{ \underline{\lambda}^{3} - \vartheta \underline{\lambda} t \right\} \right] = \overline{\Delta} \cdot \left[\left\{ \underline{\lambda}^{3} \right\} - \overline{\Delta} \cdot \left[\vartheta \underline{\lambda} t \right] \right] $
-	$\overline{\Delta} f \cdot \overline{\Delta}^3 + \underbrace{d}{\Delta} \cdot \overline{\Delta}^3 - \overline{\Delta}^3 \cdot \overline{\Delta} f - \underbrace{\partial}{\Delta} \cdot \overline{\Delta} f$
=	$\underline{\nabla} \xi - \underline{\nabla} g + \int \underline{\nabla} g^2 - \underline{\nabla} \xi - \underline{\nabla} g - g \underline{\nabla}^2 \xi$
u.	$\frac{f \overline{Y}^2}{9} - 9 \overline{Y}^2 f$
	· · · · · · · · · · · · · · · · · · ·

, proof

Question 3

A Cartesian position vector is denoted by \mathbf{r} and $r = |\mathbf{r}|, r \neq 0$.

Show that



Question 4

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i G.B.

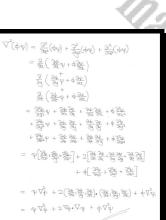
It is given that $\varphi = \varphi(x, y, z)$ and $\psi = \psi(x, y, z)$ are twice differentiable functions.

Show, with a detailed method, that

 $\nabla^2(\varphi\psi) = \psi \nabla^2 \varphi + 2\nabla \varphi \cdot \nabla \psi + \varphi \nabla^2 \psi.$

"Cp

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na

proof



Question 6

K.C.

It is given that

 $\varphi(x, y, z) = z + \sinh x \sin y \, .$

a) Verify that φ is a solution of Laplace's equation

 $\nabla^2 \varphi = 0.$

b) Hence find a vector field **F**, so that

 $\nabla \cdot \mathbf{F} = 0$ and $\nabla \wedge \mathbf{F} = \mathbf{0}$.

c) Verify that F found in part (b) is solenoidal and irrotational.

(ay)= sunho sing = ¢(Xy) $(-song) = -\phi(a_ig)$ $= \phi(\alpha_{ij}) - \phi(\alpha_{ij}) + c$ b) $\nabla^2_{\phi} = \Sigma(\Sigma_{\phi}) = 0$ (Div (Grad of)=0) 4-(WARTINY) $\mathbb{Z}^{\nu}\left(\mathbb{Z}\phi\right) = \mathcal{O}^{\nu} - \left(\mathbb{D}(\mathcal{D}(\mathcal{D}^{\nu})) \right)$ $: \nabla \varphi = \left(\frac{\partial \varphi}{\partial x}, \frac{\partial \varphi}{\partial y}, \frac{\partial \varphi}{\partial z} \right) = \left[\text{cashasmy}, \text{sinhacosy}, 1 \right]$: <u>F</u> = [ichassing unbacasi] = <u>F</u> : y]+ ==[sunhx cosy] + ==[] $\overline{\omega} = (0,0,0)$: IRROTATIONA

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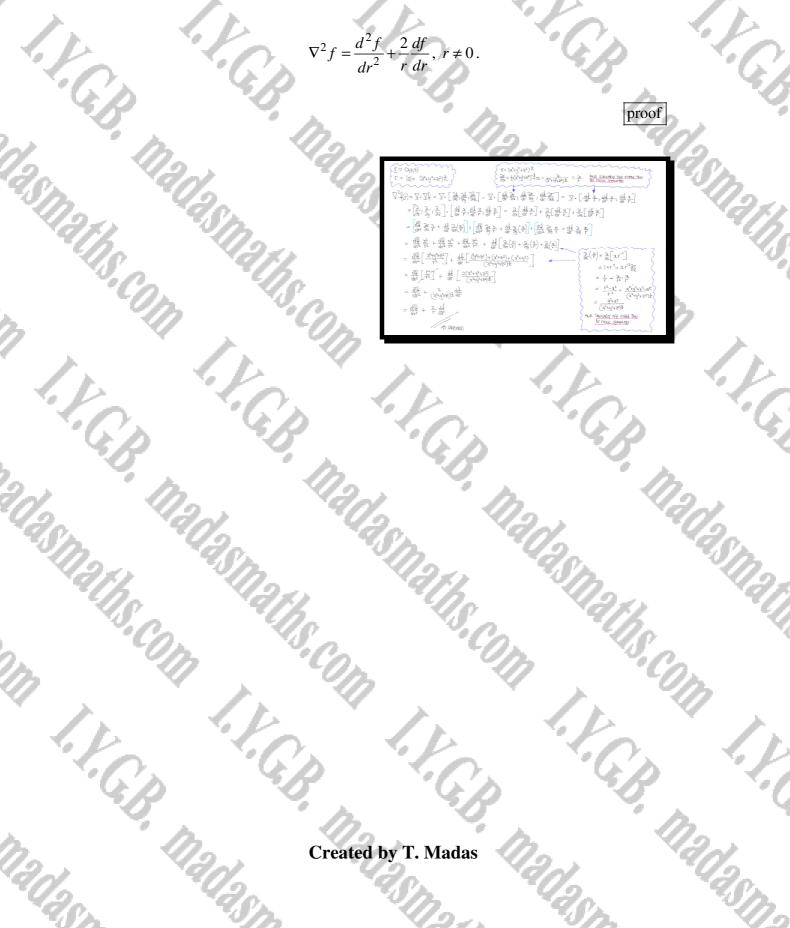
 $\mathbf{F} = (\cosh x \sin y)\mathbf{i} + (\sinh x \cos y)\mathbf{j} + \mathbf{k}$

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Question 7

A Cartesian position vector is denoted by \mathbf{r} and $r = |\mathbf{r}|$.

Given that f(r) is a twice differentiable function, show that

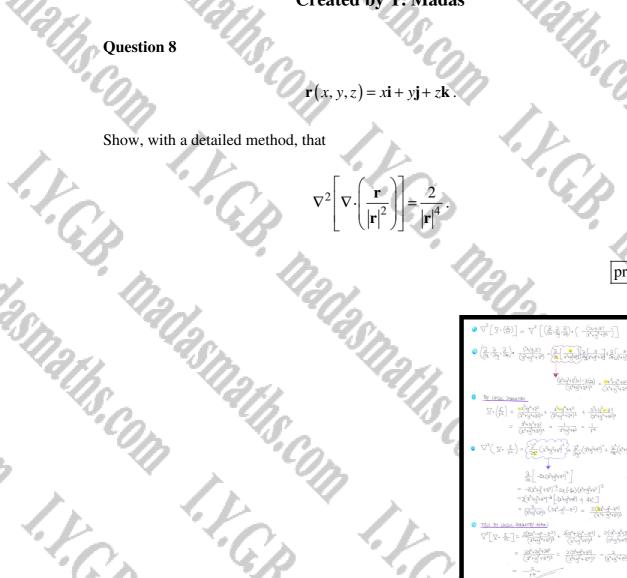


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Question 8

>

$$\mathbf{r}(x, y, z) = x\mathbf{i} + y\mathbf{j} + z\mathbf{k} \, .$$





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Question 9

The scalar function φ is given below in terms of the non zero constants λ and μ .

 $\varphi(x, y, z) = e^x \sin(\lambda y + \lambda z) \cos(\mu y - \mu z).$

Given that

 $\nabla \cdot (\nabla \varphi) = 0,$

show, with a detailed method, that $\lambda^2 + \mu^2 = \frac{1}{2}$.



- $(\mathfrak{sy-y})_{20}(\mathfrak{sR+y})\mathfrak{mz}^{\mathcal{L}}_{9}=(\mathfrak{s}_{|\mathcal{Y}|}\mathfrak{c})\varphi$ BEDRY SW(A+B) = SUNACOSB + COSASUNB SUN(A-B) = SUNACOSB- COSASUNB SUN(A-B) = SUNACOSB- COSASUNB
- Sm(A+B) +Sm(A-B) = 25mAcosB $A \log B \equiv \frac{1}{2} \sin(A + B) + \frac{1}{2} \sin(A - B)$
- Hence $\left(d_{[2]}(s) = \frac{1}{2} e_{s}^{2} \operatorname{en}\left[(k+3) \overline{a} + (\overline{y}-k) \overline{s} \right] + \frac{1}{2} e_{s}^{2} \operatorname{en}\left[(\overline{y}-k) \overline{g} + (\overline{y}+k) \overline{s} \right] \right)$
- $+ \left[\frac{1}{2} \left(g_{(+1)} \right) \cos \left(g_{(+1)} \right) + \frac{1}{2} \left(g_{(+1)} \right) + \frac{1}{2} \left(g_{(+1)} \right) \cos \left(g_{(+1)} \right) + \frac{1}{2} \left(g_{(+1)} \right) + \frac{1}{$ $= \frac{1}{2} \left[\left[s(\eta, \Omega + y(\eta, \Omega) + y(\eta, \Omega) + \frac{1}{2} s(\eta, \Omega) + \eta(\eta, \Omega) \right] 2 \cos(\eta, \Omega) \frac{1}{2} \frac{1}{2} \right] + \frac{1}{2} \left[\left[s(\eta, \Omega) + y(\eta, \Omega) + \eta(\eta, \Omega) \right] 2 \cos(\eta, \Omega) \frac{1}{2} \frac{1}{2} \right]$
- $\boxed{ \mathbf{\nabla} \cdot \mathbf{\nabla} \mathbf{\varphi} } = \frac{1}{2} e_{\text{SM}}^{2} \left[(\underline{\lambda} + \mathbf{y}) \mathbf{y} + (\mathbf{\lambda} \mathbf{y}) \mathbf{z} \right] + \frac{1}{2} e_{\text{SM}}^{2} \left[(\mathbf{\lambda} \mathbf{y}) \mathbf{y} + (\mathbf{\lambda} + \mathbf{y}) \mathbf{z} \right]$ $-\frac{1}{2} \frac{e^2}{2} (j+k)^2 \frac{e^{-j}}{2} \left[(j+k)^2 + (j-k)^2 \right] - \frac{1}{2} \frac{e^2}{2} (j-k)^2 \frac{e^{-j}}{2} \frac{e^{-j}}{2} \left[(j-k)^2 + (j+k)^2 \right]$ $\left[\underbrace{\mathbb{E}}_{\left(q+k\right)} + \underbrace{\mathbb{E}}_{\left(q-k\right)} \operatorname{Imz}_{\mathcal{S}} \left(q+k\right)^{2} \oplus \underbrace{\mathbb{E}}_{\left(q-k\right)} + \underbrace{\mathbb{E}}_{\left(q+k\right)} + \underbrace{\mathbb{E}}_{\left(q+k\right)} \operatorname{Imz}_{\mathcal{S}} \left(q+k\right)^{2} \oplus \underbrace{\mathbb{E}}_{\left(q+k\right)} \right) \right]$
 - $= \frac{1}{2} e^{2} \sin \left[\left(\frac{1}{2} + \gamma \right) g + \left(\lambda \gamma \right) \overline{g} \right] \left[\left(\left(\frac{1}{2} + \gamma \right)^{2} \left(\lambda \gamma \right)^{2} \right) \right] \\ + \frac{1}{2} e^{2} \sin \left[\left(\frac{1}{2} \gamma \right) g + \left(1 + \gamma \right) \overline{g} \right] \left[\left(1 \left(\lambda \gamma \right)^{2} \left(\lambda + \gamma \right)^{2} \right) \right]$

 $: \frac{1}{2} e^{2k} Suh \left[(0, \mu)y + (0, \mu)z \right] \left[(-\lambda^2 - 2k \mu - \mu^2 - \lambda^2 + 2k \mu - \mu^2 \right] \\ + \frac{1}{2} e^{2k} Suh \left[(0, \mu)y + (0, \mu)z \right] \left[(-\lambda^2 + 2k \mu - \mu^2 - \lambda^2 - 2k \mu - \mu^2 \right]$

proof

- $= \frac{1}{2} \frac{e^{\alpha}}{e^{\alpha}} sm \left[(\lambda + \gamma)y + (\lambda \gamma)z \right] \left[(-2\lambda^{2} 2\gamma^{2}) \right]$ $+ \frac{1}{2} \frac{e^{\alpha}}{e^{\alpha}} sm \left[(\lambda \gamma)y + (\lambda + \gamma)z \right] \left[(-2\lambda^{2} 2\gamma^{2}) \right]$
- $\begin{bmatrix} \frac{1}{2}e^{2x}(1-2\lambda^2-2\beta^2) \left[Sin \left[(\frac{1}{2}+\gamma)\frac{1}{3}+(\frac{1}{2}+\gamma)\frac{1}{2} \right] + Sin \left[(\frac{1}{2}+\gamma)\frac{1}{3}+(\frac{1}{2}+\gamma)\frac{1}{2} \right] \\ e^{2x}(1-2\lambda^2-2\gamma^2) \frac{1}{4}(2\gamma)\frac{1}{4}(2\gamma)\frac{1}{4} \\ \end{bmatrix}$

 - $\# \Psi(\lambda_{i}\mu) = (-2\lambda^2 2\mu^2)$
 - = 4 SOUTION IF $1-2\lambda^2-2\mu^2=0$ I.F $2\lambda^2+2\mu^2=1$

Question 10

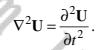
It is given that

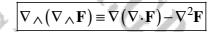
 $\mathbf{A} \wedge (\mathbf{B} \wedge \mathbf{C}) \equiv \mathbf{B} (\mathbf{A} \cdot \mathbf{C}) - (\mathbf{A} \cdot \mathbf{B}) \mathbf{C} \,.$

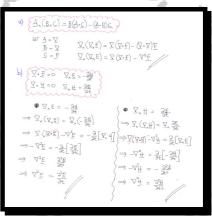
a) Use the above identity to find a simplified expression for ∇∧(∇∧F), where F is a smooth vector field.

The smooth vector fields E and H, satisfy the following relationships.

- $\nabla \cdot \mathbf{E} = 0$
- $\nabla \wedge \mathbf{E} = -\frac{\partial \mathbf{H}}{\partial t}$
- $\nabla \cdot \mathbf{H} = 0$
- $\nabla \wedge \mathbf{H} = \frac{\partial \mathbf{E}}{\partial t}$
- b) Show that E and H, satisfy the wave equation







Question 11

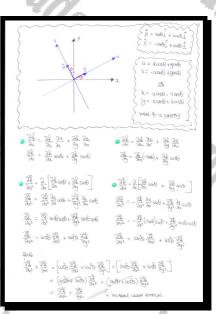
F.C.B.

I.F.G.p.

The Laplacian operator ∇^2 in the standard two dimensional Cartesian system of coordinates is defined as

 $\nabla^2() \equiv \frac{\partial^2}{\partial x^2}() + \frac{\partial^2}{\partial y^2}().$

Show that the two dimensional Laplacian operator is invariant under rotation.



F.C.B.

proof

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Question 12

It is given that if \mathbf{F} is a smooth vector field, then

$$\nabla_{\wedge} (\nabla_{\wedge} \mathbf{F}) = \nabla (\nabla \cdot \mathbf{F}) - \nabla^2 \mathbf{F}.$$

a) By using index summation notation, or otherwise, prove the validity of the above vector identity.

Maxwell's equations for the electric field E and magnetic field B, satisfy

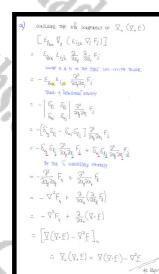
$$\nabla \cdot \mathbf{E} = \frac{\rho}{\varepsilon_0}, \quad \nabla_{\wedge} \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}, \quad \nabla \cdot \mathbf{B} = 0 \quad \text{and} \quad \nabla_{\wedge} \mathbf{B} = \mu_0 \mathbf{J} + \mu_0 \varepsilon_0 \frac{\partial \mathbf{E}}{\partial t},$$

where ρ is the electric charge density, **J** is the current density, and μ_0 and ε_0 are positive constants.

b) Show that $\frac{\partial \rho}{\partial t} + \nabla \cdot \mathbf{J} = 0$.

c) Given further that $\rho = 0$ and $\mathbf{J} = \mathbf{0}$, show also that

 $\nabla^2 \mathbf{E} = \mu_0 \varepsilon_0 \frac{\partial^2 \mathbf{E}}{\partial t^2}$ and $\nabla^2 \mathbf{B} = \mu_0 \varepsilon_0 \frac{\partial^2 \mathbf{B}}{\partial t^2}$.



 $\begin{array}{l} \left\{ \begin{array}{c} \left\{ \begin{array}{c} \left\{ X_{k} \right\} \\ \left\{ X_{$

$$\begin{split} & \text{SumMark streams over } \left(\widehat{\mathbf{x}} \right) \\ & \widehat{\mathbf{y}} \otimes \widehat{\mathbf{y}} = \widehat{\mathbf{x}} - \widehat{\mathbf{y}} \\ & \widehat{\mathbf{y}} = \widehat{\mathbf{x}} \\ & \widehat{\mathbf{y}} \otimes \widehat{\mathbf{y}} \\ & \text{other two out on the kerne fournal} \\ & \xrightarrow{\mathbf{y}} \left(\widehat{\mathbf{y}}, \widehat{\mathbf{y}} \right) = \widehat{\mathbf{y}} \otimes \widehat{\mathbf{y}} \\ & \xrightarrow{\mathbf{y}} \left(\widehat{\mathbf{y}}, \widehat{\mathbf{y}} \right) = \widehat{\mathbf{y}} \\ & \text{ for the town of of herr (a)} \\ & \xrightarrow{\mathbf{y}} \left(\widehat{\mathbf{y}}, \widehat{\mathbf{y}} \right) = \widehat{\mathbf{y}} \otimes \widehat{\mathbf{y}} \\ & \xrightarrow{\mathbf{y}} \left(\widehat{\mathbf{y}}, \widehat{\mathbf{y}} \right) = \widehat{\mathbf{y}} \otimes \widehat{\mathbf{y}} \\ & \xrightarrow{\mathbf{y}} \left(\widehat{\mathbf{y}}, \widehat{\mathbf{y}} \right) = \widehat{\mathbf{y}} \otimes \widehat{\mathbf{y}} \\ & \xrightarrow{\mathbf{y}} \left(\widehat{\mathbf{y}}, \widehat{\mathbf{y}} \right) \\ & \xrightarrow{\mathbf{y}} \left(\widehat{\mathbf{y}}, \widehat{\mathbf{y}} \right) = \widehat{\mathbf{y}} \otimes \widehat{\mathbf{y}} \\ & \xrightarrow{\mathbf{y}} \left(\widehat{\mathbf{y}}, \widehat{\mathbf{y}} \right) = \widehat{\mathbf{y}} \otimes \widehat{\mathbf{y}} \\ & \xrightarrow{\mathbf{y}} \left(\widehat{\mathbf{y}}, \widehat{\mathbf{y}} \right) \\ & \xrightarrow{\mathbf{y}} \left(\widehat{\mathbf{y}}, \widehat{\mathbf$$

proof

Question 13

E.G.A

.K.C.

Show that the Laplacian operator in the standard two dimensional Polar system of coordinates is given by

 $\nabla^{2}() \equiv \frac{\partial^{2}}{\partial r^{2}}() + \frac{1}{r}\frac{\partial}{\partial r}() + \frac{1}{r^{2}}\frac{\partial^{2}}{\partial \theta^{2}}().$

proof $= \cos^2 \theta + \frac{34}{2} - \cos^2 \theta + \frac{1}{2} - \frac{34}{2} + \frac{1}{2} - \frac{1}{2} \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2}$ $\int \frac{\partial^2 \mathcal{E}}{2\partial \theta} \, \theta_{H} \mathcal{L} + \frac{\partial^2}{\partial \theta} \, \theta_{L} \omega_{0} \int \frac{\partial \mathcal{H} \mathcal{E}}{z_{1}} +$ $\frac{\delta \sigma_{\text{constraint}}}{\delta \sigma_{\text{constraint}}} = \frac{\delta \sigma_{\text{constraint}}}{\delta \sigma_{\text{constraint}}}} = \frac{\delta \sigma_{\text{constraint}}}{\delta \sigma_{\text{constraint}}} = \frac{\delta \sigma_{\text{constraint$ • 34 = 34 3r + 34 39 $+ \frac{5m\theta \cos \theta}{r^2} \frac{2\phi}{2\theta} + \frac{\sin^2 \theta}{r^2} \frac{3\theta}{302}$ = 31 34 + 34 39 $\frac{\partial \mathcal{L}}{\partial \mathcal{J}} + \frac{\partial \mathcal{L}}{\partial \mathcal{J}} + \frac{\partial \mathcal{L}}{\partial \mathcal{J}} + \frac{\partial \mathcal{L}}{\partial \mathcal{J}} + \frac{\partial \mathcal{L}}{\partial \mathcal{J}} \frac{\partial \mathcal{L}}{\partial \mathcal{J}}$ $\frac{\Im h}{\Im \varphi} \left(\frac{(\overline{x}_{i}, \overline{a}_{j})}{x} \right) + \frac{\Im h}{\Im h} \left(-\frac{\Im x}{a} \right) \frac{(\mu \frac{3}{2})}{x} = \frac{(\overline{x}_{j}, \overline{a}_{j})}{x} \frac{\Im h}{2\varphi} - \left(\frac{3}{a} \times \frac{3\mu A_{j}}{a} \right) \frac{\Im h}{2\varphi}$ $\frac{3k^2}{26} + \frac{7k^2}{24} + \frac{3k^2}{24} + \frac{3k^2}{24} + \frac{7k^2}{24} + \frac{7k^2}{24} + \frac{3k^2}{24} +$ $\frac{2}{Q^2 + g^2 t} \frac{24}{\theta^2} = -\frac{9}{t^2 + g^2} \frac{24}{\theta^2} = -\frac{1}{t} \frac{\cos \theta}{\theta^2} \frac{24}{\theta^2} = -\frac{1}{t^2} \frac{\cos \theta}{\theta^2} \frac{24}{\theta^2}$ $\begin{bmatrix} \frac{\partial \phi}{\partial x} = & \frac{\partial \phi}{\partial x} - & \frac{\partial \phi}{\partial x} \frac{\partial \phi}{\partial x} \end{bmatrix} \quad \text{or 4 oriented $\left[\frac{\partial}{\partial x} = & \frac{\partial \phi}{\partial x} - & \frac{\partial \phi}{\partial x} \frac{\partial}{\partial x} \right] $$ $\frac{\partial \varphi_{0}}{\partial \psi} = \frac{\partial \varphi_{0}}{\partial \psi} \frac{\partial \varphi_{0}}{\partial \psi} = \frac{\partial \varphi_{0}}{\partial \psi} + \frac{\partial \varphi_{0}}{\partial \psi} + \frac{\partial \varphi_{0}}{\partial \psi} \frac{\partial \varphi_{0}}{\partial \psi} + \frac{\partial \varphi_{0}}{\partial \psi} \frac{\partial \varphi_{0}}{\partial \psi}$ $\frac{\widehat{g_{1}}}{\widehat{g_{1}}} = \frac{\Im_{4}}{\widehat{g_{1}}} \left(\frac{(\overline{g_{1}}, \overline{h_{1}})}{\widehat{g_{1}}} \right) + \frac{\Im_{6}}{\widehat{g_{1}}} \left(\frac{\chi}{\chi} \times \frac{\iota + \frac{g_{2}}{\chi}}{(} \right) = -\frac{(\overline{g_{2}}, \overline{h_{1}})}{\widehat{g_{1}}} \frac{\Im_{4}}{\widehat{g_{1}}} + -\frac{\Im_{6}}{\widehat{g_{1}}} \left(\frac{\chi}{\pi} \frac{\pi_{1}, \overline{h_{2}}}{\pi_{\pi}} \right)$ $= \operatorname{sh}_{\theta} \frac{2}{3} \left(\operatorname{sh}_{\theta} \frac{2}{3} \right) + \operatorname{sh}_{\theta} \frac{2}{3} \left(\operatorname{colo}_{\theta} \frac{2}{3} \right) + \operatorname{colo}_{\theta} \frac{2}{3} \left(\operatorname{sh}_{\theta} \frac{2}{3} \right) + \operatorname{colo}_{\theta} \frac{2}{3} \left(\operatorname{colo}_{\theta} \frac{2}{3} \right)$ $= \frac{\partial}{(\partial_{x}^{2} + d_{x})^{\frac{1}{2}}} \frac{\partial}{\partial t} + \frac{x}{x^{2} + d_{x}}} \frac{\partial}{\partial t} = \frac{u}{u} \frac{\partial}{\partial t} + \frac{u}{u} \frac{\partial}{\partial t} \frac{u$ $=\frac{1}{26}\left(\frac{1}{26}\left(\frac{1}{26}\right)\frac{1}{26}\left(\frac{1$ $\frac{\partial \phi}{\partial \phi} = \frac{\partial \phi}{\partial t} + \frac{\partial \phi}{\partial t} \frac{\partial \phi}{\partial t} + \frac{\partial \phi}{\partial t} \frac{\partial \phi}{\partial t} = \frac{\partial \phi}{\partial t} + \frac{\partial \phi}{\partial t} + \frac{\partial \phi}{\partial t} \frac{\partial \phi}{\partial t} + \frac{\partial \phi}{\partial$ $\left[\frac{1}{2}\frac{d^2 G}{d^2 G} G^{0}(z) + \frac{d^2 G}{dG} G^{0}(z)\right] + \left[\frac{d^2 G}{dG^2 G} + \frac{1}{2} + \frac{d^2 G}{dG} \frac{1}{2} + \right] dzadd mz + \frac{d^2 G}{2} \frac{d^2 mz}{d^2} = -\frac{1}{2}$ DISTATINES. $\bullet \quad \frac{\partial f_{\sigma}}{\partial \phi} = \frac{\partial x}{\partial \phi} \left(\frac{\partial x}{\partial \phi} \right) = \left(\frac{\partial x}{\partial \phi} - \frac{\partial x}{\partial \phi} \frac{\partial y}{\partial \phi} - \frac{\partial x}{\partial \phi} \frac{\partial y}{\partial \phi} \right)$ $+ \frac{42}{r^2} \frac{1}{r^2} - \frac{1}{2} \frac{1}{r^2} \frac$ $\frac{1}{160}\frac{9}{7}\frac{9}{7}\frac{9}{100}\frac{9}{100}\frac{1}{100} + \frac{1}{100}\frac{9}{100}\frac{9}{100}\frac{9}{100}\frac{9}{100}\frac{9}{100}\frac{1}{100}\frac{$ $\begin{array}{l} \displaystyle \left(\frac{46}{96},\frac{9}{7},\frac{1}{7}\right) & \displaystyle \left(\frac{4}{5},\frac{9}{96}\right) & \displaystyle \left(\frac{3}{5},\frac{9}{96},\frac{1}{7}\right) & \displaystyle \left(\frac{4}{3},\frac{9}{7},\frac{9}{96},\frac{9}{1}\right) & \displaystyle \left(\frac{4}{7},\frac{9}{7},\frac{9}{1}\right) & \displaystyle \left(\frac{1}{7},\frac{9}{7},\frac{9}{1}\right) & \displaystyle \left(\frac{1}{7},\frac{9}{7},\frac{9}{1}\right) & \displaystyle \left(\frac{1}{7},\frac{9}{1},\frac{9}{1}\right) & \displaystyle \left(\frac{1}{7},\frac{9}{1},\frac{9}{1},\frac{9}{1}\right) & \displaystyle \left(\frac{1}{7},\frac{9}{1},\frac{9}{1},\frac{9}{1}\right) & \displaystyle \left(\frac{1}{7},\frac{9}{1},\frac{9}{1},\frac{9}{1}\right) & \displaystyle \left(\frac{1}{7},\frac{9}{1},\frac{9}{1},\frac{9}{1},\frac{9}{1}\right) & \displaystyle \left(\frac{1}{7},\frac{9}{1},\frac{9}{$ $= \frac{1}{2} \frac{$ $-\frac{\cos\theta_{200}}{r^2} + \frac{\partial \varphi}{\partial \theta} + \frac{\cos\theta_{200}}{r^2} - \frac{\partial \varphi}{\partial \theta^2}$ $\operatorname{Subb} \frac{32_{0}}{3r^{2}} + \frac{\cos^{2}_{0}}{r^{2}} \frac{32_{0}}{3\theta^{2}} + \frac{2SyO_{OSC}}{r} \frac{32_{0}}{3r^{2}\theta} - \frac{2SSO_{OSC}}{r^{2}} \frac{34_{0}}{r\theta} + \frac{\cos^{2}_{0}}{r} \frac{34_{0}}{\thetar}$ Plant RUM = $sy_0 \frac{\partial g_0}{\partial r_0} + \frac{h_0}{r_0} \frac{\partial g_0}{\partial r_0} + \frac{gy_0}{r} \frac{\partial g_0}{\partial r_0} - \frac{h_0}{r_0} \frac{\partial g_0}{\partial \theta} + \frac{h_0^2 \theta}{r_0} \frac{\partial g_0}{\partial \theta}$ HANC $\frac{\partial \Phi}{\partial t^2} = \cos \frac{\partial \Phi}{\partial t^2} + \frac{\partial u^2 \Phi}{V^2} \frac{\partial \Phi}{\partial t^2}$ $\frac{32}{30^2} = sail 0 \frac{34}{312} + \frac{sail 0}{r^2} \frac{34}{302} - \frac{sail 0}{r^2} \frac{34}{302} + \frac{sail 0}{r^2} \frac{34}{303} + \frac{sail 0}{r} \frac{34}{4r}$ $\frac{\partial t^2}{\partial \Phi} + \frac{\partial q_2}{\partial \Phi} = (cad \partial + dad b) \frac{\partial q_1}{\partial \Phi} + \frac{1}{L} (cad \partial + cad b) \frac{\partial t}{\partial \Phi} + \frac{1}{L^2} (cad \partial + da d b) \frac{\partial q_2}{\partial \Phi}$ $\nabla^2 \phi = \frac{\partial^2 \phi}{\partial r^2} + \frac{1}{r} \frac{\partial \phi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \sigma^2}$ $\frac{\partial^2}{\partial x} + \frac{\partial^2}{\partial y} = \frac{\partial}{\partial r^2} + \frac{1}{r}\frac{\partial}{\partial r} + \frac{1}{r^2}\frac{\partial}{\partial \theta^2}$